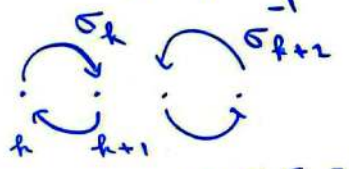


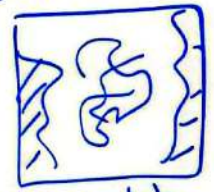
Erica, 9/6/22

Braid group: B_n



Relations: $\sigma_1 \sigma_2 \sigma_1 = \sigma_2 \sigma_1 \sigma_2$
 $\sigma_1 \sigma_3 = \sigma_3 \sigma_1$

Can construct braid from orbit data



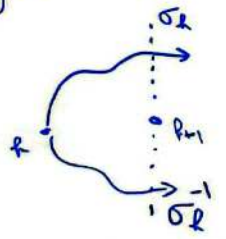
lift to braid



NOT closed

Float data

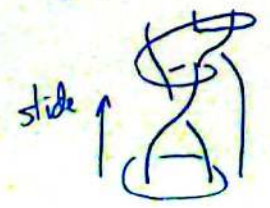
Assign generators for each crossing along a projection line.



Obtain sequence $\alpha = \sigma_2^{-1} \sigma_3 \sigma_1^2 \sigma_2^{-1} \dots$

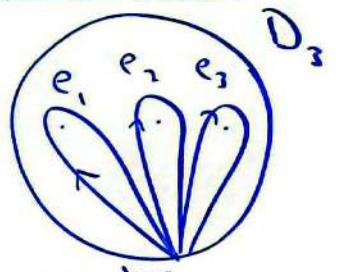
If closed, change of projection is conjugation $\alpha' = \beta \alpha \beta^{-1}$

Growth of braid: dilatation of associated mapping class of homeos $D_n \rightarrow D_n$.
 Asymptotic growth rate of loop "caught" on braid



How to compute this?
 Dynamical coordinates, etc.

Artin action:



generators for $\pi_1(D_3)$



right action



$$e_1 \sigma_1 = e_1 e_2 e_1^{-1}$$

$$e_2 \sigma_1 = e_1$$

$$e_3 \sigma_1 = e_3$$

$$e_1 e_2 \sigma_1 = (e_1 \sigma_1) (e_2 \sigma_1)$$

$$e_1 \sigma_1 \sigma_2 = (e_1 \sigma_1) \sigma_2$$

"Word length" in π_1 grows at the same rate as the growth of braid.

So just count symbols!

$$e_1 \sigma_1 \sigma_2^{-1} = (e_1 e_2 e_1^{-1}) \sigma_2^{-1}$$

$$= (e_1 \sigma_2^{-1}) (e_2 \sigma_2^{-1}) (e_1^{-1} \sigma_2^{-1})$$

$$= e_1 (e_3) (e_1^{-1})$$

Now apply to each symbol \rightarrow grows exponentially.
 Very hard to keep track of in practice.

Better: "Abelianize"

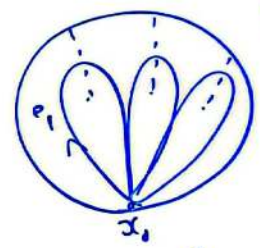
$$e_1 \sigma_1 = e_1 + e_2 - e_1 \text{ uops!}$$

$$e_2 \sigma_1 = e_1$$

$$e_3 \sigma_1 = e_3$$

Linear representation, but of symmetric group! No growth.

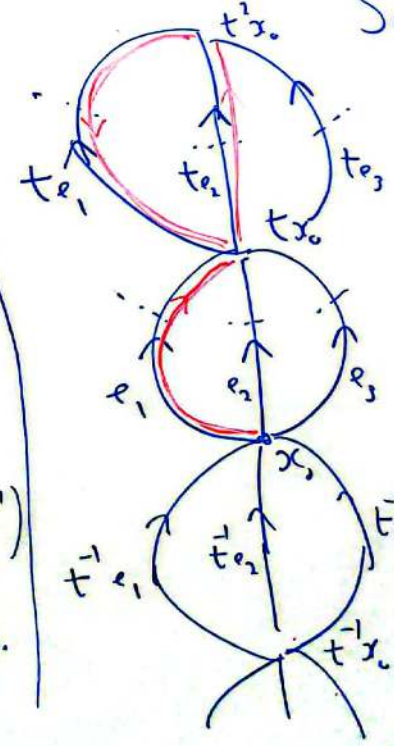
Keep a bit more info. Use a branched cover of D_3 . Make 3 "cuts".



Crossing a cut takes you up/down a "floor" (deck)

Loop e_1 becomes an arc

Schematic representation as a "1-skeleton"



$$e_1 \sigma_1 = e_1 (t e_2) (t e_1)^{-1}$$

t is a symbolic parameter that labels the deck.

Abelianize:

$$e_1 \sigma_1 = e_1 + t e_2 - t e_1$$

$$= (1-t) e_1 + t e_2$$

Linear representation, but not symmetric group.

Burau representation:

$$e_1 \sigma_1 = (1-t)e_1 + e_2$$

$$e_2 \sigma_1 = e_1$$

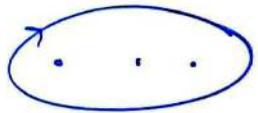
$$e_3 \sigma_1 = e_3$$

$$\text{Matrix: } [\sigma_1] = \left(\begin{array}{ccc|c} 1-t & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ \hline 0 & 0 & 1 & 0 \end{array} \right)$$

$$[\sigma_2] = \left(\begin{array}{c|cc} 1 & 0 & 0 \\ \hline 0 & 1-t & 1 \\ 0 & 1 & 0 \end{array} \right)$$

etc. for more strings.

$e_1 + te_2 + t^2e_3 + \dots + t^{n-1}e_n$ is invariant.



corresponds to loop around all the punctures. (lifted)

Change basis: $u_1 = e_1 - e_2$
 $u_2 = e_2 - e_3$
 \vdots
 $u_{n-1} = e_{n-1} - e_n$

$$[\sigma_k] = I_{k-2}$$

Get reduced Burau representation (more familiar)

$$\oplus \begin{pmatrix} 1 & t & 0 \\ 0 & -t & 0 \\ 0 & 1 & 1 \end{pmatrix} \oplus I_{n-k-2}$$

in k, k position.

So far t is a symbolic parameter.

Can pick specific values: $t^m = 1 \rightarrow$ finite cover

$t=1$: no cover

$t=-1$: double-covers

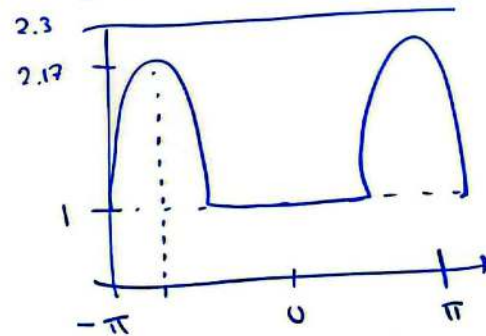
Thm: (Fried/Kolev) braid α with Burau rep $[\alpha]$
 growth $\lambda \geq \sup_{|t|=1} \text{spr}[\alpha]$

This is a fast and easy bound on the growth.

If bound is exact, then it must be so for $t=-1$
 (cover coincides with "orientation double cover")

Boyland/Harrington

But $t=-1$ not always best choice



$$t = e^{id}$$

$$\alpha = \sigma_1 \sigma_2 \sigma_3^{-1}$$

Not much is known about the "quality" of this bound.

See also Lawrence-Krammer representation, which can sometimes improve bound. (example by Lynch)

What else is Burau good for?

Yeung, Cohen-Steiner, Desbrun (2020)

Use Burau eigensystem to quantify "coherence"

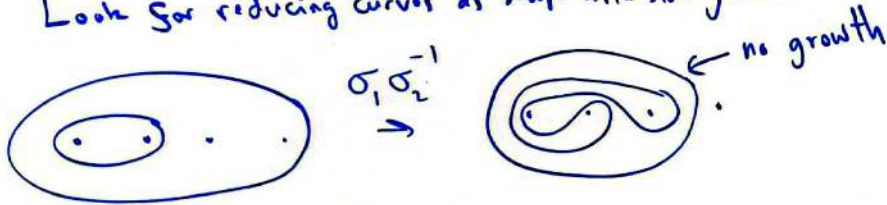


reducible braid
(one of the 3 cases in TN th.)

Related to detection of "Lagrangian coherent structures"

Allshouse + J-LT → using Dynnikov loop coords.

Look for reducing curves as loops with slow growth.



YCD had the insight that the eigenvector structure of $[\alpha]$ captures coherence with piecewise-constant eigenvector entries.

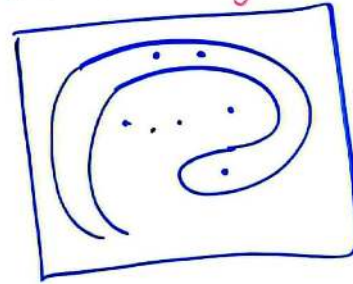
Use Burau param t near 1 with $\arg t < \frac{1}{n}$ to guarantee unitarity and existence of p -vectors.

FAST! Room for refinement.

example: modified Duffing oscillator



chaotic
+ invariant regions



Algos detect the fact that trajectories belong to different dynamical regions.