Braids and Dynamics

Jean-Luc Thiffeault

Department of Mathematics University of Wisconsin – Madison

Conference on Applied Geometry and Topology University of Pennsylvania Philadelphia, PA 29 September 2023



part 1 periodic motion

the taffy puller



Taffy is a type of candy.

Needs to be pulled: this aerates it and makes it lighter and chewier.

We can assign a growth: length multiplier per period.

(Here $(1+\sqrt{2})^2$... more later.)

[movie by M. D. Finn]





making candy cane





[Wired: This Is How You Craft 16,000 Candy Canes in a Day]

four-pronged taffy puller





http://www.youtube.com/watch?v=Y7tlHDsquVM

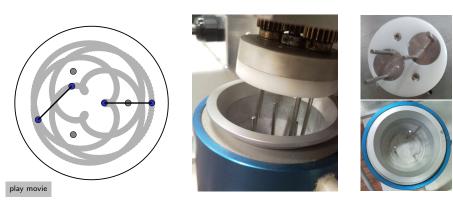
[MacKay (2001); Halbert & Yorke (2014)]

play movie

the mixograph



Experimental device for kneading bread dough:



[Department of Food Science, University of Wisconsin. Photos by J-LT.] For a *lot* more, see 'The Mathematics of Taffy Pullers,' Thiffeault, J.-L. (2018). *Math. Intelligencer*, **40** (1), 26–35. arXiv:1608.00152.

the mixograph as a braid



Encode the topological information as a sequence of generators of the Artin braid group B_n .

Equivalent to the 7-braid

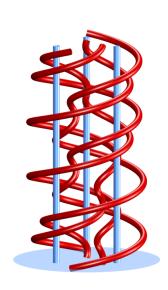
$$\sigma_3\sigma_2\sigma_3\sigma_5\sigma_6^{-1}\sigma_2\sigma_3\sigma_4\sigma_3\sigma_1^{-1}\sigma_2^{-1}\sigma_5$$

The growth is the largest root of

$$x^8 - 4x^7 - x^6 + 4x^4 - x^2 - 4x + 1$$

 $\simeq 4.186\,$

Compare to taffy pullers: 5.828



braids and rod-stirring



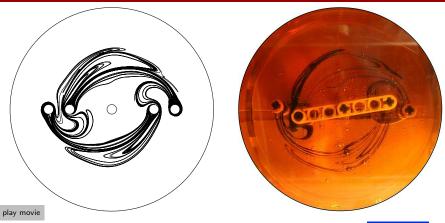


play movie play movie

[Boyland, P. L., Aref, H., & Stremler, M. A. (2000). *J. Fluid Mech.* **403**, 277–304; Simulations by M. D. Finn, S. E. Tumasz, and J-LT.]

4+1 rods





[Finn, M. D. & Thiffeault, J.-L. (2011). SIAM Rev. 53 (4), 723–743]



mathematical description



Periodic stirring protocols in two dimensions can be described by a homeomorphism $\varphi: \mathbb{S} \to \mathbb{S}$, where \mathbb{S} is a surface.

For instance, in a closed circular container,

- ullet φ describes the mapping of fluid elements after one full period of stirring, obtained by solving the Stokes equation;
- S is the disc with holes in it, corresponding to the stirring rods.

Goal: Topological characterization of φ .

[The theory extends to handlebodies, but not as relevant for applications...]

three main ingredients



- **1** The Thurston–Nielsen classification theorem (idealized φ);
- **2** Handel's isotopy stability theorem (link to real φ);
- 3 Topological entropy (quantitative measure of mixing).

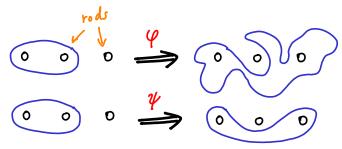
isotopy



 φ and ψ are isotopic if ψ can be continuously 'reached' from φ without moving the rods. Write $\varphi \simeq \psi$.

(Defines isotopy classes.)

Convenient to think of isotopy in terms of material loops. Isotopic maps act the same way on loops (up to continuous deformation).



(Loops will always mean essential loops.)

Thurston-Nielsen classification theorem



Theorem

 φ is isotopic to a homeomorphism ψ , where ψ is in one of the following three categories:

finite-order for some integer k > 0, $\psi^k \simeq$ identity;

reducible ψ leaves invariant a disjoint union of essential simple closed curves, called reducing curves;

pseudo-Anosov ψ leaves invariant a pair of transverse measured singular foliations, \mathfrak{F}^u and \mathfrak{F}^s , such that $\psi(\mathfrak{F}^u,\mu^u)=(\mathfrak{F}^u,\lambda\,\mu^u)$ and $\psi(\mathfrak{F}^s,\mu^s)=(\mathfrak{F}^s,\lambda^{-1}\mu^s)$, for dilatation $\lambda>1$.

The three categories characterize the isotopy class of φ .

We want pseudo-Anosov for good mixing.

Handel's isotopy stability theorem



The TN classification tells us about a simpler map ψ , the TN representative. What about the original map φ ?

Theorem (Handel, 1985)

If ψ is pseudo-Anosov and isotopic to $\varphi: \mathbb{S} \to \mathbb{S}$, then there is a compact, φ -invariant set, $\mathbb{Y} \subset \mathbb{S}$, and a continuous, onto mapping $\alpha: \mathbb{Y} \to \mathbb{S}$, so that $\alpha \varphi = \psi \alpha$.

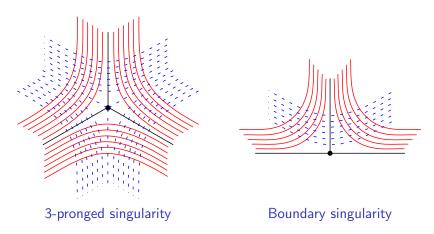
This is called a semiconjugacy (α not generally invertible).

Succinctly: the dynamics of the pseudo-Anosov map 'survive' isotopy, and so φ is at least as complicated as ψ . (In particular, it has at least as much topological entropy.)

a singular foliation

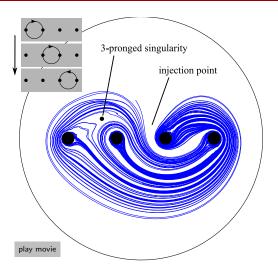


The 'pseudo' in pseudo-Anosov refers to the fact that the foliations can have a finite number of pronged singularities.



visualizing a singular foliation





- A four-rod stirring protocol;
- Material lines trace out leaves of the unstable foliation;
- Each rod has a 1-pronged singularity.
- One 3-pronged singularity in the bulk.
- One injection point (top): corresponds to boundary singularity;

[Thiffeault, J.-L., Finn, M. D., Gouillart, E., & Hall, T. (2008). Chaos, 18, 033123]

the topological program



- Consider a motion of stirring elements, such as rods.
- Determine if the motion is isotopic to a pseudo-Anosov mapping.
- Compute topological quantities, such as foliation, entropy, etc.
- Analyze and optimize.



[shameless plug for new book]

insight: do we need the rods?





[Gouillart, E., Kuncio, N., Dauchot, O., Dubrulle, B., Roux, S., & Thiffeault, J.-L.

(2007). Phys. Rev. Lett. 99, 114501]



ghost rods ('tiges fantômes')



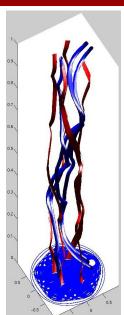
Topological analysis can be done on other objects than rods – for instance, islands or unstable periodic orbits.

We simply follow the islands and examine the braid they form, which gives us bounds on topological entropy.

In this framework we call the islands ghost rods.

[Gouillart, E., Finn, M. D., & Thiffeault, J.-L. (2006). *Phys. Rev. E*, **73**, 036311]

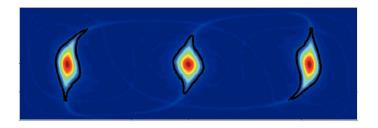
[implemented by Stremler & Chen (2007); Thiffeault et al. (2009); Binder (2010); Stremler et al. (2011)]



ghost rods (cont'd)



One of the best examples of ghost rods is from Stremler et al. (2011):



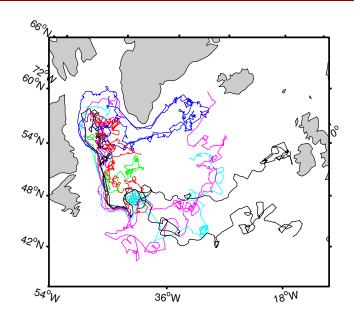
The islands are made to follow the $\sigma_2 \sigma_1^{-1}$ stirring protocol by clever wall motions! (viscous Stokes flow)

[Stremler, M. A., Ross, S. D., Grover, P., & Kumar, P. (2011). *Phys. Rev. Lett.* **106**, 114101]

part 2 non-periodic motion

oceanic float trajectories





oceanic floats: data analysis



What can we measure?

- single-particle dispersion (not a good use of all data)
- correlation functions (useful)
- Lyapunov exponents (some luck needed!)

Another possibility:

Compute the braid group generators σ_i for the float trajectories (convert to a sequence of symbols), then look at how loops grow. Obtain a topological entropy for the motion (similar to Lyapunov exponent, or to the 'growth' of taffy pullers).

iterating a loop



It is well-known that the entropy can be obtained by applying the motion of the punctures to a closed curve (loop) repeatedly, and measuring the growth of the length of the loop (Bowen, 1978).

The problem is twofold:

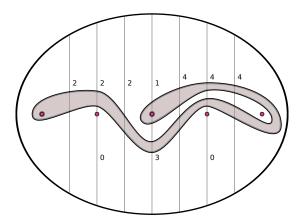
- Need to keep track of the loop, since its length is growing exponentially;
- Need a simple way of transforming the loop according to the motion of the punctures.

However, simple closed curves are easy objects to manipulate in 2D. Since they cannot self-intersect, we can describe them topologically with very few numbers.

solution to problem 1: loop coordinates



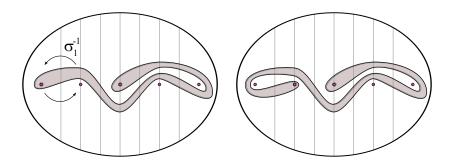
What saves us is that a closed loop can be uniquely reconstructed from the number of intersections with a set of curves. For instance, the Dynnikov coordinates involve intersections with vertical lines:



solution to problem 2: action on coordinates



Moving the punctures according to a braid generator changes some crossing numbers:

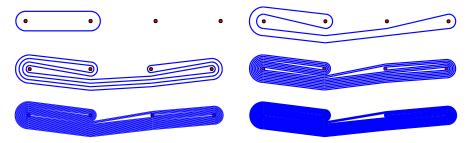


There is an explicit formula for the change in the coordinates! [Dynnikov (2002); Moussafir (2006); Hall & Yurttaş (2009); Thiffeault (2010)]

growth of L

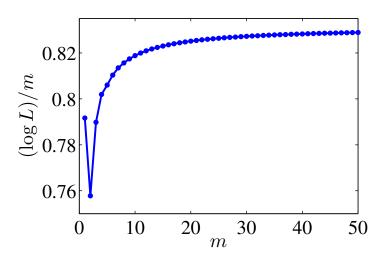


For a specific rod motion, say as given by the braid $\sigma_3^{-1}\sigma_2^{-1}\sigma_3^{-1}\sigma_2\sigma_1$, we can easily see the exponential growth of L and thus measure the entropy:



growth of L(2)





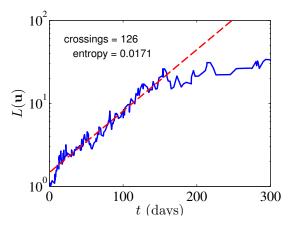
m is the number of times the braid acted on the initial loop.

[Moussafir, J.-O. (2006). Func. Anal. and Other Math. 1 (1), 37-46]

oceanic floats: entropy



10 floats from Davis' Labrador sea data:

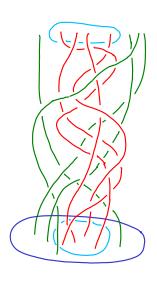


Floats have an entanglement time of about 50 days — timescale for horizontal stirring.

Source: WOCE subsurface float data assembly center (2004)

Lagrangian Coherent Structures

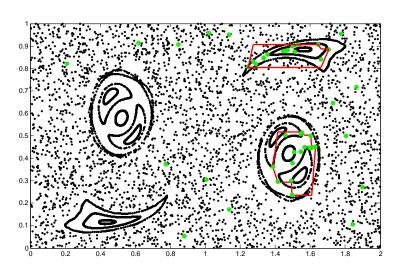




- There is a lot more information in the braid than just entropy;
- For instance: imagine there is an isolated region in the flow that does not interact with the rest, bounded by Lagrangian coherent structures (LCS);
- Identify LCS and invariant regions from particle trajectory data by searching for curves that grow slowly or not at all.
- [see Haller, G. & Beron-Vera, F. J. (2012).
 Physica D, 241 (20), 1680–1702.]
- Topological approach: [Allshouse & Thiffeault (2012); Filippi et al. (2020); Yeung et al. (2020)].

double-gyre coherent structures

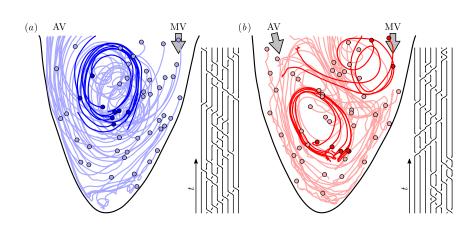




play movie [Allshouse, M. R. & Thiffeault, J.-L. (2012). Physica D, 241 (2), 95–105]

braids in the heart

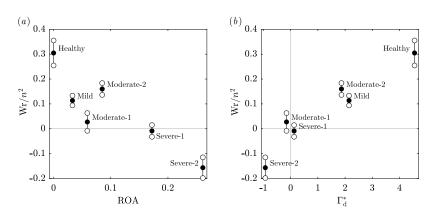




[Di Labbio, G., Thiffeault, J.-L., & Kadem, L. (2022). Flow, 2, E12]

braids in the heart (cont'd)



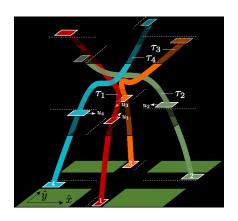


Wr writhe of braid ROA Regurgitant Orifice Area Γ_4^* circulation

[Di Labbio, G., Thiffeault, J.-L., & Kadem, L. (2022). Flow, 2, E12]

multiagent modeling: cars at an intersection



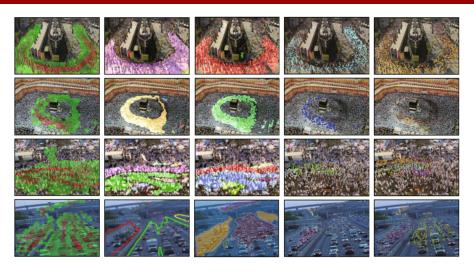


[Mavrogiannis, C., DeCastro, J., & Srinivasa, S. (2022). preprint]

This view of agent coordination is closely linked to Rob Ghrist's work on configuration space (U. Penn).

complexity of crowd movement

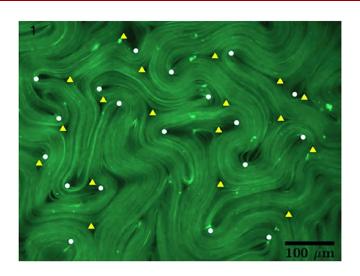




[Akpulat, M. & Ekinci, M. (2019). Frontiers of Information Technology & Electronic Engineering, 20 (6), 849–861]

braiding in active nematics





[Smith, S. A. & Gong, R. (2022). Frontiers in Physics, 10]

some research directions



- We don't have solid theory for aperodic or open braids.
- Computational methods for isotopy class (random entanglements of trajectories – LCS method, see Allshouse & Thiffeault (2012); Filippi et al. (2020); Yeung et al. (2020).
- 'Designing' for topological chaos (see Stremler & Chen (2007)).
- Combine with other measures, e.g., mix-norms (Mathew et al., 2005; Lin et al., 2011; Thiffeault, 2012).
- Matlab toolbox https://github.com/jeanluct/braidlab.
- 3D?! (lots of missing theory; E-Tec approach shows promise [Roberts, E., Sindi, S., Smith, S. A., & Mitchell, K. A. (2019). *Chaos,* 29 (1), 013124]).

references I



- Akpulat, M. & Ekinci, M. (2019). Frontiers of Information Technology & Electronic Engineering, 20 (6), 849–861.
- Allshouse, M. R. & Thiffeault, J.-L. (2012). Physica D, 241 (2), 95–105.
- Bestvina, M. & Handel, M. (1995). Topology, 34 (1), 109-140.
- Binder, B. J. (2010). Phys. Lett. A, 374, 3483-3486.
- Binder, B. J. & Cox, S. M. (2008). Fluid Dyn. Res. 40, 34-44.
- Bowen, R. (1978). In: *Structure of Attractors* volume 668 of *Lecture Notes in Math.* pp. 21–29, New York: Springer.
- Boyland, P. L., Aref, H., & Stremler, M. A. (2000). J. Fluid Mech. 403, 277-304.
- Boyland, P. L., Stremler, M. A., & Aref, H. (2003). Physica D, 175, 69-95.
- D'Alessandro, D., Dahleh, M., & Mezić, I. (1999). IEEE Transactions on Automatic Control, 44 (10), 1852–1863.
- Di Labbio, G., Thiffeault, J.-L., & Kadem, L. (2022). Flow, 2, E12.
- Dynnikov, I. A. (2002). Russian Math. Surveys, 57 (3), 592-594.
- Filippi, M., Budišić, M., Allshouse, M. R., Atis, S., Thiffeault, J.-L., & Peacock, T. (2020). Phys. Rev. Fluids, 5, 054504.
- Finn, M. D. & Thiffeault, J.-L. (2011). *SIAM Rev.* **53** (4), 723–743.
- Gouillart, E., Finn, M. D., & Thiffeault, J.-L. (2006). Phys. Rev. E, 73, 036311.

references II



Gouillart, E., Kuncio, N., Dauchot, O., Dubrulle, B., Roux, S., & Thiffeault, J.-L. (2007). *Phys. Rev. Lett.* **99**, 114501.

Halbert, J. T. & Yorke, J. A. (2014). Topology Proceedings, 44, 257–284.

Hall, T. & Yurttaş, S. Ö. (2009). Topology Appl. 156 (8), 1554–1564.

Haller, G. & Beron-Vera, F. J. (2012). *Physica D*, **241** (20), 1680–1702.

Handel, M. (1985). Ergod. Th. Dynam. Sys. 8, 373-377.

Kobayashi, T. & Umeda, S. (2007). In: Proceedings of the International Workshop on Knot Theory for Scientific Objects, Osaka, Japan pp. 97–109, Osaka, Japan: Osaka Municipal Universities Press.

Lin, Z., Doering, C. R., & Thiffeault, J.-L. (2011). J. Fluid Mech. 675, 465-476.

MacKay, R. S. (2001). Philos. Trans. Royal Soc. Lond. A, 359, 1479-1496.

Mathew, G., Mezić, I., & Petzold, L. (2005). Physica D, 211 (1-2), 23-46.

Mavrogiannis, C., DeCastro, J., & Srinivasa, S. (2022). preprint.

Moussafir, J.-O. (2006). Func. Anal. and Other Math. 1 (1), 37–46.

Roberts, E., Sindi, S., Smith, S. A., & Mitchell, K. A. (2019). Chaos, 29 (1), 013124.

Smith, S. A. & Gong, R. (2022). Frontiers in Physics, 10.

Stremler, M. A. & Chen, J. (2007). Phys. Fluids, 19, 103602.

references III



Stremler, M. A., Ross, S. D., Grover, P., & Kumar, P. (2011). Phys. Rev. Lett. 106, 114101.

Thiffeault, J.-L. (2005). Phys. Rev. Lett. 94 (8), 084502.

Thiffeault, J.-L. (2010). Chaos, 20, 017516.

Thiffeault, J.-L. (2012). *Nonlinearity*, **25** (2), R1–R44.

Thiffeault, J.-L. (2018). *Math. Intelligencer*, **40** (1), 26–35. arXiv:1608.00152.

Thiffeault, J.-L. & Finn, M. D. (2006). Philos. Trans. Royal Soc. Lond. A, 364 (1849), 3251–3266.

Thiffeault, J.-L., Finn, M. D., Gouillart, E., & Hall, T. (2008). Chaos, 18, 033123.

Thiffeault, J.-L., Gouillart, E., & Finn, M. D. (2009). In: Analysis and Control of Mixing with Applications to Micro and Macro Flow Processes, (Cortelezzi, L. & Mezić, I., eds) volume 510 of CISM International Centre for Mechanical Sciences pp. 339–350, Vienna: Springer.

Thurston, W. P. (1988). Bull. Am. Math. Soc. 19, 417-431.

Yeung, M., Cohen-Steiner, D., & Desbrun, M. (2020). Chaos, 30, 033122.