

HW 9 Solutions

① (a) $T(p(x)) = 2x(2x+3) + 2$
$$= \boxed{4x^2 + 6x + 2}$$

(b) 1. $x^2 + 3x + 2 = \alpha_1 \cdot 1 + \alpha_2 \cdot x + \alpha_3(2x^2 + 1)$

$$2\alpha_3 = 1$$

$$\alpha_1 = 3/2$$

$$\alpha_2 = 3$$

$$\rightarrow \alpha_2 = 3$$

$$\alpha_1 + \alpha_3 = 2$$

$$\alpha_3 = 1/2$$

$$\boxed{[p]_{\mathcal{B}} = \begin{pmatrix} 3/2 \\ 3 \\ 1/2 \end{pmatrix}}$$

2. $T(p) = 4x^2 + 6x + 2 = \alpha_1 \cdot 1 + \alpha_2 \cdot x + \alpha_3(2x^2 + 1)$

$$2\alpha_3 = 4$$

$$\alpha_1 = 0$$

$$\alpha_2 = 6$$

$$\rightarrow \alpha_2 = 6$$

$$\alpha_1 + \alpha_3 = 2$$

$$\alpha_3 = 2$$

$$\boxed{[T(p)]_{\mathcal{B}} = \begin{pmatrix} 0 \\ 6 \\ 2 \end{pmatrix}}$$

3. $[T]_{\mathcal{B}} = ([T_{v_1}]_{\mathcal{B}} \quad [T_{v_2}]_{\mathcal{B}} \quad [T_{v_3}]_{\mathcal{B}})$

$$T_{v_1} = T(1) = 2x \cdot 0 + 0 = 0 \quad \text{so} \quad [T_{v_1}]_{\mathcal{B}} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$T_{v_2} = T(x) = 2x \cdot 1 + 0 = 2x \quad \text{so} \quad [T_{v_2}]_{\mathcal{B}} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$$

$$T_{v_3} = T(2x^2 + 1) = 2x(4x) + 4 = 4(2x^2 + 1) \quad \text{so} \quad [T_{v_3}]_{\mathcal{B}} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix}$$

$$\boxed{[T]_{\mathcal{B}} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix}}$$

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$$(b) \quad 4. \quad [T]_{\mathcal{B}}[p]_{\mathcal{B}} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix} \begin{pmatrix} 3/2 \\ 3 \\ 1/2 \end{pmatrix} = \begin{pmatrix} 0 \\ 6 \\ 2 \end{pmatrix} = [T(p)]_{\mathcal{B}}.$$

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(a) Done!

$$(b) \quad 1. \quad x^2 + 3x + 2 = \alpha_1 \cdot 1 + \alpha_2 \cdot (x+1) + \alpha_3 (x^2 + x + 1)$$

$$\begin{aligned} \alpha_3 &= 1 & \alpha_1 &= -1 \\ \alpha_3 + \alpha_2 &= 3 & \rightarrow \alpha_2 &= 2 \\ \alpha_3 + \alpha_2 + \alpha_1 &= 2 & \alpha_3 &= 1 \end{aligned} \quad \boxed{[p]_{\mathcal{C}} = \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}}$$

$$2. \quad [v_1]_{\mathcal{C}}: \quad 1 = \alpha_1 \cdot 1 + \alpha_2 \cdot (x+1) + \alpha_3 (x^2 + x + 1)$$

$$\rightarrow \alpha_1 = 1, \alpha_2 = 0, \alpha_3 = 0$$

$$[v_1]_{\mathcal{C}} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$[v_2]_{\mathcal{C}}: \quad x = \alpha_1 \cdot 1 + \alpha_2 (x+1) + \alpha_3 (x^2 + x + 1)$$

$$\rightarrow \alpha_1 = -1, \alpha_2 = 1, \alpha_3 = 0$$

$$[v_2]_{\mathcal{C}} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$[v_3]_{\mathcal{C}}: \quad 2x^2 + 1 = \alpha_1 \cdot 1 + \alpha_2 (x+1) + \alpha_3 (x^2 + x + 1)$$

$$\rightarrow \alpha_1 = 1, \alpha_2 = -2, \alpha_3 = 2$$

$$[v_3]_{\mathcal{C}} = \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix}$$

$$\boxed{M_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 2 \end{pmatrix}}$$

(2)

$$(b) \quad 3. M_{e \leftarrow B} [p]_B = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 3/2 \\ 3 \\ 1/2 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix} = [p]_e.$$

$$(c) \quad 1. [T]_e = ([Tw_1]_e \quad [Tw_2]_e \quad [Tw_3]_e)$$

$$Tw_1 = T(1) = 0 \quad \text{so} \quad [Tw_1]_e = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$Tw_2 = T(x+1) = 2x \cdot 1 + 0 \cdot 2x = \alpha_1 \cdot 1 + \alpha_2 (x+1) + \alpha_3 (x^2+x+1)$$

$$\rightarrow \alpha_1 = -2 \quad \alpha_2 = 2 \quad \alpha_3 = 0$$

$$\text{so } [Tw_2]_e = \begin{pmatrix} -2 \\ 2 \\ 0 \end{pmatrix}$$

$$Tw_3 = T(x^2+x+1) = 2x(2x+1) + 2$$

$$= 4x^2 + 2x + 2 = \alpha_1 \cdot 1 + \alpha_2 (x+1) + \alpha_3 (x^2+x+1)$$

$$\rightarrow \alpha_1 = 0 \quad \alpha_2 = -2 \quad \alpha_3 = 4$$

$$\text{so } [Tw_3]_e = \begin{pmatrix} 0 \\ -2 \\ 4 \end{pmatrix} \quad \text{and}$$

$$\boxed{[T]_e = \begin{pmatrix} 0 & -2 & 0 \\ 0 & 2 & -2 \\ 0 & 0 & 4 \end{pmatrix}}$$

$$2. \quad \left(\begin{array}{ccc|ccc} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -2 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1 \end{array} \right) \xrightarrow[R_2 + R_3]{R_1 - \frac{1}{2}R_3} \left(\begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & -1/2 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 2 & 0 & 0 & 1 \end{array} \right)$$

$$\xrightarrow[R_1 + R_2]{1/2 R_3} \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 1/2 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 0 & 0 & 1/2 \end{array} \right)$$

$$\boxed{(M_{e \leftarrow B})^{-1} = \begin{pmatrix} 1 & 1 & 1/2 \\ 0 & 1 & -1 \\ 0 & 0 & 1/2 \end{pmatrix}}$$

$$\text{Note: } (M_{e \leftarrow B})^{-1} = M_{B \leftarrow e}$$

$$(2) \quad (c) \quad 3. \quad (M_{C \leftarrow B})^{-1} [T]_C M_{C \leftarrow B} = \begin{pmatrix} 1 & 1 & 1/2 \\ 0 & 1 & 1/2 \\ 0 & 0 & 1/2 \end{pmatrix} \begin{pmatrix} 0 & -2 & 0 \\ 0 & 2 & -2 \\ 0 & 0 & 4 \end{pmatrix} \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix} = [T]_B$$

(3) (a) Note that $T - \lambda \text{Id}$ is a linear transformation. Thus,

$$(T - \lambda \cdot \text{Id}) 0_V = 0_V = (T - \lambda \cdot \text{Id}) v$$

$$\text{but } v \neq 0_V$$

so $T - \lambda \cdot \text{Id}$ is not one-to-one. In particular, it is not invertible.

$$(b) \quad A_\lambda = [T - \lambda \cdot \text{Id}]_B = \left([(T - \lambda \cdot \text{Id})v_1]_B \quad [(T - \lambda \cdot \text{Id})v_2]_B \quad [(T - \lambda \cdot \text{Id})v_3]_B \right)$$

$$(T - \lambda \cdot \text{Id})v_1 = T(1) - \lambda \cdot \text{Id}(1) = 0 - \lambda = -\lambda \quad \text{so } [(T - \lambda \cdot \text{Id})v_1]_B = \begin{pmatrix} -\lambda \\ 0 \\ 0 \end{pmatrix}$$

$$(T - \lambda \cdot \text{Id})v_2 = T(x) - \lambda \cdot \text{Id}(x) = 2x - \lambda x = (2 - \lambda)x \quad \text{so } [(T - \lambda \cdot \text{Id})v_2]_B = \begin{pmatrix} 0 \\ 2 - \lambda \\ 0 \end{pmatrix}$$

$$(T - \lambda \cdot \text{Id})v_3 = T(x^2) - \lambda \cdot \text{Id}(x^2) = 4x^2 + 2 - \lambda x^2 = (4 - \lambda)x^2 + 2 \quad \text{so } [(T - \lambda \cdot \text{Id})v_3]_B = \begin{pmatrix} 2 \\ 0 \\ 4 - \lambda \end{pmatrix}$$

$$\text{and } A_\lambda = \begin{pmatrix} -\lambda & 0 & 2 \\ 0 & 2 - \lambda & 0 \\ 0 & 0 & 4 - \lambda \end{pmatrix}$$

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$$(b) P_A(\lambda) = \det A_\lambda = -\lambda(2-\lambda)(4-\lambda)$$

since A_λ is upper triangular.

Clearly, the roots of $P_A(\lambda)$ are $\lambda=0, 2, 4$.

$$(c) \lambda=0 \quad \ker A_0 = \ker \begin{pmatrix} 0 & 0 & 2 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{pmatrix} \quad \begin{array}{l} 2z=0 \\ 2y=0 \\ x=t \end{array}$$

$$V_0 = \ker A_0 = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} t \mid t \in \mathbb{R} \right\}$$

Then $B_0 = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$ is a basis for V_0 .

$$\lambda=2 \quad \ker A_2 = \ker \begin{pmatrix} -2 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \quad \begin{array}{l} 2z=0 \\ -2x+2z=0 \\ -2x=0 \end{array} \quad \begin{array}{l} y=t \\ z=0 \\ x=t \end{array}$$

$$V_2 = \ker A_2 = \left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} t \mid t \in \mathbb{R} \right\}$$

Then $B_2 = \left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$ is a basis for V_2 .

$$\lambda=4 \quad \ker A_4 = \ker \begin{pmatrix} -4 & 0 & 2 \\ 0 & -2 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} -4x+2z=0 \\ -2y=0 \\ z=t \end{array} \quad \begin{array}{l} x=\frac{1}{2}z \\ y=0 \\ z=t \end{array}$$

$$V_4 = \ker A_4 = \left\{ \begin{pmatrix} 1/2 \\ 0 \\ 1 \end{pmatrix} t \mid t \in \mathbb{R} \right\}$$

Then $B_4 = \left\{ \begin{pmatrix} 1/2 \\ 0 \\ 1 \end{pmatrix} \right\}$ is a basis for V_4 .

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$$(a) A_\lambda = A - \lambda \cdot I = \begin{pmatrix} 1-\lambda & 2 & 0 \\ 0 & 3-\lambda & 0 \\ 2 & -4 & 2-\lambda \end{pmatrix}$$

$$\det A_\lambda = (2-\lambda)(1-\lambda)(3-\lambda)$$

has roots $\lambda = 1, 2, 3$

$$\lambda = 1 \quad \ker A_1 = \ker \begin{pmatrix} 0 & 2 & 0 \\ 0 & 2 & 0 \\ 2 & -4 & 2 \end{pmatrix} \quad \begin{array}{l} 2y = 0 \rightarrow y = 0 \\ 2x - 4y + 2z = 0 \\ x = -z \quad z = t \end{array}$$

$$V_1 = \ker A_1 = \left\{ \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} t \mid t \in \mathbb{R} \right\}$$

Then $B_1 = \left\{ \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \right\}$ is a basis for V_1 .

$$\lambda = 2 \quad \ker A_2 = \ker \begin{pmatrix} -1 & 2 & 0 \\ 0 & 1 & 0 \\ 2 & -4 & 0 \end{pmatrix} \quad \begin{array}{l} y = 0 \\ -x + 2y = 0 \\ x = 0 \end{array} \quad z = t$$

$$V_2 = \ker A_2 = \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} t \mid t \in \mathbb{R} \right\}$$

Then $B_2 = \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ is a basis for V_2 .

$$\lambda = 3 \quad \ker A_3 = \ker \begin{pmatrix} -2 & 2 & 0 \\ 0 & 0 & 0 \\ 2 & -4 & -1 \end{pmatrix} \quad \begin{array}{l} 2x + 2y = 0 \\ 2x - 4y - z = 0 \\ y = t \end{array} \quad \begin{array}{l} x = -y \\ z = 4y - 2x \end{array}$$

$$V_3 = \ker A_3 = \left\{ \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} t \mid t \in \mathbb{R} \right\}$$

Then $B_3 = \left\{ \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} \right\}$ is a basis for V_3 .

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$$(b) A_\lambda = A - \lambda \cdot I = \begin{pmatrix} 3-\lambda & 2 & 1 \\ 1 & 2-\lambda & -1 \\ -1 & 2 & 5-\lambda \end{pmatrix}$$

$$\det A_\lambda = (3-\lambda) \left((2-\lambda)(5-\lambda) + 2 \right) - 2(5-\lambda-1) + 1(2+(2-\lambda))$$

(cofactor expansion)

$$= (3-\lambda)(12-7\lambda+\lambda^2) - 10 + 2\lambda + 2 + 2 + 2 - \lambda$$

$$= 36 - 21\lambda + 3\lambda^2 - 10 + 2\lambda + 2 + 2 + 2 - \lambda$$

$$= -\lambda^3 + 10\lambda^2 - 32\lambda + 32$$

$$= -(\lambda-2)(\lambda-4)^2$$

roots of $\lambda = 2, 4$.

$$\lambda = 2 \quad \ker A_2 = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 0 & -1 \\ -1 & 2 & 3 \end{pmatrix}$$

$$\left(\begin{array}{ccc|ccc} 1 & 2 & 1 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 & 0 \\ -1 & 2 & 3 & 0 & 0 & 0 \end{array} \right) \xrightarrow[R_2 - R_1]{R_3 + R_1} \left(\begin{array}{ccc|ccc} 1 & 2 & 1 & 0 & 0 & 0 \\ 0 & -2 & -2 & 0 & 0 & 0 \\ 0 & 4 & 4 & 0 & 0 & 0 \end{array} \right) \xrightarrow[R_2 + 2R_2]{R_1 + R_2} \left(\begin{array}{ccc|ccc} 1 & 0 & -1 & 0 & 0 & 0 \\ 0 & -2 & -2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$x - z = 0$$

$$y = -z$$

$$z = t$$

$$V_2 = \ker A_2 = \left\{ \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} t \mid t \in \mathbb{R} \right\}$$

Then $\mathcal{B}_2 = \left\{ \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \right\}$ is a basis

for V_2 .

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(5) $\lambda = 4$

$$\ker V_4 = \ker \begin{pmatrix} -1 & 2 & 1 \\ 1 & -2 & -1 \\ -1 & 2 & 1 \end{pmatrix}$$

$$\left(\begin{array}{ccc|c} -1 & 2 & 1 & 0 \\ 1 & -2 & -1 & 0 \\ -1 & 2 & 1 & 0 \end{array} \right) \xrightarrow{\substack{R_2+R_1 \\ R_3-R_1}} \left(\begin{array}{ccc|c} -1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$-x + 2y + z = 0$$

$$y = s$$

$$z = t$$

$$x = 2y + z$$

$$V_4 = \ker A_4 = \left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} s + \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} t \mid s, t \in \mathbb{R} \right\}$$

Then a basis for V_4 is $\mathcal{B}_4 = \left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\}$.