

Lecture 9: Finite-time Lyapunov exponents

Last time:

$$\lambda_X^{(r)} = \lim_{t \rightarrow \infty} \frac{1}{t} \log \|D\varphi_t(X)\nu\|$$

For ergodic systems, $\lambda_X^{(r)} = \lambda^{(r)}$.

Now consider dropping the limit:

$$\lambda_X^{(r)}(t) = \frac{1}{t} \log \|D\varphi_t(X)\nu\|$$

Now even for ergodic systems these are a function of X .

Consider the SVD of $D\varphi_t(X)$:

$$D\varphi_t(X) = U_t(X) D_t(X) V_t^T(X).$$

Drop the t 's and X 's

$$\begin{aligned} \|D\varphi_t(X)\nu\|^2 &= \nu \cdot D\varphi_t^T D\varphi_t \cdot \nu \\ &= \nu \cdot V D^2 V^T \cdot \nu \end{aligned}$$

Now choose $\nu_i^{(h)} = V_{ih}$, the h th column of V .

$$\begin{aligned}
\| D\varphi_t(X) v^{(h)} \|^2 &= v_i^{(h)} V_{im} D_{ml}^2 V_{jl} v_j^{(h)} \\
&= V_{ih} V_{im} D_{ml}^2 V_{jl} V_{jk} \\
&= D_{hh}^2 \quad (\text{no sum over } h)
\end{aligned}$$

So even for finite time we can define the eigenspaces. We have also

$$D_{hh} = e^{\lambda_x^{(h)}(t) t}$$

It is convenient to derive equations for the time-evolution of the SVD.

Recall: $\frac{d}{dt} D\varphi_t = (\nabla u)^T D\varphi_t$

Let $M = D\varphi_t$, $A = (\nabla u)^T$.

$$\dot{M} = AM, \quad M = UDV^T$$

$$\dot{M} = \dot{U}DV^T + U\dot{D}V^T + U\dot{V}^T = AM$$

$$(*) \quad U^T \dot{U} D + \dot{D} + D \dot{V}^T V = \underbrace{U^T A U}_{\hat{A}}$$

Note that $U^T \dot{U}$ is antisymmetric, since

$$\frac{d}{dt} (U^T U) = 0 = \dot{U}^T U + U^T \dot{U}$$

$$(U^T \dot{U})^T = -U^T \dot{U}$$

and similarly for $V^T \dot{V}$.

$$(U^T \dot{U} D)_{ij} = (U^T \dot{U})_{ih} D_{hj} = (U^T \dot{U})_{ij} D_{jj}$$

$$(D \dot{V}^T V)_{ij} = D_{ih} (\dot{V}^T V)_{hj} = D_{ii} (\dot{V}^T V)_{ij}$$

No sum
over j

Hence, if we evaluate the matrix equation (*) on its diagonal ($i=j$), we find:

$$\underbrace{(U^T \dot{U})_{ii}}_0 D_{ii} + \dot{D}_{ii} + D_{ii} \underbrace{(\dot{V}^T V)_{ii}}_0 = \hat{A}_{ii} D_{ii}$$

(no sum over i)

$$\dot{D}_{ii} = \hat{A}_{ii} D_{ii}$$

(no sum over i)

Equation for
eigenvalues of M
(depends on U)

Next we need equations for U and V.

Take (*) again but evaluate for $i \neq j$:

$$(1) \quad (U^T \dot{U})_{ij} D_{jj} + \underbrace{\dot{D}_{ij}}_0 + D_{ii} (\dot{V}^T V)_{ij} = \hat{A}_{ij} D_{jj}$$

$(i \neq j, \text{ no sum over } i \text{ and } j)$

Interchange i, j :

$$(U^T \dot{U})_{ji} D_{ii} + D_{jj} (\dot{V}^T V)_{ji} = \hat{A}_{ji} D_{ii}$$

$$(2) \quad -(U^T \dot{U})_{ij} D_{ii} - D_{jj} (\dot{V}^T V)_{ij} = \hat{A}_{ji} D_{ii}$$

Now divide (1) by D_{jj} and (2) by D_{ii} and add:

$$\left(\frac{D_{ii}}{D_{jj}} - \frac{D_{jj}}{D_{ii}} \right) (\dot{V}^T V)_{ij} = \hat{A}_{ij} + \hat{A}_{ji}$$

$$\text{let } \Delta_{ij} = D_{ii} / D_{jj}.$$

$$(\dot{V}^T V)_{ij} = \frac{\hat{A}_{ij} + \hat{A}_{ji}}{\Delta_{ij} - \Delta_{ji}}$$

$(i \neq j)$

The RHS is antisym in $i \leftrightarrow j$, as required

Note that $(\dot{V}^T V)_{ij} = 0$ for $i=j$.

Can turn this into an equation for \dot{V} :

$$\dot{V}_{ij} = -V_{il} (\dot{V}^T V)_{lj}$$

Now $\Delta_{ij} = D_{ii}/D_{jj}$

with $D_{ii} = e^{\lambda^{(i)} t}$

Since:

$$\begin{aligned} (\dot{V}^T V) V^T &= \dot{V}^T \\ V (\dot{V}^T V)^T &= \dot{V} \\ -V (\dot{V}^T V) &= \dot{V} \end{aligned}$$

Now assume we order the exponents such that

$$\lambda^{(1)} > \lambda^{(2)} > \dots > \lambda^{(n)}$$

(Reverse from theorem, but more convenient at this point.)

Then $\Delta_{ij} = e^{(\lambda^{(i)} - \lambda^{(j)}) t}$

For large t , $\Delta_{ij} \rightarrow \begin{cases} \infty, & i < j \\ -\infty, & i > j \end{cases}$

So $\Delta_{ij} + \Delta_{ji} \rightarrow \exp(|\lambda^{(i)} - \lambda^{(j)}| t) + O(-|\lambda^{(i)} - \lambda^{(j)}| t),$
 $t \rightarrow \infty$

Hence,

$$(\dot{V}V)_{ij} = e^{-|\lambda^{(i)} - \lambda^{(j)}|t} (\hat{A}_{ij} + \hat{A}_{ji}) + O(e^{-2|\lambda^{(i)} - \lambda^{(j)}|t}),$$

$t \rightarrow \infty$

Conclude:

$\dot{V} \rightarrow 0$ exponentially, at a rate given by the 'gap' between exponents.

This will happen even if the $\lambda^{(i)}$ themselves haven't quite converged yet.

This is typical: the Lyapunov exponents often converge slowly, but the characteristic direction on a given trajectory converges very rapidly.

What about the U ?

Take $\frac{(1)}{D_{ii}} + \frac{(2)}{D_{jj}}$:

$$(U^T \dot{U})_{ij} \Delta_{ji} + (\dot{V}^T V)_{ij} = \hat{A}_{ij} \Delta_{ji}$$

$$-(U^T \dot{U})_{ij} \Delta_{ij} - (\dot{V}^T V)_{ij} = \hat{A}_{ji} \Delta_{ij}$$

$$\Rightarrow (U^T \dot{U})_{ij} (\Delta_{ji} - \Delta_{ij}) = \Delta_{ij} \hat{A}_{ji} + \Delta_{ji} \hat{A}_{ij}$$

$$(U^T \dot{U})_{ij} = \frac{\Delta_{ij} \hat{A}_{ji} + \Delta_{ji} \hat{A}_{ij}}{(\Delta_{ji} - \Delta_{ij})}$$

(i ≠ j, no sum over i and j)

For large t,

$$(U^T \dot{U})_{ij} = \begin{cases} -\hat{A}_{ji}, & i < j \\ \hat{A}_{ij}, & i > j \end{cases} \quad t \rightarrow \infty$$

So $\dot{U} \neq 0 \Rightarrow U$ doesn't converge.