

Shape Matters

Homogenization for a confined Brownian microswimmer

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(Joint w. Hongfei Chen)

Brownian microswimmers

A hand-drawn diagram of a microswimmer. It has a central body with three axes extending from it: one horizontal along the bottom labeled 'X', one diagonal upwards and to the right labeled 'Y', and one vertical axis labeled 'theta'. A curved arrow indicates rotation around the 'theta' axis. Below the body, there is a downward-pointing arrow labeled 'Brownian' and 'EdW_i^2 = dt'.

$$dX = V dt + \sqrt{2D_X} dW_1$$
$$dY = \sqrt{2D_Y} dW_2$$
$$d\theta = \sqrt{2D_\theta} dW_3$$

ROTATE (lab).

$$dx = (V dt + \sqrt{2D_X} dW_1) \cos \theta - \sin \theta \sqrt{2D_Y} dW_2$$
$$dy = (\sqrt{2D_X} dW_1) \sin \theta + \cos \theta \sqrt{2D_Y} dW_2$$
$$d\theta = \sqrt{2D_\theta} dW_3$$

Fokker-Planck (Kolm. forward) eqn:

$$\rho(x, y, \theta, t)$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\mu \rho - D \nabla \rho) = 0$$

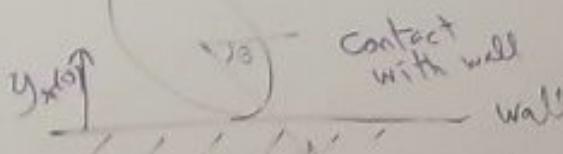
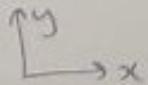
$$\mu = \begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix}, \quad D = \begin{pmatrix} D_x \cos^2 \theta + D_y \sin^2 \theta & \frac{1}{2}(D_x - D_y) & 0 \\ \frac{1}{2}(D_x - D_y) & " & 0 \\ 0 & 0 & D_\theta \end{pmatrix}$$

$$D_x = D_y, \quad D = \begin{pmatrix} D_x & 0 & 0 \\ 0 & D_x & 0 \\ 0 & 0 & D_\theta \end{pmatrix}$$

Gravit. force, etc. (Kurzheller & Franosch, 2017)

So far: no boundary.

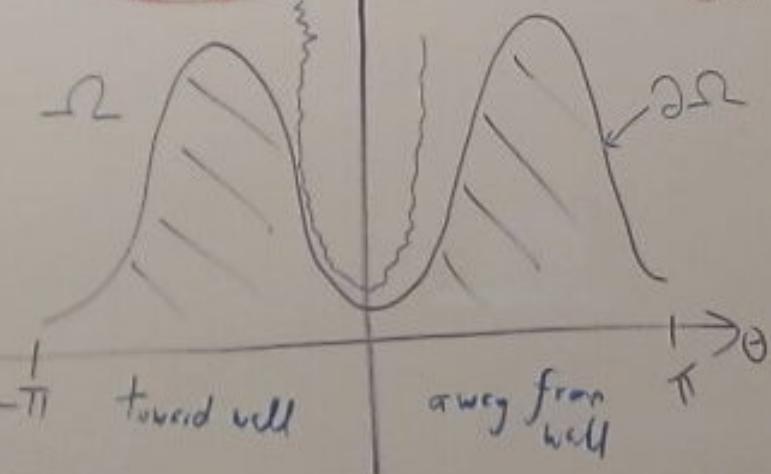
Shape not important



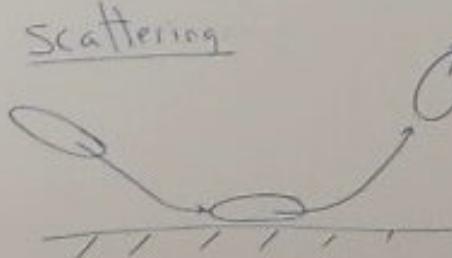
"wall distance function" $y_x(\theta)$

ellip: $y_x(\theta) = \sqrt{a^2 \sin^2 \theta + b^2 \cos^2 \theta}$

drift U_{int}



Scattering

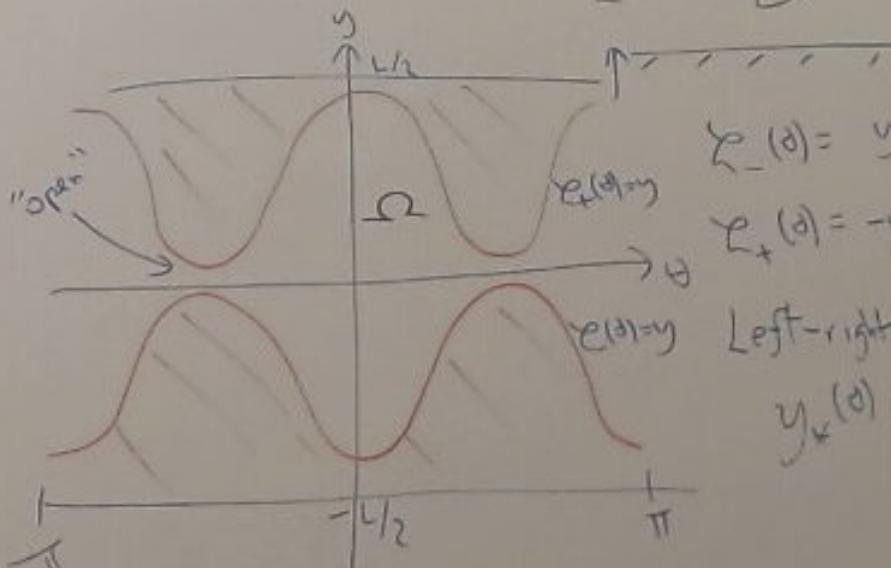
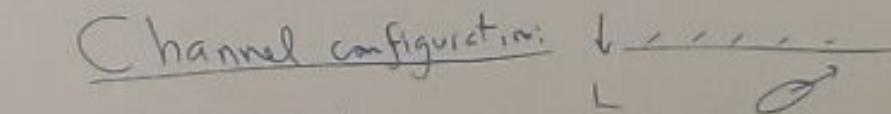


$$\frac{\partial p}{\partial t} + \nabla \cdot (\mu p - D \nabla p) = 0 \quad \text{in } \Omega$$

$$f = \mu p - D \nabla p \quad \text{prob flux}$$

Boundary condition: $f|_{\Gamma} = 0, \text{ on } \partial\Omega$

Channel configuration



Left-right symmetric:
 $y_x(\theta) = y_x(\theta - \pi)$

$y_x(\theta)$ related to Legendre transform of shape.

F-P eqn in channel

$$\partial_t p + \nabla \cdot (\mu \mathbf{r} - D \nabla p) = 0$$

Geometry makes this hard!

Simplify: $D_\theta = \epsilon \ll 1$

Use asymptotic expansion

$$p = p_0 + \epsilon p_1 + \dots, \quad T = \epsilon t$$

$$p_0(y, \theta) = P(\theta, T) e^{\sigma(\theta)y}$$

$$\partial_T p + \partial_\theta (\mu(\theta) - \partial_\theta P) = 0$$

$$\sigma(\theta) = U \sin \theta / D_{yy}^{(\theta)}$$

$$\mu(\theta) = \frac{\sigma(\theta)}{2 \sinh \Delta} \left(e^{\Delta \zeta'_+} - e^{-\Delta \zeta'_-} \right) \xleftarrow{\text{shape}}$$

$$\Delta(\theta) = \frac{1}{2} \sigma(\theta) (\zeta'_+(\theta) - \zeta'_-(\theta))$$

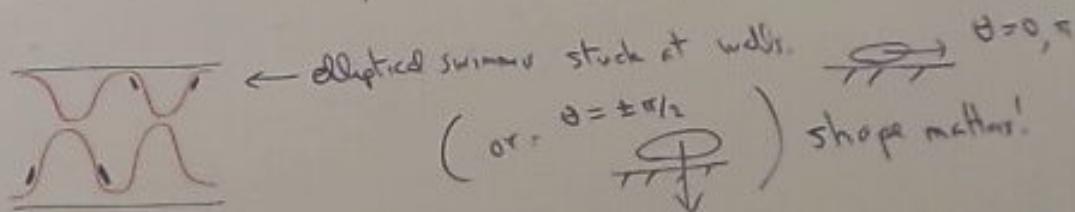
$$\begin{aligned} n \cdot f &= 0 \text{ or } 2\pi \\ f &= \mu p - D \nabla p \\ p(y, \theta) \end{aligned}$$

$$\text{Invariant density } \partial_\theta (\mu p - \partial_\theta p) = 0$$

$$\mu p - \partial_\theta p = \omega/2\pi$$

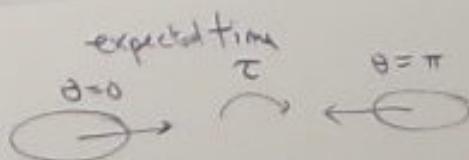
Can show $\omega = 0$ for left-right symmetric swimmer
"detailed balance"

Otherwise $\mathbb{E} \mu = \omega$ mean rotation rate
as swimmer bounces off walls



(or $\theta = \pm \pi/2$) shape matters!

Mean reversal time:



Small D_s , again

$$\mu(0)\tau + \tau'' = -1$$

$$\tau(\pm\pi) = 0$$

We want $\tau(0)$. ^{mean} _{reversal} (MRT)

Without drift: Holcman & Schuss (2014)
"narrow exit" limit

For L-R symmetric ($D_x = D_y$)

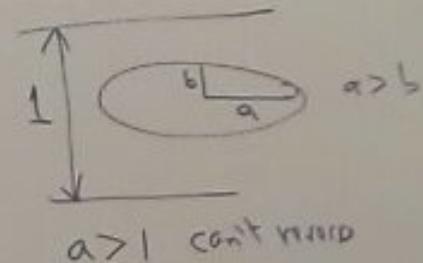
$$\tau(0) = \frac{1}{4} \int_0^\pi \frac{d\theta}{P(\theta)}$$

↑
invariant density

Integral controlled by "bottlenecks" of small $P(\theta)$.
(For example: narrow channel, sticking to walls)

$\mu = 0$ (no swimming, diffusion only)

$$\tau(0) = \frac{(\pi - 2a)(\pi - \arccos a)}{D_s \sqrt{1-a^2}}$$



(Valid for small D_s)

With swimming harder:

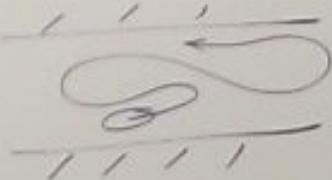
$$\beta = \frac{U_0}{2D_s} \gg 1 \quad \text{P\'eclet number}$$

"needle" swimmer ($b=0$)

$$\tau(0) = \frac{\pi}{2\beta} e^\beta \quad (D_x = D_y)$$

exponential! Sticks to walls.

Effective diffusion:



$$E x^2 = 2 D_{\text{eff}} t$$

"Homogenize" the F-P eqn.
(only in x^1)

$$x \mapsto x/\eta, \quad t \mapsto t/\eta^2$$

... fairly standard derivation (see preprint)

$$\partial_t P = D_{\text{eff}} \partial^2 P$$

$$D_{\text{eff}} = E D_{xx} + D_{\text{enhanced}}$$

$$\int_{-\pi}^{\pi} D_{xx} P d\theta$$

$$D_{\text{enh}} = - \int_{-\pi}^{\pi} E \bar{w} \bar{X} d\theta \quad \bar{w} = \text{weight depending on shape}$$

$$\bar{E}(\theta) = U \cos \theta - U \sin \theta \frac{D_{xy}(\theta)}{D_{yy}(\theta)}$$

\bar{X} satisfies a cell problem:

$$\partial_\theta (\nu \bar{X} - \bar{w} \partial_\theta \bar{X}) = -EP$$

$\nu = \frac{\nu + \bar{w}}{\bar{w}}$

Can maybe solve for simple shapes?

But more importantly we can show bound:

$$D_{\text{enh}} \leq \frac{1}{2} \tau(0) (E|\bar{E}|)^2 \leq \frac{1}{2} \tau(0) U^2$$

($D_x \geq D_y/2$)

"intuition"



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