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Topological optimization and the simplest maps

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The taffy puller





[Photo and movie by M. D. Finn.]

[movie 1]

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The mixograph

Model experiment for kneading bread dough:



[Department of Food Science, University of Wisconsin. Photos by J-LT.]

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Planetary Mixers

In food processing, rods are often used for stirring.





[movie 2] ⓒBLT Inc.

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Experiment of Boyland, Aref, & Stremler





[movie 3] [movie 4]

[P. L. Boyland, H. Aref, and M. A. Stremler, J. Fluid Mech. 403, 277 (2000)]

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Braid description of taffy puller



The three rods of the taffy puller in a space-time diagram. Defines a braid on n = 3 strands, $\sigma_1^2 \sigma_2^{-2}$ (three periods shown).

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Braid description of mixograph



$\sigma_3\sigma_2\sigma_3\sigma_5\sigma_6^{-1}\sigma_2\sigma_3\sigma_4\sigma_3\sigma_1^{-1}\sigma_2^{-1}\sigma_5$ braid on B_7 , the braid group on 7 strands.

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Topological entropy of a braid

Burau representation for 3-braids:

$$[\sigma_1] = \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix}, \qquad [\sigma_2] = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix},$$
$$\sigma_1^{-1} \sigma_2] = [\sigma_1^{-1}] \cdot [\sigma_2] = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}.$$

This matrix has spectral radius $(3 + \sqrt{5})/2$ (Golden Ratio²), and hence the topological entropy is log[$(3 + \sqrt{5})/2$].

This is the growth rate of a 'rubber band' caught on the rods.

This matrix trick only works for 3-braids, unfortunately.



Optimizing over generators

- Entropy can grow without bound as the length of a braid increases;
- A proper definition of optimal entropy requires a cost associated with the braid.
- Divide the entropy by the smallest number of generators required to write the braid word.
- For example, the braid $\sigma_1^{-1} \sigma_2$ has entropy $\log[(3 + \sqrt{5})/2]$ and consists of two generators.
- Its Topological Entropy Per Generator (TEPG) is thus $\frac{1}{2} \log[(3 + \sqrt{5})/2] = \log[\text{Golden Ratio}].$
- Assume all the rods move.

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Optimal braid

- In B_3 and B_4 , the optimal TEPG is log[Golden Ratio].
- Realized by $\sigma_1^{-1}\sigma_2$ and $\sigma_1^{-1}\sigma_2\sigma_3^{-1}\sigma_2$, respectively.
- In B_n , n > 4, the optimal TEPG is $< \log[Golden Ratio]$.

Why? Recall Burau representation:

$$[\sigma_1] = \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix}, \qquad [\sigma_2] = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix},$$

Its spectral radius provides a lower bound on entropy. However,

$$|[\sigma_1]| = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \qquad |[\sigma_2]| = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix},$$

provides an upper bound! Need to find Joint Spectral Radius.



Periodic Array of Rods

- Consider periodic lattice of rods.
- Move all the rods such that they execute σ₁ σ₂⁻¹ with their neighbor (Boyland et al., 2000).



- The entropy per 'switch' is $log(1 + \sqrt{2})$, the Silver Ratio!
- This is optimal for a periodic lattice of two rods (follows from D'Alessandro et al. (1999)).
- Also optimal if we assign cost by simultaneous operation.

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Silver Mixers!

- The designs with entropy given by the Silver Ratio can be realized with simple gears.
- All the rods move at once: very efficient.



[movie 5]

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Build it!





[movie 6] [movie 7]



Experiment: Silver mixer with four rods





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Silver mixer with six rods



[movie 8]



The Minimizer problem

- On a given surface of genus g, which pA has the least λ ?
- If the foliation is orientable (vector field), then things are much simpler;
- Action of the pA on first homology captures dilatation λ;
- Polynomials of degree 2g;
- Procedure:
 - We have a guess for the minimizer;
 - Find all integer-coefficient, reciprocal polynomials that could have smaller largest root;
 - Show that they can't correspond to pAs;
 - For the smallest one that can, construct pA.

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Newton's formulas

We need an efficient way to bound the number of polynomials with largest root smaller than $\lambda.$ Given a reciprocal polynomial

$$P(x) = x^{2g} + a_1 x^{2g-1} + \dots + a_2 x^2 + a_1 x + 1$$

we have Newton's formulas for the traces,

$$\operatorname{Tr}(\phi_*^k) = -\sum_{m=1}^{k-1} a_m \operatorname{Tr}(\phi_*^{k-m}) - ka_k,$$

where

- ϕ is a (hypothetical) pA associated with P(x);
- ϕ_* is the matrix giving the action of the pA ϕ on first homology;
- $Tr(\phi_*)$ is its trace.

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Bounding the traces

The trace satisfies

$$|\operatorname{Tr}(\phi_*^k)| = \left|\sum_{m=1}^g (\lambda_m^k + \lambda_m^{-k})\right| \le g(r^k + r^{-k})$$

where λ_m are the roots of ϕ_* , and $r = \max_m(|\lambda_m|)$.

- Bound $\operatorname{Tr}(\phi_*^k)$ with $r < \lambda$, $k = 1, \dots, g$;
- Use these g traces and Newton's formulas to construct candidate P(x);
- Overwhelming majority have fractional coeffs \rightarrow discard!
- Carefully check the remaining polynomials:
 - Is their largest root real?
 - Is it strictly greater than all the other roots?
 - Is it really less than λ ?
- Largest tractable case: $g = 8 (10^{12} \text{ polynomials})$.

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Lefschetz's fixed point theorem

This procedure still leaves a fair number of polynomials — though not enormous (10's to 100's, even for g = 8.) The next step involves using Lefschetz's fixed point theorem to eliminate more polynomials:

$$L(\phi) = 2 - \operatorname{Tr}(\phi_*) = \sum_{\boldsymbol{p} \in \operatorname{Fix}(\phi)} \operatorname{Ind}(\phi, \boldsymbol{p})$$

where

- $L(\phi)$ is the Lefschetz number;
- Fix(φ) is set of fixed points of φ;
- $\operatorname{Ind}(\phi, p)$ is index of ϕ at p.

We can easily compute $L(\phi^k)$ for every iterate using Newton's formula.



Eliminating polynomials

Outline of procedure: for a surface of genus g,

- Use the Euler–Poincaré formula to list possible singularity data for the foliations;
- For each singularity data, compute possible contributions to the index (depending on how the singularities and their separatrices are permuted);
- Check if index is consistent with Lefschetz's theorem.

With this, we can reduce the number of polynomials to one or two!

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Minimizers for orientable foliations

g	polynomial	minimizer
2	$X^4 - X^3 - X^2 - X + 1$	$\simeq 1.72208$ †
3	$X^6 - X^4 - X^3 - X^2 + 1$	$\simeq 1.40127$
4	$X^8 - X^5 - X^4 - X^3 + 1$	$\simeq 1.28064$
5	$X^{10} + X^9 - X^7 - X^6 - X^5 - X^4 - X^3 + X + 1$	$\simeq 1.17628$ *
6	$X^{12} - X^7 - X^6 - X^5 + 1$	$\gtrsim 1.17628$
7	$X^{14} + X^{13} - X^9 - X^8 - X^7 - X^6 - X^5 + X + 1$	$\simeq 1.11548$
8	$X^{16} - X^9 - X^8 - X^7 + 1$	$\simeq 1.12876$

- † Zhirov (1995)'s result; also for nonorientable [Lanneau-T];
- * Lehmer's number; realized by Leininger (2004)'s pA;
- For genus 6 we have not explicitly constructed the pA;
- Genus 6 is the first nondecreasing case.
- Genus 7 and 8: pA's found by Aaber & Dunfield (2010) and Kin & Takasawa (2010b) [g = 7]; Hironaka (2009) [g = 8].



- Having rods undergo 'braiding' motion guarantees a minimal amound of entropy (stretching of material lines).
- Can optimize to find the best rod motions, but depends on choice of 'cost function.'
- For two natural cost functions, the Golden Ratio and Silver Ratio pop up!
- Found orientable minimizer on surfaces of genus g ≤ 8; only known nonorientable case is for genus 2.

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