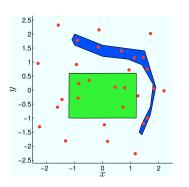
Jean-Luc Thiffeault<sup>1</sup> Michael Allshouse<sup>2</sup>

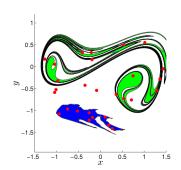
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<sup>2</sup>Department of Mechanical Engineering MIT

SIAM Conference on Applications of Dynamical Systems Snowbird, Utah, 22 May 2011

# Sparse trajectories and material loops





How do we efficiently detect trajectories that 'bunch' together?

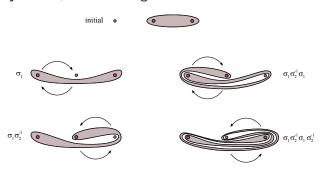
[movie 1]

Growth of loops

Growth of loops

# Growth of loops enclosing trajectories

For 3 trajectories, look at the growth of curves:



We use the braid generator notation:  $\sigma_i$  means the clockwise interchange of the *i*th and (i + 1)th trajectory. (Inverses are counterclockwise.)

The motion above is denoted  $\sigma_1 \sigma_2^{-1}$ .

Growth of loops

# Growth of loops (2)

The rate of growth  $h = \log \lambda$  is called the topological entropy.

But how do we find the rate of growth of curves for motions on the disk?

For 3 trajectories it's easy: the entropy for  $\sigma_1 \sigma_2^{-1}$  is  $h = \log \varphi^2$ , where  $\varphi$  is the Golden Ratio!

For more trajectories, use Moussafir iterative technique (2006).

```
[Thiffeault, Phys. Rev. Lett. (2005); Chaos (2010); Gouillart et al., Phys. Rev. E (2006) 'ghost rods']
```

# Iterating a loop

It is well-known that the entropy can be obtained by applying the trajectories to a closed curve (loop) repeatedly, and measuring the growth of the length of the loop (Bowen, 1978).

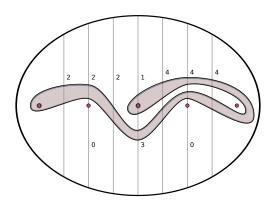
### The problem is twofold:

- 1. Need to keep track of the loop, since its length is growing exponentially;
- 2. Need a simple way of transforming the loop according to the trajectories.

However, simple closed curves are easy objects to manipulate in 2D. Since they cannot self-intersect, we can describe them topologically with very few numbers.

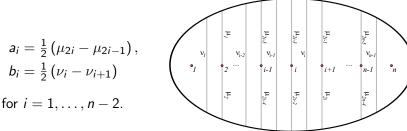
# Solution to problem 1: Loop coordinates

What saves us is that a closed loop can be uniquely reconstructed from the number of intersections with a set of curves. For instance, the crossing numbers count intersections with vertical lines:



# Dynnikov coordinates

Now take the difference of crossing numbers:



The vector of length (2n-4),

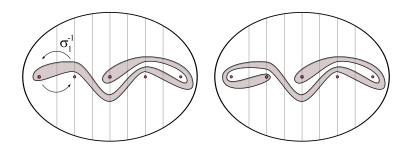
$$\mathbf{u} = (a_1, \ldots, a_{n-2}, b_1, \ldots, b_{n-2})$$

is called the Dynnikov coordinates of a loop.

There is a one-to-one correspondence between closed loops and these coordinates: you can't do it with fewer than 2n-4 numbers.

# Solution to problem 2: Action on coordinates

Moving the points according to a braid generator changes some crossing numbers:



There is an explicit formula for the change in the coordinates!

# Action on loop coordinates

The update rules for  $\sigma_i$  acting on a loop with coordinates  $(\mathbf{a}, \mathbf{b})$ can be written

$$a'_{i-1} = a_{i-1} - b^{+}_{i-1} - (b^{+}_{i} + c_{i-1})^{+},$$
  

$$b'_{i-1} = b_{i} + c^{-}_{i-1},$$
  

$$a'_{i} = a_{i} - b^{-}_{i} - (b^{-}_{i-1} - c_{i-1})^{-},$$
  

$$b'_{i} = b_{i-1} - c^{-}_{i-1},$$

where

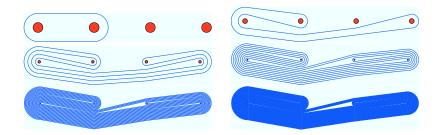
$$f^+ := \max(f, 0), \qquad f^- := \min(f, 0).$$
  
 $c_{i-1} := a_{i-1} - a_i - b_i^+ + b_{i-1}^-.$ 

This is called a piecewise-linear action.

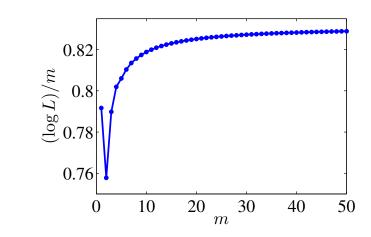
Easy to code up (see for example Thiffeault (2010)).

## Growth of L

For a specific set of trajectories, say as given by the braid  $\sigma_3^{-1}\sigma_2^{-1}\sigma_3^{-1}\sigma_2\sigma_1$ , we can easily see the exponential growth of L and thus measure the entropy:

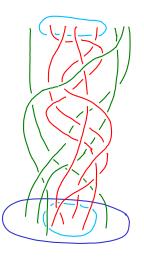


# Growth of L(2)



m is the number of times the braid acted on the initial loop.

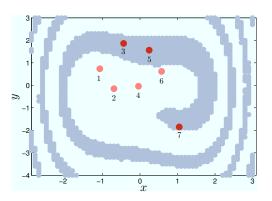
# Lagrangian Coherent Structures



- There is a lot more information in the braid than just entropy;
- For instance: imagine there is an isolated region in the flow that does not interact with the rest, bounded by Lagrangian coherent structures (LCS);
- Identify LCS and invariant regions from particle trajectory data by searching for curves that grow slowly or not at all.
- For now: regions are not 'leaky.'

# Sample system: Modified Duffing oscillator

LCS

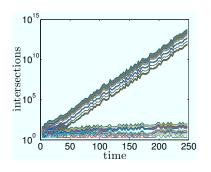


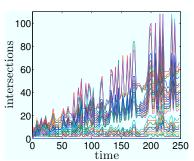
$$\dot{x} = y + \alpha \cos \omega t,$$

$$\dot{y} = x(1-x^2) + \gamma \cos \omega t - \delta y,$$

+ rotation to further hide two regions.  $\alpha = .1$ ,  $\gamma = .14$ ,  $\delta = .08$ ,  $\omega = 1$ .

# Growth of a vast number of loops

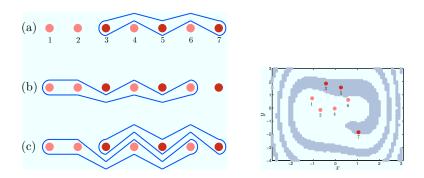




Left: semilog plot; Right: linear plot of slow-growing loops.

Clearly two types of loops!

## What do the slowest-growing loops look like?



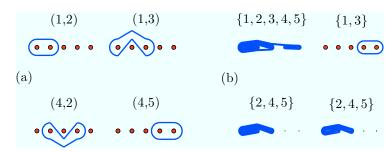
[(c) appears because the coordinates also encode 'multiloops.']

#### Here's the bad news:

- There are an infinite number of loops to consider.
- But we don't really expect hyper-convoluted initial loops (nor do we care so much about those).
- Even if we limit ourselves to loops with Dynnikov coordinates between -1 and 1, this is still  $3^{2n-4}$  loops.
- This is too many...can only treat about 10–11 trajectories using this direct method.

# An improved method: Pair-loops

The biggest problem is that we only look at whether a loop grows or not. But there is a lot more information to be found in how a loop entangles the trajectories as it evolves.



Consider loops that enclose only two trajectories at once. More involved analysis, but scales *much* better with *n*.

# **Improvement**

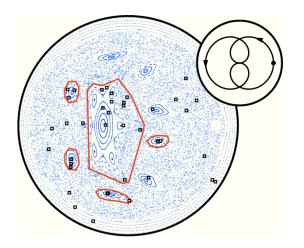
#### Run times in seconds:

# of trajectories	6	7	8	9	10	11	20
direct method	0.46	0.70	6.0	53	462	3445	N/A
pair-loop method	9.5	11.6	12.3	13	15	20	128

Bottleneck for the pair-loop method is finding the non-growing loops. (Should scale as  $n^2$  for large enough n.)

The downside is that the pair-loop method is much more complicated. But in the end it accomplishes the same thing.

# A physical example: Rod stirring device



[movie 2]

## Conclusions

- Having trajectories undergo 'braiding' motion guarantees a minimal amount of entropy (stretching of material lines);
- This idea can also be used on fluid particles to estimate entropy;
- Need a way to compute entropy fast: loop coordinates;
- There is a lot more information in this braid: extract it! (Lagrangian coherent structures);
- Is this useful? We need good physical problems to try it on!
- See Thiffeault (2005, 2010) and soon preprint by Allshouse & Thiffeault.

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