

The topology of fluid mixing

Jean-Luc Thiffeault

Department of Mathematics
University of Wisconsin – Madison

Center for Nonlinear Analysis Seminar
Carnegie Mellon University, 26 March 2013

Supported by NSF grants DMS-0806821 and CMMI-1233935



the taffy puller



This may not look like it has much to do with stirring, but notice how the taffy is stretched and folded exponentially.

Often the hydrodynamics are less important than the topological nature of the rod motion.

[movie by M. D. Finn]

play movie

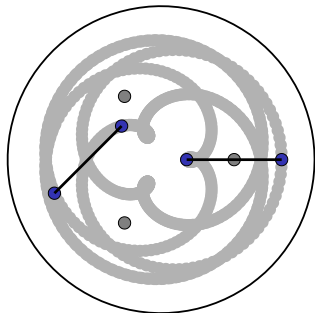


making candy cane

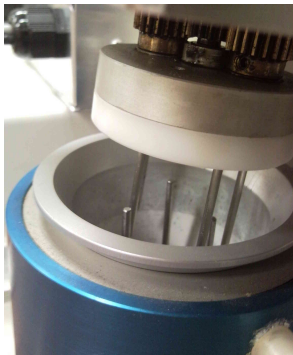


[*Wired*: This Is How You Craft 16,000 Candy Canes in a Day]

Experimental device for kneading bread dough:

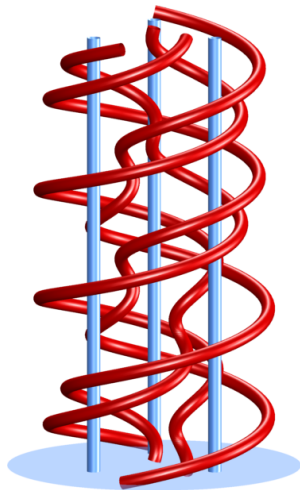


play movie



[Department of Food Science, University of Wisconsin. Photos by J-LT.]

Encode the topological information
as a sequence of **generators** of the
Artin braid group B_n .

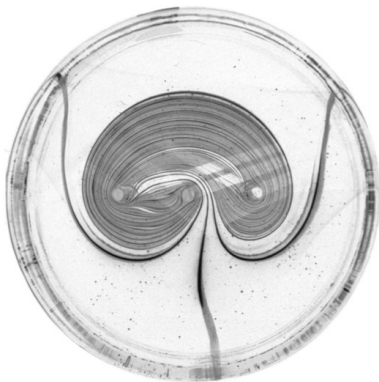


Equivalent to the 7-braid $\sigma_3\sigma_2\sigma_3\sigma_5\sigma_6^{-1}\sigma_2\sigma_3\sigma_4\sigma_3\sigma_1^{-1}\sigma_2^{-1}\sigma_5$

experiment of Boyland, Aref & Stremler



play movie



play movie

[Boyland, P. L., Aref, H., & Stremler, M. A. (2000). *J. Fluid Mech.* **403**, 277–304; Simulations by M. D. Finn.]



Focus on **closed systems**.

Periodic stirring protocols in two dimensions can be described by a **homeomorphism** $\varphi : \mathcal{S} \rightarrow \mathcal{S}$, where \mathcal{S} is a surface.

For instance, in a closed circular container,

- φ describes the mapping of fluid elements after one full period of stirring, obtained by solving the Stokes equation;
- \mathcal{S} is the **disc** with holes in it, corresponding to the stirring rods.

Goal: **Topological characterization of φ** .

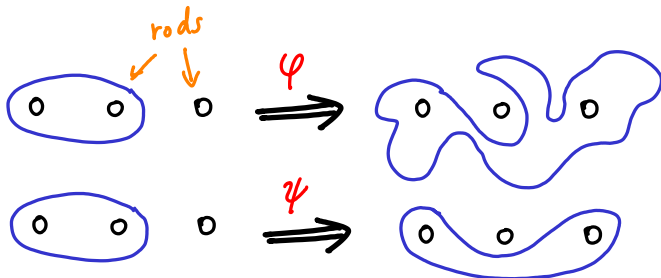


- ① The Thurston–Nielsen classification theorem ([idealized \$\varphi\$](#));
- ② Handel's isotopy stability theorem ([link to real \$\varphi\$](#));
- ③ Topological entropy ([quantitative measure of mixing](#)).

φ and ψ are **isotopic** if ψ can be continuously 'reached' from φ without moving the rods. Write $\varphi \simeq \psi$.

(Defines **isotopy classes**.)

Convenient to think of isotopy in terms of material loops. Isotopic maps act the same way on loops (up to continuous deformation).



(Loops will always mean **essential** loops.)

Theorem

φ is isotopic to a homeomorphism ψ , where ψ is in one of the following three categories:

finite-order for some integer $k > 0$, $\psi^k \simeq \text{identity}$;

reducible ψ leaves invariant a disjoint union of essential simple closed curves, called *reducing curves*;

pseudo-Anosov ψ leaves invariant a pair of transverse measured **singular foliations**, \mathcal{F}^u and \mathcal{F}^s , such that $\psi(\mathcal{F}^u, \mu^u) = (\mathcal{F}^u, \lambda \mu^u)$ and $\psi(\mathcal{F}^s, \mu^s) = (\mathcal{F}^s, \lambda^{-1} \mu^s)$, for **dilatation** $\lambda > 1$.

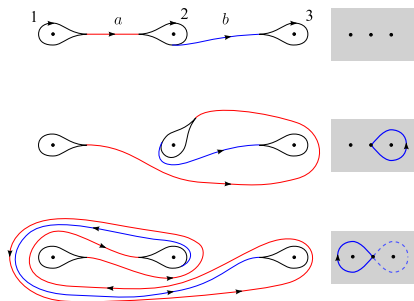
The three categories characterize the **isotopy class** of φ .

We want **pseudo-Anosov** for good mixing.



- Consider a **motion of stirring elements**, such as rods.
- Determine if the motion is **isotopic to a pseudo-Anosov mapping**.
- **Compute** topological quantities, such as foliation, entropy, etc.
- **Analyze** and **optimize**.

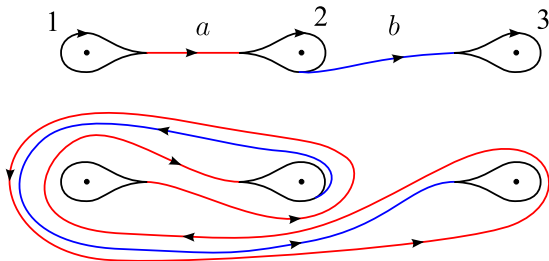
'Figure-8' motion: $\sigma_2^{-2}\sigma_1^2$



exp. by E. Gouillart and O. Dauchot

Thurston introduced **train tracks** as a way of characterizing the measured foliation. The name stems from the 'cusps' that look like train switches.

train track map for figure-eight



$$a \mapsto a\bar{2}\bar{a}\bar{1}ab\bar{3}\bar{b}\bar{a}1a, \quad b \mapsto \bar{2}\bar{a}\bar{1}ab$$

Easy to show that this map is **efficient**: under repeated iteration, cancellations of the type $a\bar{a}$ or $b\bar{b}$ never occur.

There are algorithms, such as Bestvina & Handel (1995), to find efficient train tracks. (Toby Hall has an implementation in C++.)



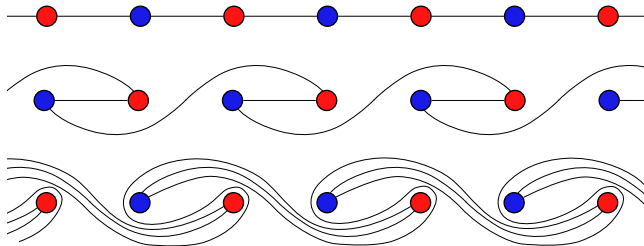
As the TT map is iterated, the number of symbols grows exponentially, at a rate given by the **topological entropy**, $\log \lambda$. This is a lower bound on the **minimal length of a material line** caught on the rods.

Find from the TT map by **Abelianizing**: count the number of occurrences of a and b , and write as matrix:

$$\begin{pmatrix} a \\ b \end{pmatrix} \mapsto \begin{pmatrix} 5 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}$$

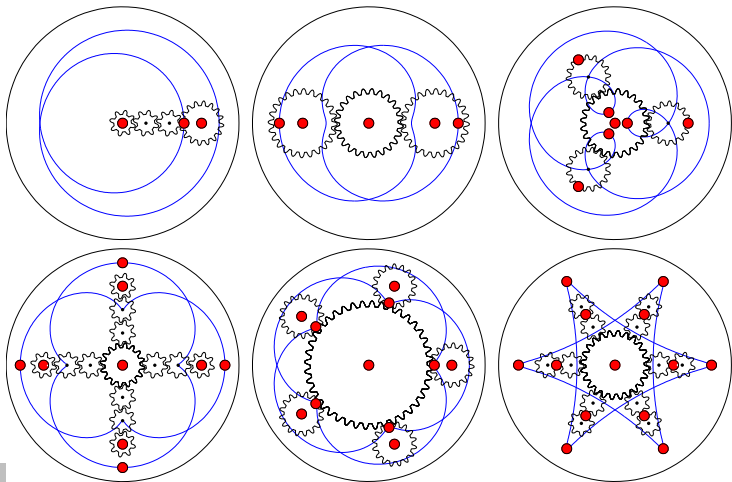
The largest eigenvalue of the matrix is $\lambda = (1 + \sqrt{2})^2 \simeq 5.83$. Hence, asymptotically, the length of the 'blob' is multiplied by 5.83 for each full stirring period.

- Consider periodic lattice of rods.
- Move all the rods such that they execute the Boyland *et al.* (2000) rod motion (J-LT & Finn, 2006; Finn & J-LT, 2011).



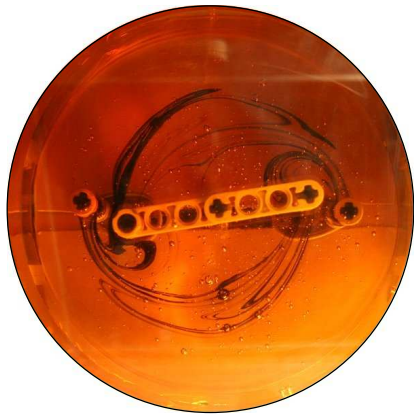
- The dilatation per period is χ^2 , where $\chi = 1 + \sqrt{2}$ is the **Silver Ratio**!
- This is **optimal** for a periodic lattice of two rods (Follows from D'Alessandro *et al.* (1999)).

- The designs with dilatation given by the silver ratio can be realized with simple gears.
- All the rods move at once: very efficient.





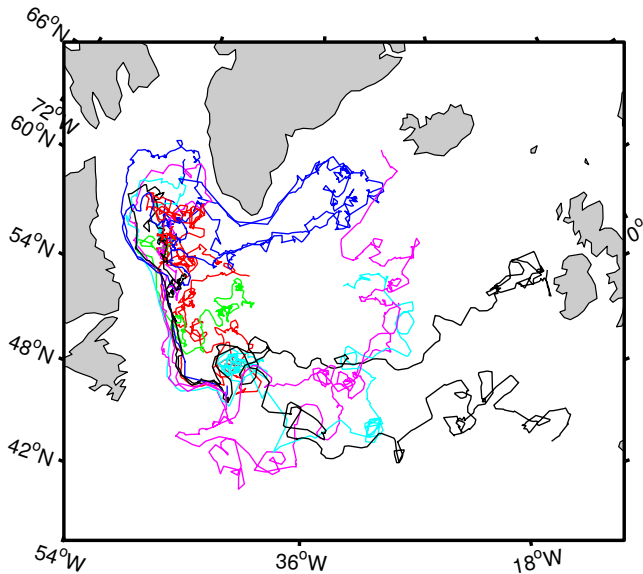
play movie



play movie

[See Finn, M. D. & J-LT (2011). *SIAM Rev.* **53** (4), 723–743 for proofs, heavily influenced by work on π_1 -stirrers of Boyland, P. L. & Harrington, J. (2011). *Algeb. Geom. Topology*, **11** (4), 2265–2296.]

oceanic float trajectories





What can we measure?

- Single-particle dispersion (not a good use of all data)
- Correlation functions (what do they mean?)
- Lyapunov exponents (some luck needed!)

Another possibility:

Compute the **braid group generators** σ_i for the float trajectories (convert to a sequence of symbols), then look at how loops grow. Obtain a **topological entropy** for the motion (similar to Lyapunov exponent).



It is well-known that the entropy can be obtained by applying the motion of the punctures to a closed curve (loop) repeatedly, and measuring the growth of the length of the loop (Bowen, 1978).

The problem is twofold:

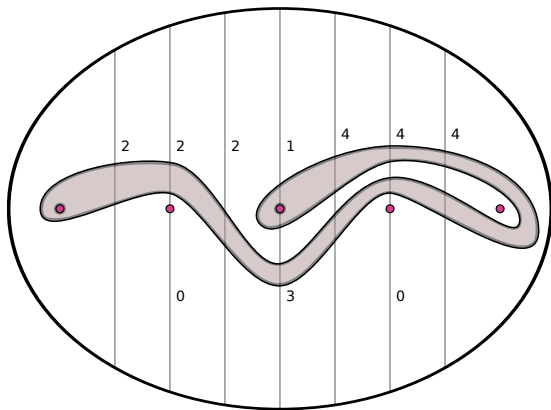
- 1 Need to keep track of the loop, since its length is growing exponentially;
- 2 Need a simple way of transforming the loop according to the motion of the punctures.

However, simple closed curves are easy objects to manipulate in 2D. Since they cannot self-intersect, we can describe them **topologically** with very few numbers.

solution to problem 1: loop coordinates



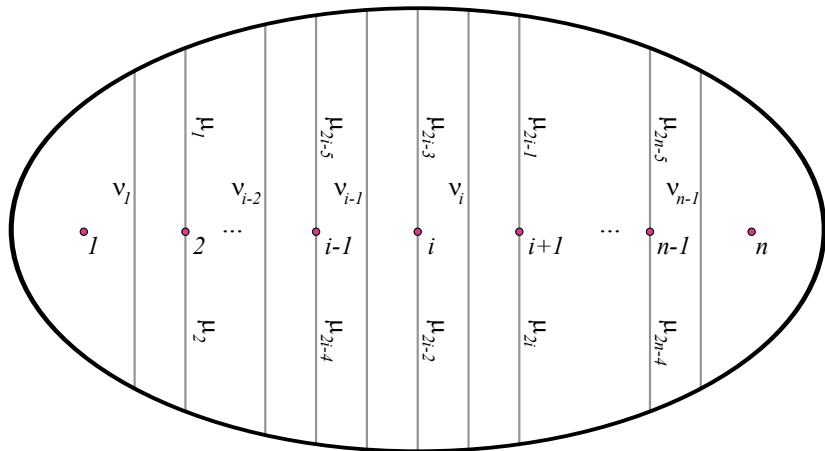
What saves us is that a closed loop can be uniquely reconstructed from the number of intersections with a set of curves. For instance, the [Dybnikov coordinates](#) involve intersections with vertical lines:



crossing numbers



Label the crossing numbers:



Now take the difference of crossing numbers:

$$a_i = \frac{1}{2} (\mu_{2i} - \mu_{2i-1}),$$

$$b_i = \frac{1}{2} (\nu_i - \nu_{i+1})$$

for $i = 1, \dots, n - 2$.

The vector of length $(2n - 4)$,

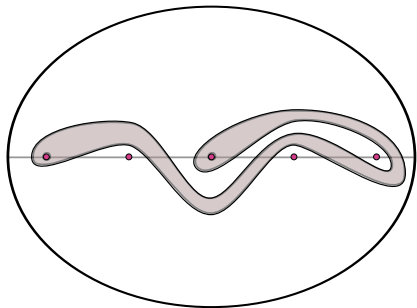
$$\mathbf{u} = (a_1, \dots, a_{n-2}, b_1, \dots, b_{n-2})$$

is called the **Dynnikov coordinates** of a loop.

There is a one-to-one correspondence between closed loops and these coordinates: you can't do it with fewer than $2n - 4$ numbers.

A useful formula gives the **minimum intersection number** with the 'horizontal axis':

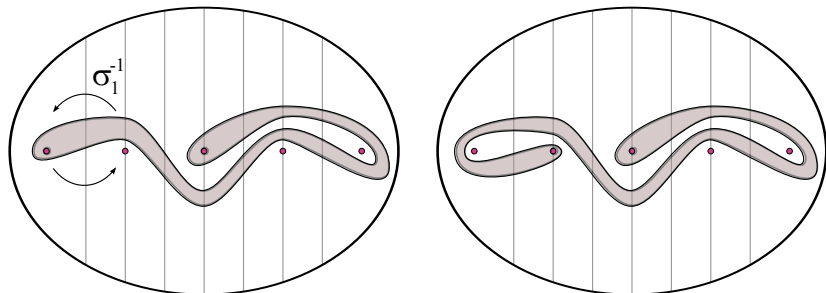
$$L(\mathbf{u}) = |a_1| + |a_{n-2}| + \sum_{i=1}^{n-3} |a_{i+1} - a_i| + \sum_{i=0}^{n-1} |b_i|,$$



For example, the loop on the left has $L = 12$.

The crossing number grows proportionally to the the length.

Moving the punctures according to a braid generator changes some crossing numbers:



There is an explicit formula for the change in the coordinates!



The **update rules** for σ_i acting on a loop with coordinates (\mathbf{a}, \mathbf{b}) can be written

$$a'_{i-1} = a_{i-1} - b_{i-1}^+ - (b_i^+ + c_{i-1})^+ ,$$

$$b'_{i-1} = b_i + c_{i-1}^- ,$$

$$a'_i = a_i - b_i^- - (b_{i-1}^- - c_{i-1})^- ,$$

$$b'_i = b_{i-1} - c_{i-1}^- ,$$

where

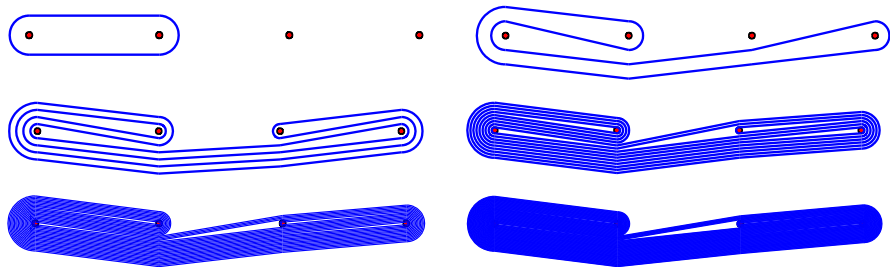
$$f^+ := \max(f, 0), \quad f^- := \min(f, 0).$$

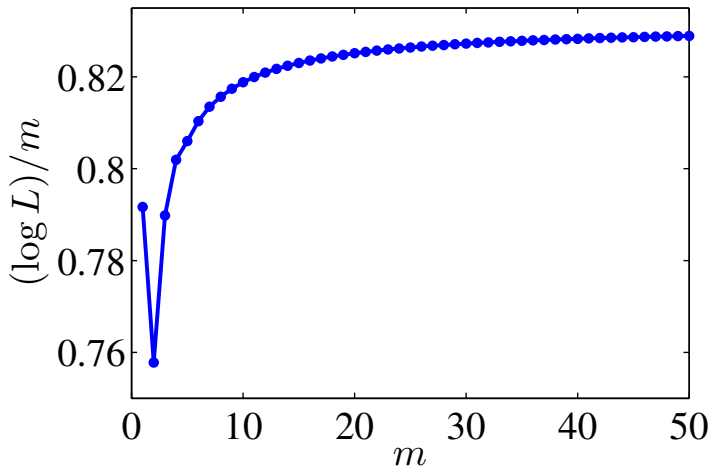
$$c_{i-1} := a_{i-1} - a_i - b_i^+ + b_{i-1}^- .$$

This is called a **piecewise-linear action**.

Easy to code up (see for example J-LT (2010)).

For a specific rod motion, say as given by the braid $\sigma_3^{-1}\sigma_2^{-1}\sigma_3^{-1}\sigma_2\sigma_1$, we can easily see the exponential growth of L and thus measure the entropy:

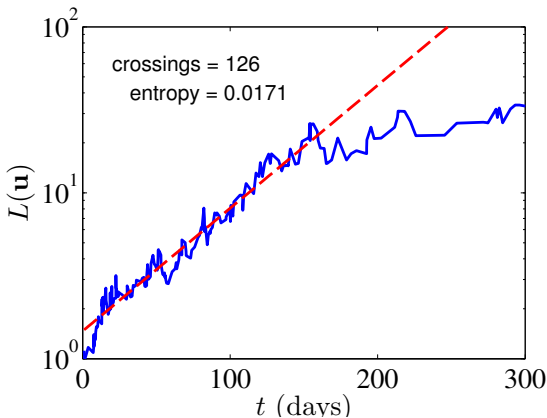




m is the number of times the braid acted on the initial loop.

[Moussafir, J.-O. (2006). *Func. Anal. and Other Math.* 1 (1), 37–46]

10 floats from Davis' Labrador sea data:



Floats have an entanglement time of about 50 days — timescale for horizontal stirring.

Source: WOCE subsurface float data assembly center (2004)



- The **nature of the isotopy** between the pA and real system.
- **Sharpness** of the entropy bound (Tumasz & J-LT, 2013).
- **Computational methods** for isotopy class (random entanglements of trajectories – LCS method, see Allshouse & J-LT (2012)).
- **'Designing'** for topological chaos (see Stremler & Chen (2007)).
- Combine with **other measures**, e.g., **mix-norms** (Mathew *et al.*, 2005; Lin *et al.*, 2011; J-LT, 2012).
- **3D?!** (lots of missing theory)



- Allshouse, M. R. & J-LT (2012). *Physica D*, **241** (2), 95–105.
- Bestvina, M. & Handel, M. (1995). *Topology*, **34** (1), 109–140.
- Binder, B. J. & Cox, S. M. (2008). *Fluid Dyn. Res.* **40**, 34–44.
- Bowen, R. (1978). In: *Structure of Attractors* volume 668 of *Lecture Notes in Math.* pp. 21–29, New York: Springer.
- Boyland, P. L., Aref, H., & Stremler, M. A. (2000). *J. Fluid Mech.* **403**, 277–304.
- Boyland, P. L. & Harrington, J. (2011). *Algeb. Geom. Topology*, **11** (4), 2265–2296.
- Boyland, P. L., Stremler, M. A., & Aref, H. (2003). *Physica D*, **175**, 69–95.
- D'Alessandro, D., Dahleh, M., & Mezić, I. (1999). *IEEE Transactions on Automatic Control*, **44** (10), 1852–1863.
- Finn, M. D. & J-LT (2011). *SIAM Rev.* **53** (4), 723–743.
- Gouillart, E., Finn, M. D., & J-LT (2006). *Phys. Rev. E*, **73**, 036311.
- Handel, M. (1985). *Ergod. Th. Dynam. Sys.* **8**, 373–377.
- Kobayashi, T. & Umeda, S. (2007). In: *Proceedings of the International Workshop on Knot Theory for Scientific Objects, Osaka, Japan* pp. 97–109, Osaka, Japan: Osaka Municipal Universities Press.
- Lin, Z., Doering, C. R., & J-LT (2011). *J. Fluid Mech.* **675**, 465–476.
- Mathew, G., Mezić, I., & Petzold, L. (2005). *Physica D*, **211** (1-2), 23–46.



- Moussafir, J.-O. (2006). *Func. Anal. and Other Math.* **1** (1), 37–46.
- Stremmer, M. A. & Chen, J. (2007). *Phys. Fluids*, **19**, 103602.
- J-LT (2005). *Phys. Rev. Lett.* **94** (8), 084502.
- J-LT (2010). *Chaos*, **20**, 017516.
- J-LT (2012). *Nonlinearity*, **25** (2), R1–R44.
- J-LT & Finn, M. D. (2006). *Phil. Trans. R. Soc. Lond. A*, **364**, 3251–3266.
- J-LT, Finn, M. D., Gouillart, E., & Hall, T. (2008). *Chaos*, **18**, 033123.
- Thurston, W. P. (1988). *Bull. Am. Math. Soc.* **19**, 417–431.
- Tumasz, S. E. & J-LT (2013). *J. Nonlinear Sci.* .