

## II Representation theory of UFAHA

until further notice:

$\mathbb{F}$  alg closed

$0 \neq q \in \mathbb{F}$

$q^2 \neq 1$

LEM 1 Let  $V$  denote a fid. mod

$\hat{H}_q$ -module. Then for  $i \in \mathbb{I}$   $\exists$

$0 \neq k_i \in \mathbb{F}$  s.t.

$$(T_i - (k_i + k_i^{-1})\mathbb{F})V = 0$$

"ith corresp parameter"

$k_i$  is defined up to reciprocal.

p.f. Since  $\mathbb{F}$  is alg closed and  $\dim V < \infty$

by Schur's lemma  $\exists K_i \in \mathbb{F}$  s.t.

$$(T_i - K_i)V = 0$$

Since  $\mathbb{F}$  is alg closed the poly

$$\lambda^2 - K_i \lambda + 1$$

has a root in  $\mathbb{F}$ , call it  $k_i$ . obs

$$k_i + k_i^{-1} = K_i$$

Result follows.

$\hat{H}_q$ -modules vs  $H(k_0, k_1, k_2, k_3; q)$ -modules

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Given  $n$  mod  $\{k_i\}_{i \in \mathbb{I}}$  in  $\mathbb{F}$

Let  $V$  denote a  $H(k_0, k_1, k_2, k_3; q)$ -module.

The module structure induces an  $\mathbb{F}$ -algebra hom

$$H(k_0, k_1, k_2, k_3; q) \longrightarrow \text{End}(V)$$

Consider comp

$$\hat{H}_q \longrightarrow H(k_0, k_1, k_2, k_3; q) \longrightarrow \text{End}(V)$$

$$T_i \longrightarrow k_i t_i^{\rightarrow}$$

This gives a  $\hat{H}_q$ -module str on  $V$ .

Conversely let  $V$  denote a f.d.  $\hat{H}_q$ -module.

with corresp param  $\{k_i\}_{i \in \mathbb{I}}$

By L4  $\hat{H}_q$ -module str on  $V$  induces a

$H(k_0, k_1, k_2, k_3; q)$ -module str on  $V$

Conclusion

In the f.d.  $\hat{H}_q$  case

the rep theory of DAHA and VDAHA

is the same.

Let  $V$  denote a  $H_1$  module

[not nec. ~~fixed~~.]

$\forall i \in I$  and  $0 \neq k_i \in F$

We say  $V$  has parameter  $k_i$

if the parameter  $k_i$  exists whenever

$$(T_i - (k_i + k_i^{-1})1) V = 0$$

Let  $V$  denote a  $\hat{H}_g$ -module

For  $h \in \hat{H}_g$  and  $\theta \in F$  define

$$V_h(\theta) = \{ v \in V \mid hv = \theta v \}$$

eigenspace for  $h$  with eigenvalue  $\theta$

LEM 2 Given a  $\hat{H}_g$ -module  $V$  with parameter  $k_0$ . Assume  $k_0 \neq \pm 1$ . Then

$$V = V_{t_0}(k_0) + V_{t_0}(k_0^{-1}) \quad (\text{ds. +vs.})$$

Moreover each of  $V_{t_0}(k_0^{\pm 1})$  is invariant under  $\hat{H}_g^+$

pf on  $V$

$$t_0 + t_0^{-1} = T_0 = k_0 + k_0^{-1}$$

$$\text{so } (t_0 - k_0)(t_0 - k_0^{-1}) = 0$$

$k_0 \neq \pm 1$  so  $k_0 \neq k_0^{-1}$  so

$t_0$  is diagonalizable on  $V$  with all eigenvalues of  $t_0$  in  $\{k_0, k_0^{-1}\}$ .

To get the last assertion of the lemma recall  $t_0$  commutes with everything in  $\hat{H}_g^+$

□

Note Ref to Lem 2 we will see:

each of  $V_{t_0}(k_0^{\pm 1})$  is used as a  $H_q^+$ -module

Moreover if  $\dim V < \infty$  then  $A, B$  act on each  
of  $V_{t_0}(k_0^{\pm 1})$  as a Leonard pair.

DEF 3 Define

$$G_0 = t_0 - t_3 t_0 t_3^{-1}$$

$$G_1 = t_1 - t_0 t_1 t_0^{-1}$$

$$G_2 = t_2 - t_1 t_2 t_1^{-1}$$

$$G_3 = t_3 - t_2 t_3 t_2^{-1}$$

Recall the aut of  $\hat{H}_9$  that sends

$$t_0 \rightarrow t_1 \rightarrow t_2 \rightarrow t_3 \rightarrow t_0$$

This aut sends

$$G_0 \rightarrow G_1 \rightarrow G_2 \rightarrow G_3 \rightarrow G_0$$

LEM ~~8~~

We have

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$$(i) \quad X G_0 = G_0 X^{-1} \quad X^{-1} G_0 = G_0 X$$

$$(ii) \quad Y G_1 = G_1 Y^{-1} \quad Y^{-1} G_1 = G_1 Y$$

$$(iii) \quad X G_2 = q^{-2} G_2 X^{-1} \quad X^{-1} G_2 = q^2 G_2 X$$

$$(iv) \quad Y G_3 = q^{-2} G_3 Y^{-1} \quad Y^{-1} G_3 = q^2 G_3 Y$$

pf (i)

Recall

$$t_0 (t_0 t_3 - t_3 t_0) = (t_0 t_3 - t_3 t_0) t_0^{-1}$$

$$t_3 (t_0 t_3 - t_3 t_0) = (t_0 t_3 - t_3 t_0) t_3^{-1}$$

so

$$t_3 t_0 (t_0 t_3 - t_3 t_0) = (t_0 t_3 - t_3 t_0) t_3^{-1} t_0^{-1}$$

$$= (t_0 - t_3 t_0 t_3^{-1}) t_0^{-1}$$

Mult each term on right by  $t_3^{-1}$ :

$$\underbrace{t_3 t_0}_X \underbrace{(t_0 - t_3 t_0 t_3^{-1})}_{G_0} = t_3 t_0 (t_0 t_3 - t_3 t_0) t_3^{-1}$$

$$= \underbrace{(t_0 - t_3 t_0 t_3^{-1})}_{G_0} \underbrace{t_0^{-1} t_3^{-1}}_{X^{-1}}$$

(iii)-(iv) apply  $Z_4$ -action to (i)

□

LEM 5 let  $V$  denote a  $\hat{H}_q$  module.

(i)  $V_x(0) = 0$        $V_y(0) = 0$

(ii)  $\forall \theta \neq 0 \in \mathbb{F}$

$$G_0 V_x(\theta) \subseteq V_x(\theta^{-1})$$

$$G_2 V_x(\theta) \subseteq V_x(q^{-2}\theta^{-1})$$

[Caution: poss  $\theta = \theta^{-1}$  or  $\theta = q^{-2}\theta^{-1}$ ]

(iii)  $\forall \theta \neq 0 \in \mathbb{F}$

$$G_1 V_y(\theta) \subseteq V_y(\theta^{-1})$$

$$G_3 V_y(\theta) \subseteq V_y(q^{-2}\theta^{-1})$$

pf (i)  $x^{-1}, y^{-1}$  exist.

(ii) Show\* Given  $v \in V_x(\theta)$

$$xv = \theta v \qquad x^{-1}v = \theta^{-1}v$$

$$x G_0 = G_0 x^{-1}$$

$$\Rightarrow x G_0 v = G_0 \underbrace{x^{-1}v}_{\theta^{-1}v}$$

$$x G_0 v = \theta^{-1} G_0 v$$

$$G_0 v \in V_x(\theta^{-1})$$

Given \*

(iii) Sim to (ii)



Cor 6 let  $V$  denote a  $\hat{H}_q$ -module.

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Given  $\theta \in \mathbb{F}$  s.t.  $V_x(\theta) \neq 0$

(i) Eitan

$$G_0 V_x(\theta) = 0 \quad \sim \quad V_x(\theta^{-1}) \neq 0$$

(ii) Eitan

$$G_2 V_x(\theta) = 0 \quad \sim \quad V_x(q^{-2}\theta^{-1}) \neq 0$$

[ Sim results hold for 4 ]  
— 0 —

LEM 7 We have

$$(i) \quad G_0^2 = B^2 - B T_0 T_3 + T_0^2 + T_3^2 - 4$$

$$B = X + X^*$$

$$(ii) \quad G_1^2 = A^2 - A T_0 T_1 + T_0^2 + T_1^2 - 4$$

$$A = Y + Y^*$$

$$(iii) \quad G_2^2 = (qX + q^* X^*)^2 - (qX + q^* X^*) T_1 T_2 + T_1^2 + T_2^2 - 4$$

$$(iv) \quad G_3^2 = (qY + q^* Y^*)^2 - (qY + q^* Y^*) T_2 T_3 + T_2^2 + T_3^2 - 4$$

pf (i) By L 70, 71

(iii) - (ii) Apply Z<sub>q</sub>-sym to (i)

□

We now consider the form of the polynomial L7.

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LEM 8 For indets  $a, b, \lambda$

$$(\lambda + \lambda^{-1})^2 - (\lambda + \lambda^{-1})(a + a^{-1})(b + b^{-1}) + (a + a^{-1})^2 + (b + b^{-1})^2 - 4$$

$$= \lambda^{-2} (\lambda - a/b)(\lambda - b/a)(\lambda - ab)(\lambda - 1/ab)$$

pf (ex)

details: Eval RHS

$$\lambda^{-1} (\lambda - a/b)(\lambda - b/a) = \lambda + \lambda^{-1} - a/b - b/a$$

$$\lambda^{-1} (\lambda - ab)(\lambda - 1/ab) = \lambda + \lambda^{-1} - ab - 1/ab$$

$$\text{RHS} = (\lambda + \lambda^{-1} - a/b - b/a)(\lambda + \lambda^{-1} - ab - 1/ab)$$

$$= (\lambda + \lambda^{-1})^2 - (\lambda + \lambda^{-1}) \underbrace{\left( \frac{a}{b} + \frac{b}{a} + ab + \frac{1}{ab} \right)}_{(a+a^{-1})(b+b^{-1})}$$

$$+ \underbrace{\left( \frac{a}{b} + \frac{b}{a} \right) \left( ab + \frac{1}{ab} \right)}_{\substack{a^2 + b^2 + a^{-2} + b^{-2} \\ (a+a^{-1})^2 + (b+b^{-1})^2 - 4}}$$

$$a^2 + b^2 + a^{-2} + b^{-2}$$

$$(a+a^{-1})^2 + (b+b^{-1})^2 - 4$$

Cor 9 let  $V$  denote a  ${}^1 H_q$ -module

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Given  $0 \neq \theta \in \mathbb{F}$

(i)  $G_0^2$  acts on  $V_X(\theta)$  as

$$\theta^{-2} \left( \theta - \frac{k_0}{k_3} \right) \left( \theta - \frac{k_3}{k_0} \right) \left( \theta - k_0 k_3 \right) \left( \theta - \frac{1}{k_0 k_3} \right) \mathbb{I}$$

provided the parameters  $k_0, k_3$  exist

(ii)  $G_2^2$  acts on  $V_X(\theta)$  as

$$q^2 \theta^{-2} \left( \theta - \frac{k_1}{q k_2} \right) \left( \theta - \frac{k_2}{q k_1} \right) \left( \theta - \frac{k_1 k_2}{q} \right) \left( \theta - \frac{1}{q k_1 k_2} \right) \mathbb{I}$$

provided  $k_1, k_2$  exist

(iii)  $G_1^2$  acts on  $V_Y(\theta)$  as

$$\theta^{-2} \left( \theta - \frac{k_0}{k_1} \right) \left( \theta - \frac{k_1}{k_0} \right) \left( \theta - k_0 k_1 \right) \left( \theta - \frac{1}{k_0 k_1} \right) \mathbb{I}$$

provided  $k_0, k_1$  exist

(iv)  $G_3^2$  acts on  $V_Y(\theta)$  as

$$q^2 \theta^{-2} \left( \theta - \frac{k_2}{q k_3} \right) \left( \theta - \frac{k_3}{q k_2} \right) \left( \theta - \frac{k_2 k_3}{q} \right) \left( \theta - \frac{1}{q k_2 k_3} \right) \mathbb{I}$$

provided  $k_2, k_3$  exist.

pf Combine L7, L8.

□

Prop 10 With ref to Cor 9

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Assume the param  $k_0, k_3$  exist and

$$\theta \notin \left\{ k_0/k_3, k_3/k_0, k_0/k_3, 1/k_0k_3 \right\}$$

then

(i)  $G_0^2$  is invertible on  $V_x(\theta) + V_x(\theta^{-1})$

(ii)  $G_0$  swaps

$$V_x(\theta) \quad V_x(\theta^{-1})$$

(iii)  $\dim V_x(\theta) = \dim V_x(\theta^{-1})$

pf (i) By Cor 9 (i)

(ii) By (i) and since

$$G_0 V_x(\theta) \subseteq V_x(\theta^{-1})$$

$$G_0 V_x(\theta^{-1}) \subseteq V_x(\theta)$$

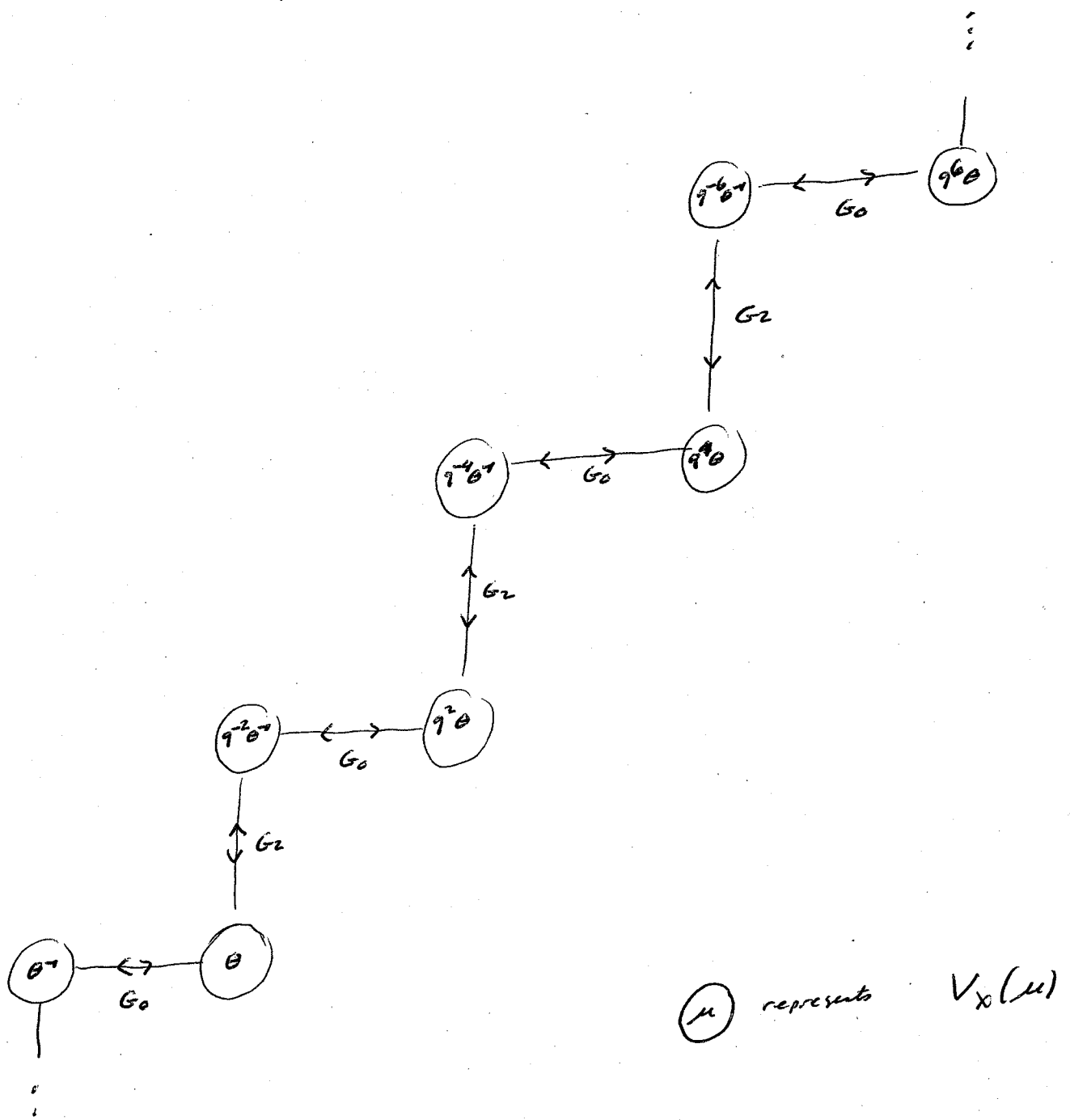
(iii) By (ii)

□

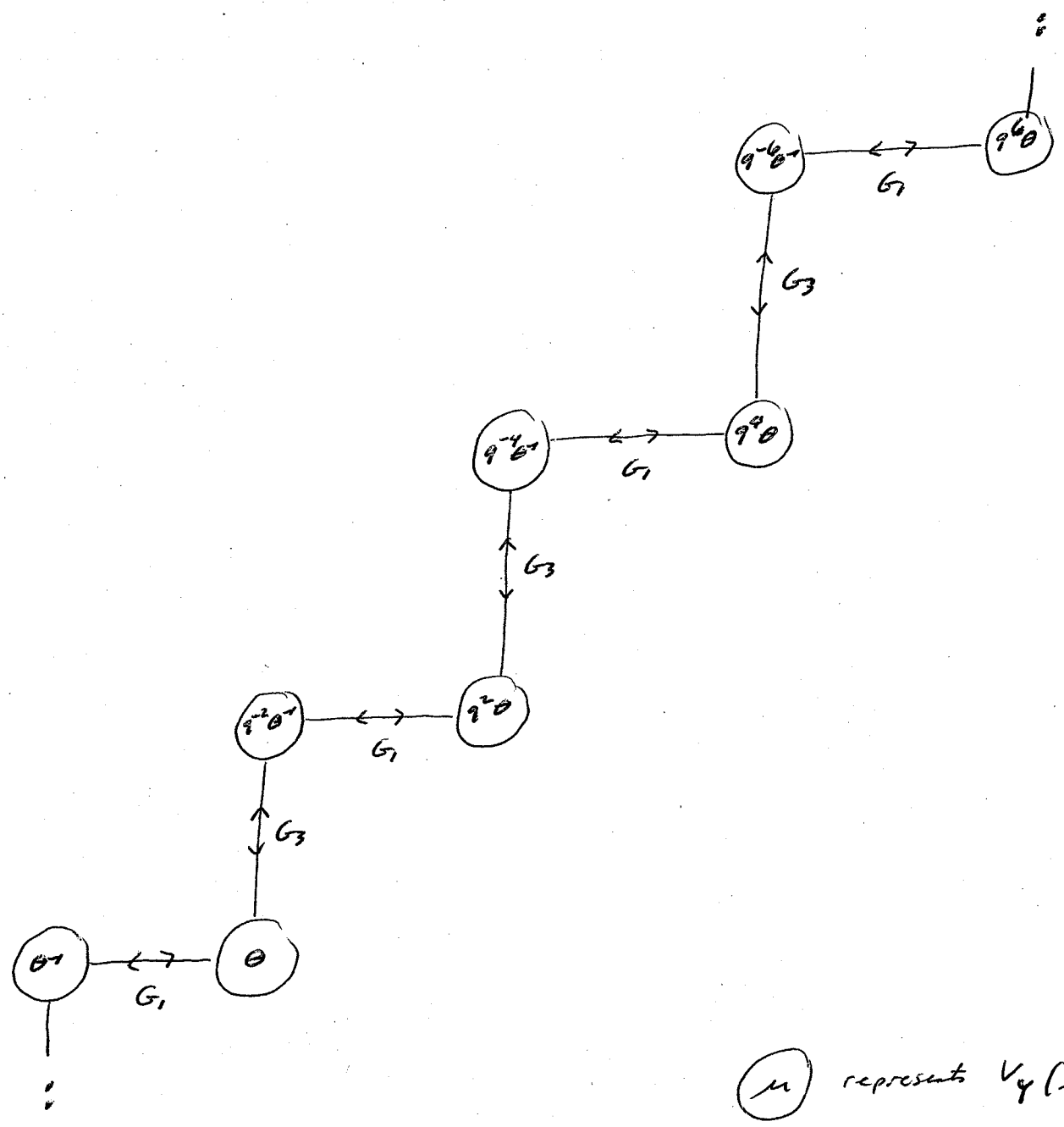
Prop 10 is about  $G_0$   
similar results hold for  $G_1, G_2, G_3$

Summary

Actions of  $G_0, G_2$  on the eigenspaces of  $X$



Actions of  $G_1, G_3$  on the  
eigenspaces of  $Y$



$\mathbb{F}$  alg closed

$$0 \neq q \in \mathbb{F} \quad q^4 \neq 1$$

Describe the  $H_q^n$  modules

LEM 11

$$(i) \quad G_0 = t_0(1 - X^{-2}) + T_3 X^{-1} - T_0$$

$$(ii) \quad G_0 = t_3(X^{-1} - X) + T_3 X - T_0$$

$$(iii) \quad G_2 = t_2(1 - q^2 X^2) + q T_1 X - T_2$$

$$(iv) \quad G_2 = t_1(qX - q^{-1}X^{-1}) + q^{-1} T_1 X^{-1} - T_2$$

pf (i)  $G_0 = t_0 - t_3 t_0 t_3^{-1}$

$$X = t_3 t_0$$

$$t_3 = X t_0^{-1}$$

$$t_3^{-1} = t_0 X^{-1}$$

$$G_0 = t_0 - \underline{X t_0 X^{-1}}$$

$$t_0 X^{-1} = \underline{X t_0} - X T_0 + T_3$$

$$G_0 = t_0 - (t_0 X^{-1} + X T_0 - T_3) X^{-1}$$

$$= t_0(1 - X^{-2}) + T_3 X^{-1} - T_0$$



(cc) Use

$$t_0 = t_3^{-1} X$$

$$= T_3 X - t_3 X$$

(ccc), (vi)

Apply  $Z_4$ -sym to (c), (cc)

$$G_0 \leftrightarrow G_2$$

$$t_0 \leftrightarrow t_2$$

$$t_1 \leftrightarrow t_3$$

$$X \leftrightarrow q^{-1} X^{-1}$$

□

LEM 12 Let  $V$  denote a  $\hat{H}_g$  module.

For  $0 \neq \theta \in \mathbb{F}$  and  $0 \neq v \in V_x(\theta)$

$$(i) \quad (\theta - \theta^{-1}) t_{0v} = (\theta T_0 - T_3)v + \theta G_0 v$$

$$(ii) \quad (\theta - \theta^{-1}) t_{3v} = (\theta T_3 - T_0)v - G_0 v$$

pf In L II (i), (ii) apply both sides to  $v$   
and use  $Xv = \theta v$  □

Ref to Lem 12

4

Cases

$$\theta = \theta^{-1} \quad (\text{i.e. } \theta = \pm 1)$$

$$\theta \neq \theta^{-1} \quad G_{0V} \neq 0$$

$$\theta \neq \theta^{-1} \quad G_{0V} = 0$$

LEM 13 With ref to L12 assume  $\theta = \pm 1$

$$(i) \quad G_{0V} = (\theta T_3 - T_0)V$$

(ii) Assume  $k_0, k_3$  exist. Then

$$G_{0V} = (\theta(k_3 r k_3^{-1}) - k_0 - k_0^{-1})V$$

$$\in \mathbb{F}V$$

pf By L12

□

LEM 14 With ref to L12 assume

$$\theta \neq \theta^{-1}$$

Then

$$(i) \quad t_{0V} = \frac{\theta T_0 - T_3}{\theta - \theta^{-1}} v + \frac{\theta}{\theta - \theta^{-1}} G_{0V}$$

$$(ii) \quad t_{0G_{0V}} = \frac{\theta^{-1} T_0 - T_3}{\theta^{-1} - \theta} G_{0V} + \frac{\theta^{-1}}{\theta^{-1} - \theta} G_{0V}^2$$

$$(iii) \quad t_{3V} = \frac{\theta T_3 - T_0}{\theta - \theta^{-1}} v + \frac{1}{\theta^{-1} - \theta} G_{0V}$$

$$(iv) \quad t_{3G_{0V}} = \frac{\theta^{-1} T_3 - T_0}{\theta^{-1} - \theta} G_{0V} + \frac{1}{\theta - \theta^{-1}} G_{0V}^2$$

pf (i) By L12 (i)

(ii) Apply (i) alone to  $v' = G_{0V}$ ,  $\theta' = \theta^{-1}$

(iii) By L12 (i)

(iv) Apply (iii) alone to  $v'' = G_{0V}$ ,  $\theta' = \theta^{-1}$

□

Prop 15. With ref to Lem 17 assume

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$\theta \neq \theta^{-1}$ ,  $G_{\theta} \neq 0$   
and that  $k_0, k_3$  exist.

Then  $v, G_{\theta}$  is a basis for a subspace of  
 $V$  that is inv under  $t_0^{\pm 1}, t_3^{\pm 1}$ .

With resp to the basis:

$$X: \begin{pmatrix} \theta & 0 \\ 0 & \theta^{-1} \end{pmatrix}$$

$$G_{\theta}: \begin{pmatrix} 0 & \theta^{-2} \left( \theta - \frac{k_0}{k_3} \right) \left( \theta - \frac{k_3}{k_0} \right) \left( \theta - k_0 k_3 \right) \left( \theta - \frac{1}{k_0 k_3} \right) \\ 1 & 0 \end{pmatrix}$$

$t_0$ :

$$\frac{\theta(k_0 + k_0^{\rightarrow}) - k_3 - k_3^{\rightarrow}}{\theta - \theta^{\rightarrow}}$$

$$\frac{(\theta - k_0 k_3^{\rightarrow}) (\theta - k_0^{\rightarrow} k_3) (\theta - k_0 k_3) (\theta - k_0^{\rightarrow} k_3^{\rightarrow})}{\theta^3 (\theta^{\rightarrow} - \theta)}$$

$$\frac{\theta}{\theta - \theta^{\rightarrow}}$$

$$\frac{\theta^{\rightarrow} (k_0 + k_0^{\rightarrow}) - k_3 - k_3^{\rightarrow}}{\theta^{\rightarrow} - \theta}$$

$t_0^{\rightarrow}$ :

$$\frac{\theta^{\rightarrow} (k_0 + k_0^{\rightarrow}) - k_3 - k_3^{\rightarrow}}{\theta^{\rightarrow} - \theta}$$

$$\frac{(\theta - k_0 k_3^{\rightarrow}) (\theta - k_0^{\rightarrow} k_3) (\theta - k_0 k_3) (\theta - k_0^{\rightarrow} k_3^{\rightarrow})}{\theta^3 (\theta - \theta^{\rightarrow})}$$

$$\frac{\theta}{\theta^{\rightarrow} - \theta}$$

$$\frac{\theta (k_0 + k_0^{\rightarrow}) - k_3 - k_3^{\rightarrow}}{\theta - \theta^{\rightarrow}}$$

$t_3$ :

$\frac{\theta(k_3+k_3^{-}) - k_0-k_0^{-}}{\theta - \theta^{-}}$	$\frac{(\theta-k_0k_3^{-})(\theta-k_0^{-}k_3)(\theta-k_0k_3)(\theta-k_0^{-}k_3^{-})}{\theta^2(\theta - \theta^{-})}$
$\frac{1}{\theta^{-} - \theta}$	$\frac{\theta^{-}(k_3+k_3^{-}) - k_0-k_0^{-}}{\theta^{-} - \theta}$

$t_3^{-}$ :

$\frac{\theta^{-}(k_3+k_3^{-}) - k_0-k_0^{-}}{\theta^{-} - \theta}$	$\frac{(\theta-k_0k_3^{-})(\theta-k_0^{-}k_3)(\theta-k_0k_3)(\theta-k_0^{-}k_3^{-})}{\theta^2(\theta^{-} - \theta)}$
$\frac{1}{\theta - \theta^{-}}$	$\frac{\theta(k_3+k_3^{-}) - k_0-k_0^{-}}{\theta - \theta^{-}}$

pf

$v, Gov$  lin indep since

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$$0 \neq v \in V_x(\theta),$$

$$0 \neq Gov \in V_x(\theta^{-1})$$

$$\theta \neq \theta^{-1}$$

Define  $W = \text{Span}\{v, Gov\}$

$t_0 W \subseteq W$  by Lem 12 (i), (ii) and since

$$Gov^2 v \in \text{Span}(v)$$

Similarly  $t_3 W \subseteq W$

Find matrices

$$x^{-1}$$

$$Gov^{-1}$$

$t_0$ : By L 14 (i), (ii) and Cor 9 (i)

$$t_0^{-1}: t_0^{-1} = T_0 - t_0$$

$t_3$ : By L 14 (iii), (iv) and Cor 9 (i)

$$t_3^{-1}: t_3^{-1} = T_3 - t_3$$

□



Note Ref to Prop 15

For  $i=0,3$  the matrix rep  $t_i$   
has trace  $k_i + k_i^{-1}$  and det 1.

Prop 16 With ref to L18 assume

$$\theta \neq \theta^{-1} \quad G_0 v = 0.$$

and that  $k_0, k_3$  exist.

Then

$$(i) \quad t_0 v = \frac{\theta(k_0 + k_0^{-1}) - k_3 - k_3^{-1}}{\theta - \theta^{-1}} v$$

$$(ii) \quad t_0^{-1} v = \frac{\theta^{-1}(k_0 + k_0^{-1}) - k_3 - k_3^{-1}}{\theta^{-1} - \theta} v$$

$$(iii) \quad t_3 v = \frac{\theta(k_3 + k_3^{-1}) - k_0 - k_0^{-1}}{\theta - \theta^{-1}} v$$

$$(iv) \quad t_3^{-1} v = \frac{\theta^{-1}(k_3 + k_3^{-1}) - k_0 - k_0^{-1}}{\theta^{-1} - \theta} v$$

$$(v) \quad \theta \in \left\{ \frac{k_0}{k_3}, \frac{k_3}{k_0}, k_0 k_3, \frac{1}{k_0 k_3} \right\}$$

pf (i) By L19 (i)

(ii) Use  $t_0^{-1} = T_0 - t_0$

(iii) By L19 (iii)

(iv) Use  $t_3^{-1} = T_3 - t_3$

(v) By Prop 10

$\mathbb{F}$  alg closed

$$0 \neq q \in \mathbb{F} \quad q^4 \neq 1$$

Continue to desc the  $\hat{H}_q$  modules

Lem 17 Let  $V$  denote a  $\hat{H}_q$  module.

$$\text{For } 0 \neq \theta \in \mathbb{F} \text{ and } 0 \neq v \in V_{\chi(\theta)}$$

$$(i) \quad (q^{-1}\theta^{-1} - q\theta) t_2 v = (q^{-1}\theta^{-1} T_2 - T_0) v + q^{-1}\theta^{-1} G_2 v$$

$$(ii) \quad (q^{-1}\theta^{-1} - q\theta) t_1 v = (q^{-1}\theta^{-1} T_1 - T_2) v - G_2 v$$

pf In L 11 (iii), (iv) apply each side to  $v$   
and use  $\chi v = \theta v$  □

Ref to Lem 17

2

Cases:

$$q\theta = q^{-1}\theta^{-1} \quad (\text{ie } \theta = \pm q^{-1})$$

$$q\theta \neq q^{-1}\theta^{-1} \quad G_2 v \neq 0$$

$$q\theta \neq q^{-1}\theta^{-1} \quad G_2 v = 0$$

LEM 18 With ref to L17 assume  $\theta = \neq q^{-1}$

then

$$(i) \quad G_2 v = (q^{-1}\theta^{-1}T_1 - T_2)v$$

(ii) Assume  $k_1, k_2$  exist. then

$$G_2 v = (q^{-1}\theta^{-1}(k_1 k_1^{-1} - k_2 k_2^{-1}))v$$

$$\in Fv$$

□

pf by L17

LEM 19 With ref to L17 assume

$$q_0 \neq q^{-1} \theta^{-1}$$

Then

$$(i) \quad t_{2V} = \frac{q^{-1} \theta^{-1} T_2 - T_1}{q^{-1} \theta^{-1} - q_0} V + \frac{q^{-1} \theta^{-1}}{q^{-1} \theta^{-1} - q_0} G_{2V}$$

$$(ii) \quad t_2 G_{2V} = \frac{q_0 T_2 - T_1}{q_0 - q^{-1} \theta^{-1}} G_{2V} + \frac{q_0}{q_0 - q^{-1} \theta^{-1}} G_{2V}^2$$

$$(iii) \quad t_{1V} = \frac{q^{-1} \theta^{-1} T_1 - T_2}{q^{-1} \theta^{-1} - q_0} V + \frac{1}{q_0 - q^{-1} \theta^{-1}} G_{2V}$$

$$(iv) \quad t_1 G_{2V} = \frac{q_0 T_1 - T_2}{q_0 - q^{-1} \theta^{-1}} G_{2V} + \frac{1}{q^{-1} \theta^{-1} - q_0} G_{2V}^2$$

pf Sim to pf of L14.

□

Prop 20 With ref to L17 assume

$$q\theta \neq q^{-1}\theta^{-1}, \quad G_{2V} \neq 0$$

and that  $k_1, k_2$  exist.

then  $v_1, G_{2V}$  is a basis for a subspace

of  $V$  that is invariant under  $t_1^{\pm 1}, t_2^{\pm 1}$ .

Rel the basis  $v_1, G_{2V}$ .

$$X: \begin{pmatrix} 0 & 0 \\ 0 & q^{-2}\theta^{-1} \end{pmatrix}$$

$$G_{2V}: \begin{pmatrix} 0 & q^2\theta^{-2} \left( \theta - \frac{k_1}{qk_2} \right) \left( \theta - \frac{k_2}{qk_1} \right) \left( \theta - \frac{k_1k_2}{q} \right) \left( \theta - \frac{1}{qk_1k_2} \right) & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$t_2:$ 

$$\frac{q^{-1}\theta^{-1}(k_2+k_2^{-1})-k_1-k_1^{-1}}{q^{-1}\theta^{-1}-q\theta} \quad \frac{q^3\left(\theta-\frac{k_1}{qk_2}\right)\left(\theta-\frac{k_2}{qk_1}\right)\left(\theta-\frac{k_1k_2}{q}\right)\left(\theta-\frac{1}{qk_1k_2}\right)}{\theta(q\theta-q^{-1}\theta^{-1})}$$

$$\frac{q^{-1}\theta^{-1}}{q^{-1}\theta^{-1}-q\theta} \quad \frac{q\theta(k_2+k_2^{-1})-k_1-k_1^{-1}}{q\theta-q^{-1}\theta^{-1}}$$

$$\frac{q\theta(k_2+k_2^{-1})-k_1-k_1^{-1}}{q\theta-q^{-1}\theta^{-1}} \quad \frac{q^3\left(\theta-\frac{k_1}{qk_2}\right)\left(\theta-\frac{k_2}{qk_1}\right)\left(\theta-\frac{k_1k_2}{q}\right)\left(\theta-\frac{1}{qk_1k_2}\right)}{\theta(q^{-1}\theta^{-1}-q\theta)}$$

 $t_2^{-1}:$ 

$$\frac{q^{-1}\theta^{-1}}{q\theta-q^{-1}\theta^{-1}} \quad \frac{q^{-1}\theta^{-1}(k_2+k_2^{-1})-k_1-k_1^{-1}}{q^{-1}\theta^{-1}-q\theta}$$

$t_1:$

$$\frac{q^{-1}\theta^{-1}(k_1+k_1^{-1})-k_2-k_2^{-1}}{q^{-1}\theta^{-1}-q\theta} \quad \frac{q^2\left(\theta-\frac{k_1}{qk_2}\right)\left(\theta-\frac{k_2}{qk_1}\right)\left(\theta-\frac{k_1k_2}{q}\right)\left(\theta-\frac{1}{qk_1k_2}\right)}{\theta^2(q^{-1}\theta^{-1}-q\theta)}$$


---


$$\frac{1}{q\theta-q^{-1}\theta^{-1}} \quad \frac{q\theta(k_1+k_1^{-1})-k_2-k_2^{-1}}{q\theta-q^{-1}\theta^{-1}}$$

$t_1^{-1}:$

$$\frac{q\theta(k_1+k_1^{-1})-k_2-k_2^{-1}}{q\theta-q^{-1}\theta^{-1}} \quad \frac{q^2\left(\theta-\frac{k_1}{qk_2}\right)\left(\theta-\frac{k_2}{qk_1}\right)\left(\theta-\frac{k_1k_2}{q}\right)\left(\theta-\frac{1}{qk_1k_2}\right)}{\theta^2(q\theta-q^{-1}\theta^{-1})}$$


---


$$\frac{1}{q^{-1}\theta^{-1}-q\theta} \quad \frac{q^{-1}\theta^{-1}(k_1+k_1^{-1})-k_2-k_2^{-1}}{q^{-1}\theta^{-1}-q\theta}$$

pf sim to pf of P15

□



Prop 21 With ref to L17 assume

$q\theta \neq q^{-1}\theta^{-1}$ ,  $G_2 v = 0$   
and that  $k_1, k_2$  exist.  
Then

(i)  $t_{2v} = \frac{q^{-1}\theta^{-1}(k_2 + k_2^{-1}) - k_1 - k_1^{-1}}{q^{-1}\theta^{-1} - q\theta} v$

(ii)  $t_{2^{-1}v} = \frac{q\theta(k_2 + k_2^{-1}) - k_1 - k_1^{-1}}{q\theta - q^{-1}\theta^{-1}} v$

(iii)  $t_{1v} = \frac{q^{-1}\theta^{-1}(k_1 + k_1^{-1}) - k_2 - k_2^{-1}}{q^{-1}\theta^{-1} - q\theta} v$

(iv)  $t_{1^{-1}v} = \frac{q\theta(k_1 + k_1^{-1}) - k_2 - k_2^{-1}}{q\theta - q^{-1}\theta^{-1}} v$

(v)  $\theta \in \left\{ \frac{k_1}{qk_2}, \frac{k_2}{qk_1}, \frac{k_1 k_2}{q}, \frac{1}{qk_1 k_2} \right\}$

pf Sim to pf of Prop 16

LEM 22

Let  $V$  denote an irred.  $\hat{H}_q$ -module

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Assume  $\neq 1, \neq q^{-1}$  are not eigenvalues of  $X$   
on  $V$  and that  $k_i$  exists for  $i \in I$ .

Assume  $X$  has at least one eigenvector  $v$  on  $V$   
[automatic if  $\dim V < \infty$ ]

Then

(i)  $V$  is spanned by

...  $G_0 G_1 v, G_2 v, v, G_0 v, G_2 G_0 v, G_0 G_2 G_0 v, \dots$   
[Some might be 0]

\*

(ii) Vectors  $*$  are eigenvectors of  $X$  on  $V$

(iii)  $X$  is diagonalizable on  $V$

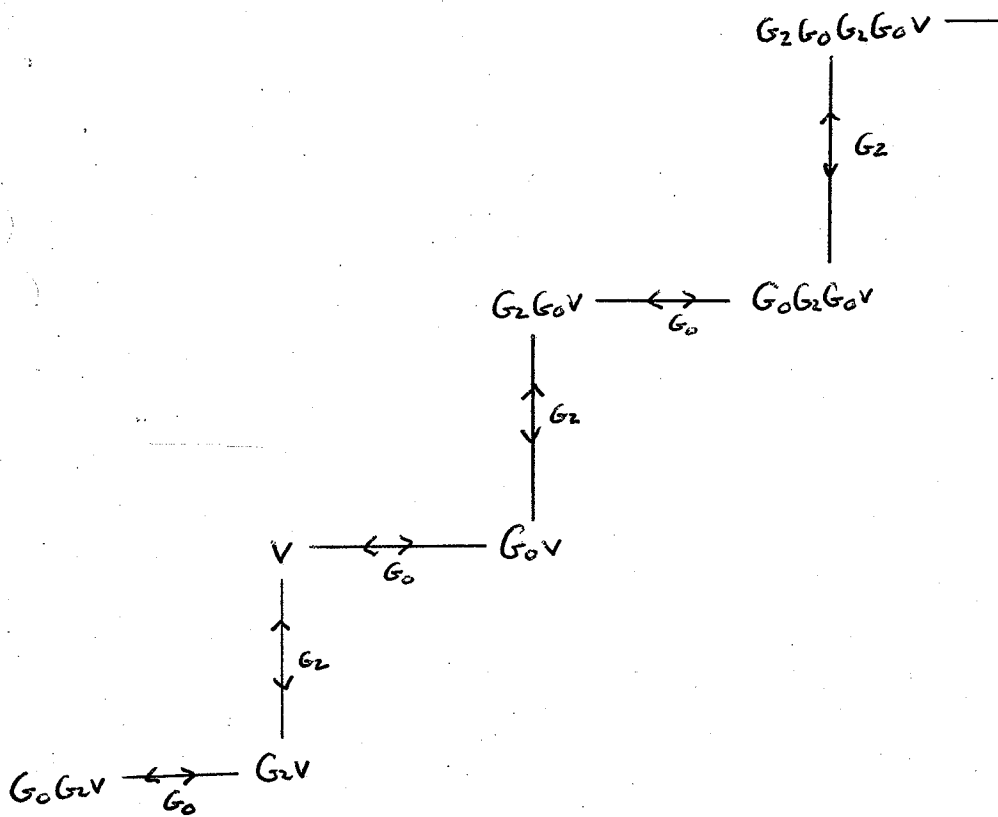
pf (i) Span of  $*$  is invar under  $\{G_i^{\pm 1}\}_{i \in I}$

(ii) By Lem 5

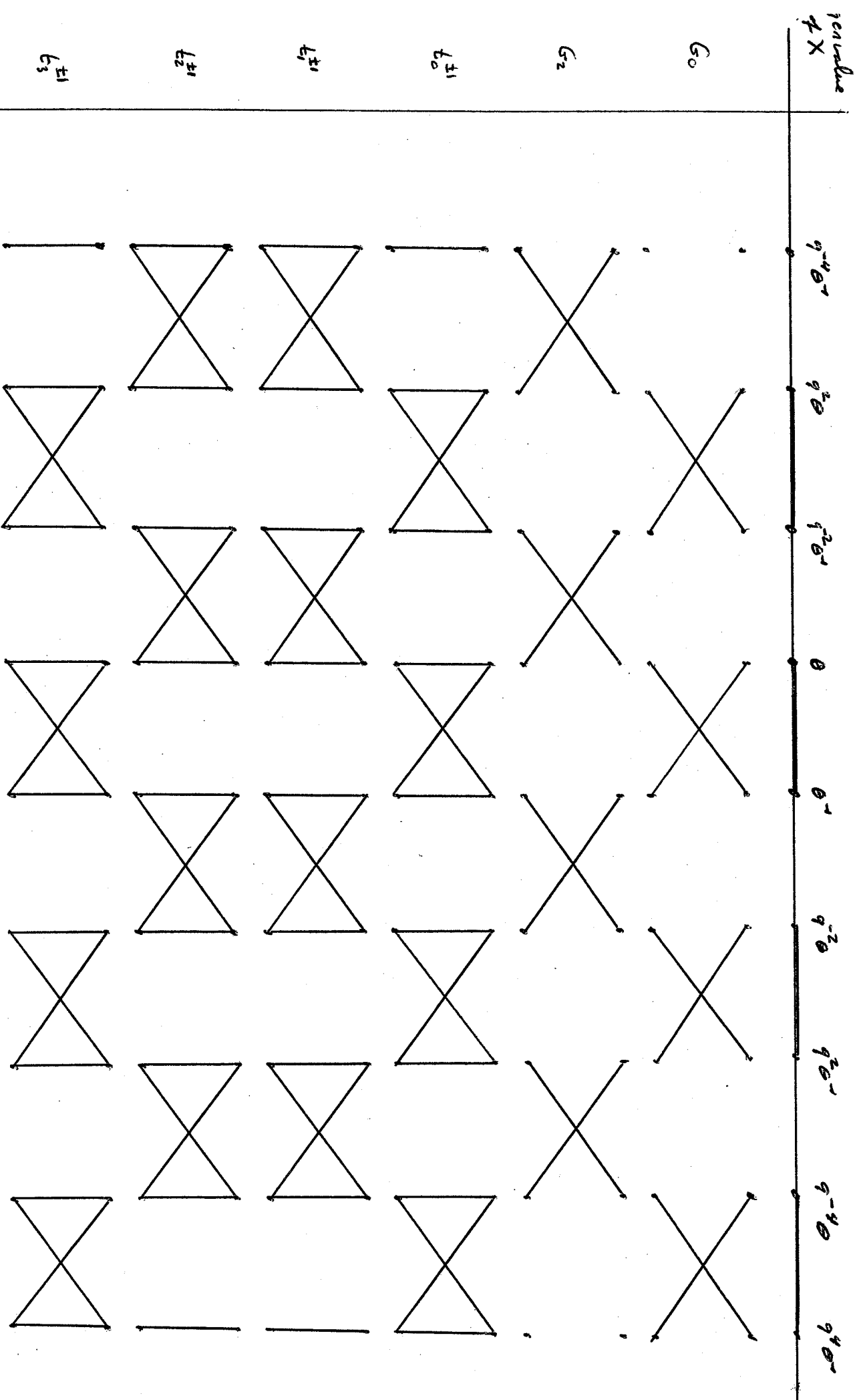
(iii) By (i), (ii)

□

With ref to L22



Actions of  $G_0, G_2, \{L_i^{\pm 1}\}_{i \in \mathbb{Z}}$  on the eigenspaces of  $X$



to see

Cor 23 Let  $V$  denote an  $\hat{H}_q$  module

Given  $0 \neq \theta \in \mathbb{F}$

(i) Assume  $\theta \neq \pm 1$  and  $k_1, k_2$  exist for  $V$ . Then both

$$t_0^{\pm} V_X(\theta) \subseteq V_X(\theta) + V_X(\theta^{-1})$$

$$t_3^{\pm} V_X(\theta) \subseteq V_X(\theta) + V_X(\theta^{-1})$$

(ii) Assume  $\theta \neq \mp q^{\pm}$  and  $k_1, k_2$  exist for  $V$ . Then both

$$t_1^{\pm 1} V_X(\theta) \subseteq V_X(\theta) + V_X(q^{-2}\theta^{-1})$$

$$t_2^{\pm 1} V_X(\theta) \subseteq V_X(\theta) + V_X(q^{-2}\theta^{-1})$$

pf (i) By P15.16 and since  $\theta \neq \theta^{-1}$ ,  $\forall v \in V_X(\theta)$

$$\begin{aligned} t_0^{\pm} v &\in \text{Span}(v, Gv) \\ &\subseteq V_X(\theta) + V_X(\theta^{-1}) \end{aligned}$$

and

$$\begin{aligned} t_3^{\pm 1} v &\in \text{Span}(v, Gv) \\ &\subseteq V_X(\theta) + V_X(\theta^{-1}) \end{aligned}$$

(ii) Similar.

Recall  $A = Y + Y^{-1}$   $Y = \epsilon \sigma_1$

For an  $\hat{H}_q$ -module  $V$  find the action  
of  $A$  on the eigenspaces of  $X$

LEM 24 Let  $V$  denote an  $\hat{H}_q$ -module.  
Assume  $\lambda_i$  exists for  $V$  ( $\forall i \in \mathbb{I}$ ).

Given  $0 \neq \theta \in \mathbb{F}$ .

(i) Assume  $\theta \notin \{\pm 1, \pm q^{-1}, \pm q^{-2}\}$ . Then

$$Y V_X(\theta) \subseteq V_X(q^2\theta) + V_X(q^{-2}\theta^{-1}) + V_X(\theta) + V_X(\theta^{-1})$$

(ii) Assume  $\theta \notin \{\pm q, \pm 1, \pm q^{-1}\}$ . Then

$$Y^{-1} V_X(\theta) \subseteq V_X(q^{-2}\theta^{-1}) + V_X(\theta) + V_X(\theta^{-1}) + V_X(q^{-2}\theta)$$

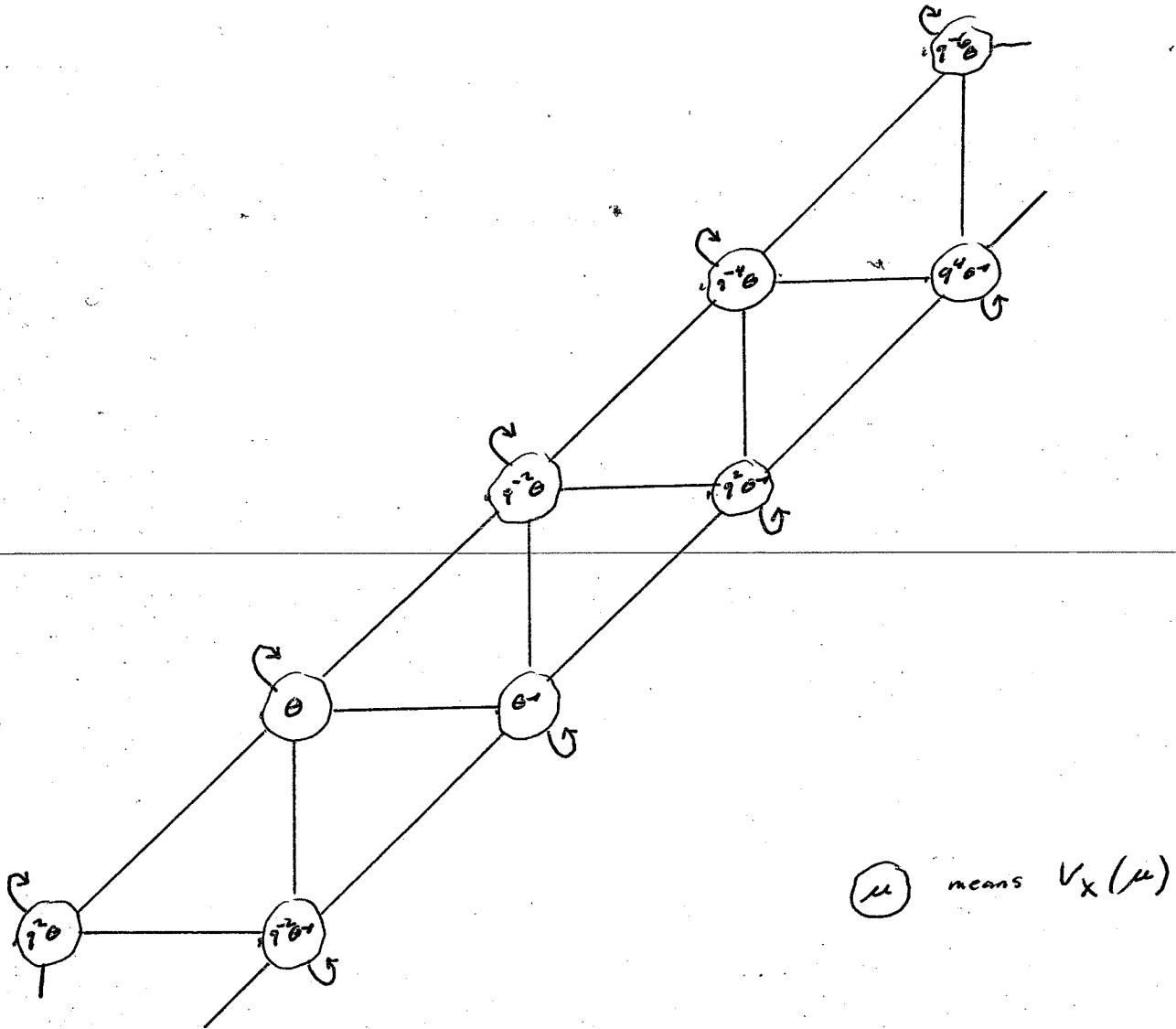
(iii) Assume  $\theta \notin \{\pm q, \pm 1, \pm q^{-1}, \pm q^{-2}\}$ . Then

$$A Y_X(\theta) \subseteq V_X(q^2\theta) + V_X(q^{-2}\theta^{-1}) + V_X(\theta) + V_X(\theta^{-1}) + V_X(q^{-2}\theta)$$

pf By Cor 23.

□

The action of  $A$  on the eigenspaces of  $X$

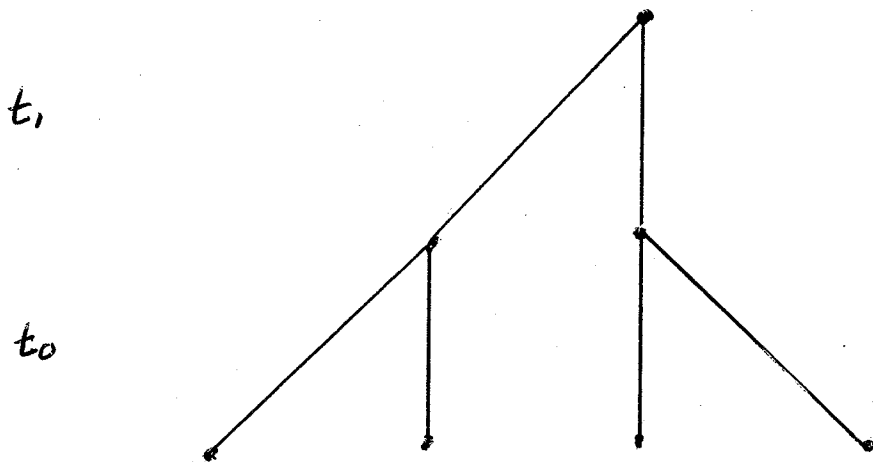


$A$  sends each eigenspace into the sum of adjacent eigenspaces

Recall  $A = Y + Y^\top$

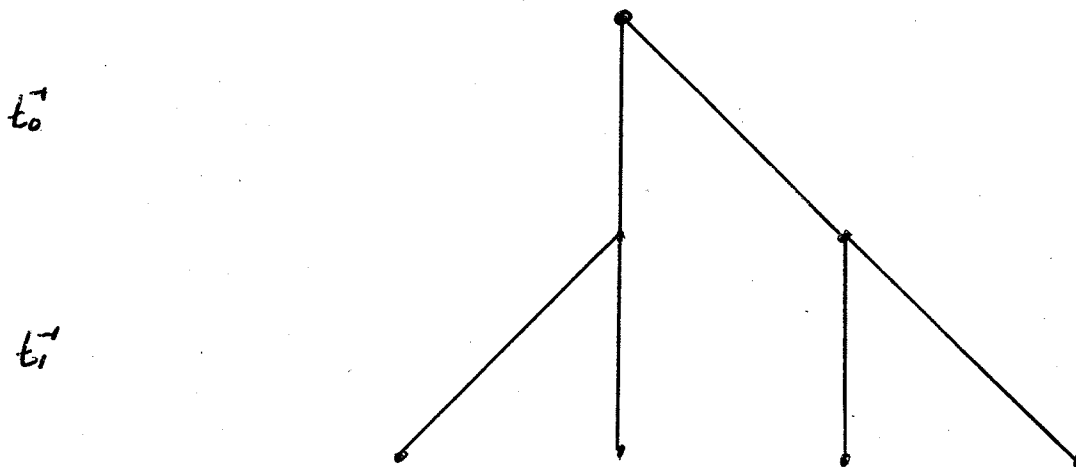
$Y = t_0 t_1$

Find action of  $A$  on the eigenspaces of  $X$



$Y \downarrow$

$$Y V_X(\theta) \subseteq V_X(q^2 \theta) + V_X(q^2 \theta^{-1}) + V_X(\theta) + V_X(\theta^{-1})$$



$Y^\top \downarrow$

$$Y^\top V_X(\theta) \subseteq V_X(q^{-2} \theta^{-1}) + V_X(\theta) + V_X(\theta^{-1}) + V_X(q^{-2} \theta)$$

$$A V_X(\theta) \subseteq V_X(q^2 \theta) + V_X(q^2 \theta^{-1}) + V_X(\theta) + V_X(\theta^{-1}) + V_X(q^{-2} \theta)$$



Next goal

Consider

$$A = Y + Y^{-1}$$

$$B = X + X^{-1}$$

Let  $V$  denote an  $\hat{H}_g$ -module

Find the action of  $A$  on the eigenspace of  $B$

LEM 25 Let  $V$  denote an  $\hat{H}_g$ -module

Given  $0 \neq \theta \in \mathbb{F}$

$$V_B(\theta + \theta^{-1}) = V_X(\theta) + V_X(\theta^{-1})$$

provided  $\theta \neq \pm 1$

pf  $\supseteq$ : clear

$\subseteq$ : Given  $v \in V_B(\theta + \theta^{-1})$  show  $v \in V_X(\theta) + V_X(\theta^{-1})$

$$Bv = (\theta + \theta^{-1})v$$

$$(X + X^{-1})v = (\theta + \theta^{-1})v$$

$$(X - \theta)(X - \theta^{-1})v = 0$$

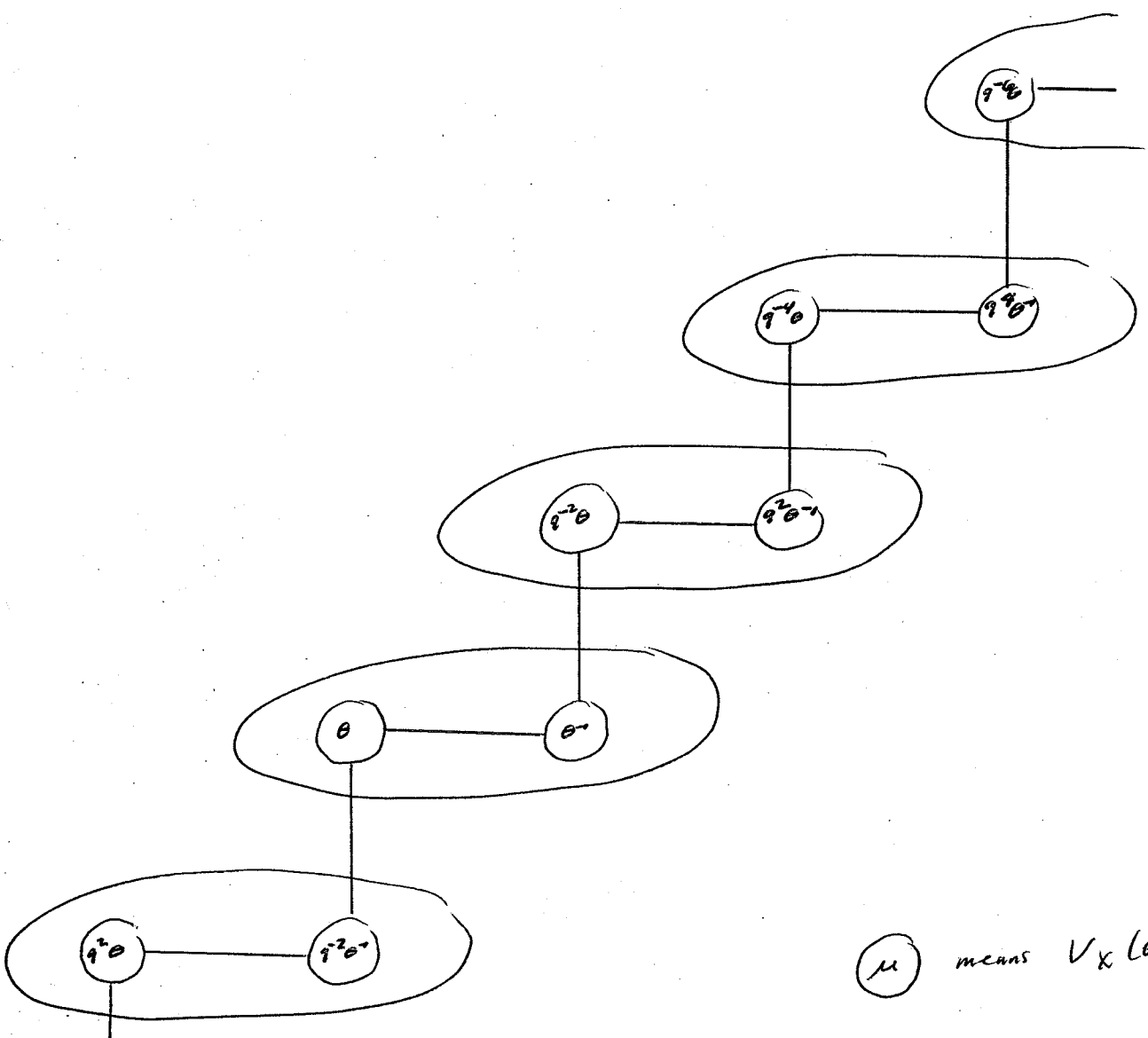
$$\frac{X - \theta^{-1}}{\theta - \theta^{-1}} v \in V_X(\theta)$$

$$\frac{X - \theta}{\theta^{-1} - \theta} v \in V_X(\theta^{-1})$$

$$v = \frac{X - \theta^{-1}}{\theta - \theta^{-1}} v + \frac{X - \theta}{\theta^{-1} - \theta} v$$

$$\in V_X(\theta) + V_X(\theta^{-1})$$

the eigenspaces of  $B = X + X^{-1}$



$\mu$  means  $V_X(\theta)$

Each  $\bigcirc \bigcirc$  is an

eigenspace of  $B$

Thm 26 let  $V$  denote an  $\hat{H}_q$  module

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Assume  $k_i$  exist for  $V$   $\forall i \in \mathbb{I}$ .

Given  $0 \neq \theta \in \mathbb{F}$ . Then

$$A V_B(\theta + \theta^{-1}) \subseteq$$

$$V_B(q^2\theta + q^{-2}\theta^{-1}) + V_B(\theta + \theta^{-1}) + V_B(q^{-2}\theta + q^2\theta^{-1})$$

provided.

$$\theta \notin \{ \pm q^{-2}, \pm q^{-1}, \pm 1, \pm q, \pm q^2 \}$$

pf Combine L 24, L 25.

□

[  $B$  acts in a sim fashion on the eigenspaces of  $A$  ]

$\mathbb{F}$  alg closed

$$0 \neq q \in \mathbb{F} \quad q^4 \neq 1$$

Continue to describe the  $\hat{H}_q$ -modules

Let  $V$  denote a  $\hat{H}_q$ -module

Cases of interest:

$X$  is diagonalizable on  $V$

or

$Y$  is diagonalizable on  $V$

(or both)

WLOG focus on \*

Under assumption \* we can improve some of our earlier results as follows

LEM 27 Let  $V$  denote an  $\hat{H}_q$ -module  
 on which  $X$  is diagonalizable. then  $\forall \theta \neq 0 \in \mathbb{F}$

$$V_B(\theta + \theta^{-1}) = V_X(\theta) + V_X(\theta^{-1})$$

[even if  $\theta = \pm 1$ ]

pf Assume  $\theta \neq \pm 1$  else done by L25

so  $\theta = \theta^{-1}$

$\supseteq$

$\subseteq$ : Given  $v \in V_B(\theta + \theta^{-1})$  show  $v \in V_X(\theta)$

$$(X + X^{-1})v = (\theta + \theta^{-1})v$$

$$(X - \theta)(X - \theta^{-1})v = 0$$

$$(X - \theta)^2 v = 0$$

$$(X - \theta)v = 0$$

since  $X$  diagonalizable

$$v \in V_X(\theta)$$

LEM 28 Let  $V$  denote an  $\hat{H}_q$ -module on which  $X$  is diagonalizable. Then for  $0 \neq \theta \in \mathbb{F}$

$$(i) \quad t_0^{\pm 1} V_X(\theta) \subseteq V_X(\theta) + V_X(\theta^{-1})$$

$$(ii) \quad t_3^{\pm 1} V_X(\theta) \subseteq V_X(\theta) + V_X(\theta^{-1})$$

$$(iii) \quad t_1^{\pm 1} V_X(\theta) \subseteq V_X(\theta) + V_X(q^{-2}\theta^{-1})$$

$$(iv) \quad t_2^{\pm 1} V_X(\theta) \subseteq V_X(\theta) + V_X(q^{-2}\theta^{-1})$$

pf (i)  $t_0$  commutes with  $B = X + X^{-1}$ .

$$\text{So} \quad t_0^{\pm 1} V_B(\theta + \theta^{-1}) \subseteq V_B(\theta + \theta^{-1})$$

$$\begin{aligned} \text{So} \quad t_0^{\pm 1} V_X(\theta) &\subseteq t_0^{\pm 1} V_B(\theta + \theta^{-1}) \\ &\subseteq V_B(\theta + \theta^{-1}) \\ &= V_X(\theta) + V_X(\theta^{-1}) \end{aligned}$$

(ii) By (i) and  $X = t_3 t_0$

(iii), (iv) Sim

□  
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LEM 29 Let  $V$  denote an  $\hat{H}_q$  module on which  $X$  is diagonalizable. Then for  $0 \neq \theta \in \mathbb{F}$

$$Y V_X(\theta) \subseteq V_X(q^2 \theta) + V_X(q^{-2} \theta) + V_X(\theta) + V_X(\theta^{-1})$$

$$Y^{-1} V_X(\theta) \subseteq V_X(q^{-2} \theta^{-1}) + V_X(\theta) + V_X(\theta^{-1}) + V_X(q^{-2} \theta)$$

$$A V_X(\theta) \subseteq V_X(q^2 \theta) + V_X(q^{-2} \theta^{-1}) + V_X(\theta) + V_X(\theta^{-1}) + V_X(q^{-2} \theta)$$

pf by L 28 and

$$Y = \text{tot.}$$

$$A = Y + Y^{-1}$$

□

Thm 30 Let  $V$  denote an  $\hat{H}_q$ -module on which

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$X$  is diagonalizable. Then for  $0 \neq \theta \in \mathbb{F}$

$$A V_{\theta}(\theta + \theta^{-1}) \subseteq$$

$$V_{\theta}(q^2\theta + q^{-2}\theta^{-1}) + V_{\theta}(\theta + \theta^{-1}) + V_{\theta}(q^{-2}\theta + q^2\theta^{-1})$$

pf Combine L27, 29.

□



Cautim Ref to th30 assume  $V$  is irred.

In gen  $V$  is not irred as a module for  $A, B$ .

Indeed suppose  $k_0$  exists and  $k_0 \neq \pm 1$

We saw earlier

$$V = V_{t_0}(k_0) + V_{t_0}(k_0^{-1}) \quad ds$$

with each  $t$

$$V_{t_0}(k_0), \quad V_{t_0}(k_0^{-1})$$

invar under  $A, B$ .

Next goal: describe the actions of  $A, B$  on  $V_{t_0}(k_0^{\pm 1})$

obs: eld $\hat{H}_s$	action on $V_{t_0}(k_0)$	action on $V_{t_0}(k_0^{-1})$
$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}}$	1	0
$\frac{t_0 - k_0}{k_0^{-1} - k_0}$	0	1

So

$$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}}, \quad \frac{t_0 - k_0}{k_0^{-1} - k_0}$$

are the primitive idempotents for the action of  $t_0$  on  $V$

Note that

$$1 = \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} + \frac{t_0 - k_0}{k_0^{-1} - k_0}$$

$$t_0 = k_0 \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} + k_0^{-1} \frac{t_0 - k_0}{k_0^{-1} - k_0}$$

$$t_0^{-1} = k_0^{-1} \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} + k_0 \frac{t_0 - k_0}{k_0^{-1} - k_0}$$

Let  $W$  denote an eigenspace for the action of

$A$  on  $V$ . Then

$$W = \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} W + \frac{t_0 - k_0}{k_0^{-1} - k_0} W \quad (ds)$$

Let  $U$  denote an eigenspace for the action of

$B$  on  $V$ . Then

$$U = \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} U + \frac{t_0 - k_0}{k_0^{-1} - k_0} U \quad (ds)$$

Thm 31 let  $V$  denote an  $H_q$ -module  
on which  $X$  is diagonalizable.

Assume  $k_0$  exists for  $V$  and  $k_0 \neq \pm 1$ .

Then for  $0 \neq \theta \in F$  both

$$\begin{aligned}
 A \quad \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} V_B(\theta + \theta^{-1}) &= \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} V_B(q^2\theta + q^{-2}\theta^{-1}) \\
 &+ \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} V_B(\theta + \theta^{-1}) \\
 &+ \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} V_B(q^{-2}\theta + q^2\theta^{-1})
 \end{aligned}$$

$$\begin{aligned}
 A \quad \frac{t_0 - k_0}{k_0^{-1} - k_0} V_B(\theta + \theta^{-1}) &= \frac{t_0 - k_0}{k_0^{-1} - k_0} V_B(q^2\theta + q^{-2}\theta^{-1}) \\
 &+ \frac{t_0 - k_0}{k_0^{-1} - k_0} V_B(\theta + \theta^{-1}) \\
 &+ \frac{t_0 - k_0}{k_0^{-1} - k_0} V_B(q^{-2}\theta + q^2\theta^{-1})
 \end{aligned}$$

Pf By Thm 30 and comments  
below it.

□

Next goal: describe forms in above Thm.

Until further notice:

$V$  denotes an  $\mathbb{H}_q$ -module on which  $X$  is diagonalizable

Assume  $k_0, k_1$  exist for  $V$  and  $k_0 \neq \pm 1$ .

Given  $0 \neq \theta \in \mathbb{F}$  and

$$0 \neq v \in V_X(\theta)$$

Assume  $\theta \neq \theta^{-1}$  and  $G_{\theta v} \neq 0$

By Prop 15

$$v, G_{\theta v}$$

is a basis for a subspace of  $V$  that is inv under  $t_0^{\pm 1}, t_1^{\pm 1}$

For  $t_0$  the eigenvalues on this space are  $k_0, k_0^{-1}$ .

Corresp eig vectors are

$$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} v,$$

$$\frac{t_0 - k_0}{k_0^{-1} - k_0} v$$

The vectors  $**$  form a basis for  $\text{Span}(v, G_{\theta v})$ .

Compare the bases  $*$ ,  $**$ .

LEM 32 With above notation

$$\frac{t_0 - k_0^{\rightarrow}}{k_0 - k_0^{\rightarrow}} v = \frac{\theta k_0 + \theta^{\rightarrow} k_0^{\rightarrow} - k_3 - k_3^{\rightarrow}}{(\theta - \theta^{\rightarrow})(k_0 - k_0^{\rightarrow})} v + \frac{\theta}{(\theta - \theta^{\rightarrow})(k_0 - k_0^{\rightarrow})} G_0 v$$

$$\frac{t_0 - k_0}{k_0^{\rightarrow} - k_0} v = \frac{\theta k_0^{\rightarrow} + \theta^{\rightarrow} k_0 - k_3 - k_3^{\rightarrow}}{(\theta - \theta^{\rightarrow})(k_0^{\rightarrow} - k_0)} v + \frac{\theta}{(\theta - \theta^{\rightarrow})(k_0^{\rightarrow} - k_0)} G_0 v$$

and

$$v = \frac{t_0 - k_0^{\rightarrow}}{k_0 - k_0^{\rightarrow}} v + \frac{t_0 - k_0}{k_0^{\rightarrow} - k_0} v$$

$$G_0 v = \frac{k_3 + k_3^{\rightarrow} - \theta k_0^{\rightarrow} - \theta^{\rightarrow} k_0}{\theta} \frac{t_0 - k_0^{\rightarrow}}{k_0 - k_0^{\rightarrow}} v$$

$$+ \frac{k_3 + k_3^{\rightarrow} - \theta k_0 - \theta^{\rightarrow} k_0^{\rightarrow}}{\theta} \frac{t_0 - k_0}{k_0^{\rightarrow} - k_0} v$$

pf Prop 15 and finally

□

$$(i) \frac{t_0 - k_0^*}{k_0 - k_0^*} G_{0V} = \frac{k_3 + k_3^* - \theta k_0^* - \theta^* k_0}{\theta} \frac{t_0 - k_0^*}{k_0 - k_0^*} \checkmark$$

$$(ii) \frac{t_0 - k_0}{k_0^* - k_0} G_{0V} = \frac{k_3 + k_3^* - \theta k_0 - \theta^* k_0^*}{\theta} \frac{t_0 - k_0}{k_0^* - k_0} \checkmark$$

pf Use Prop 15 and similarly □

LEM 34

with above notation

rel basis

$$\frac{t_0 - k_0^\rightarrow}{k_0 - k_0^\rightarrow} v_1$$

$$\frac{t_0 - k_0}{k_0^\rightarrow - k_0} v$$

the matrices rep  $t_0, X^{\pm 1}, t_3^{\pm 1}$   
are

$$t_0: \begin{pmatrix} k_0 & 0 \\ 0 & k_0^\rightarrow \end{pmatrix}$$

X:

$$\frac{(\theta + \theta^\rightarrow) k_0 - k_3 - k_3^\rightarrow}{k_0 - k_0^\rightarrow}$$

$$\frac{\theta k_0^\rightarrow + \theta^\rightarrow k_0 - k_3 - k_3^\rightarrow}{k_0^\rightarrow - k_0}$$

$$\frac{\theta k_0 + \theta^\rightarrow k_0^\rightarrow - k_3 - k_3^\rightarrow}{k_0 - k_0^\rightarrow}$$

$$\frac{(\theta + \theta^\rightarrow) k_0^\rightarrow - k_3 - k_3^\rightarrow}{k_0^\rightarrow - k_0}$$

X<sup>-1</sup>:

$$\frac{(\theta + \theta^{-1})k_0^{-1} - k_3 - k_3^{-1}}{k_0^{-1} - k_0}$$

$$\frac{\theta k_0^{-1} + \theta^{-1}k_0 - k_3 - k_3^{-1}}{k_0 - k_0^{-1}}$$

$$\frac{\theta k_0 + \theta^{-1}k_0^{-1} - k_3 - k_3^{-1}}{k_0^{-1} - k_0}$$

$$\frac{(\theta + \theta^{-1})k_0 - k_3 - k_3^{-1}}{k_0 - k_0^{-1}}$$



$t_3:$

$$\left( \begin{array}{cc} \frac{\theta + \theta^{-1} - (k_3 + k_3^{-1}) k_0^{-1}}{k_0 - k_0^{-1}} & \frac{(\theta k_0^{-1} + \theta^{-1} k_0 - k_3 - k_3^{-1}) k_0}{k_0^{-1} - k_0} \\ \frac{(\theta k_0 + \theta^{-1} k_0^{-1} - k_3 - k_3^{-1}) k_0^{-1}}{k_0 - k_0^{-1}} & \frac{\theta + \theta^{-1} - (k_3 + k_3^{-1}) k_0}{k_0^{-1} - k_0} \end{array} \right)$$

$t_3^{-1}:$

$$\left( \begin{array}{cc} \frac{\theta + \theta^{-1} - (k_3 + k_3^{-1}) k_0}{k_0^{-1} - k_0} & \frac{(\theta k_0^{-1} + \theta^{-1} k_0 - k_3 - k_3^{-1}) k_0}{k_0 - k_0^{-1}} \\ \frac{(\theta k_0 + \theta^{-1} k_0^{-1} - k_3 - k_3^{-1}) k_0^{-1}}{k_0^{-1} - k_0} & \frac{\theta + \theta^{-1} - (k_3 + k_3^{-1}) k_0^{-1}}{k_0 - k_0^{-1}} \end{array} \right)$$

pf use Prop 15 and similarly.

$$T = \begin{pmatrix} 1 & \frac{k_3 + k_3^* - \theta k_0^* - \theta^* k_0}{\theta} \\ 0 & \frac{k_2 k_2^* - \theta k_0 - \theta^* k_0^*}{\theta} \end{pmatrix}$$

$$X^{\text{new}} = T \begin{pmatrix} \theta & 0 \\ 0 & \theta^* \end{pmatrix} T^{-1}$$

$$X^{\text{new}} \quad \kappa = \theta + \theta^*, \quad \det = 1$$

$\mathbb{F}$  alg closed

$$0 \neq \eta \in \mathbb{F} \quad \eta \neq 1$$

Continue to describe the  $\hat{H}_\eta$ -module

Until further notice:

- $V$  denotes an  $\hat{H}_\eta$ -module on which  $X$  is diagonalizable
- Assume  $k_i$  exists for  $\forall i \in \mathbb{I}$
- $k_0 \neq \pm 1$

Given  $0 \neq \theta \in \mathbb{F}$

$$0 \neq v \in V_{X(\theta)}$$

Find action of  $A = YXY^{-1}$  on

$$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} v_1$$

$$\frac{t_0 - k_0}{k_0^{-1} - k_0} v$$

Since  $k_0$  only defined up to reciprocal, we are free to replace  $k_0$  by  $k_0^{-1}$ . So wlog focus on

$$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} v$$

with above notation

A

$$k_0 - k_0^*$$

2

term

coef

$$\frac{t_0 - k_0^*}{k_0 - k_0^*} \quad G_2 V$$

$$\frac{\theta k_0 + \theta^* k_0^* - k_3 - k_3^*}{(\theta - \theta^*)(q\theta - q^*\theta^*)}$$

$$\frac{t_0 - k_0^*}{k_0 - k_0^*} \quad V$$

$$\frac{\theta k_0 + \theta^* k_0^* - k_3 - k_3^*}{\theta - \theta^*} \frac{q^*\theta^* (k_1 + k_1^* - k_2 - k_2^*)}{q^*\theta^* - q\theta} + \frac{q^*\theta (k_1 + k_1^* - k_2 - k_2^*)}{\theta - \theta^*} \frac{k_3 + k_3^* - \theta k_0^* - \theta^* k_0}{q^*\theta - q\theta^*} + \frac{k_3 + k_3^*}{k_0}$$

$$\frac{t_0 - k_0^*}{k_0 - k_0^*} \quad G_2 G_0 V$$

$$\frac{\theta}{(\theta - \theta^*)(q\theta^* - q^*\theta)}$$

provided

$$\theta \neq \theta^*, \quad q\theta \neq q^*\theta^*, \quad q\theta \neq q\theta^*$$

pf

$$A \frac{t_0 - k_0^*}{k_0 - k_0^*} v = \left( \begin{array}{c} t_0 t_1 + t_1^* t_0^* \\ \parallel \\ T_1 T_1 \end{array} \right) \frac{t_0 - k_0^*}{k_0 - k_0^*} v$$

↑  
equivalent for  
 $t_0$  with equal  
 $k_0$

$$= \left( t_0 t_1 + (k_1 k_1^* - t_1) k_0^* \right) \frac{t_0 - k_0^*}{k_0 - k_0^*} v$$

$$= (t_0 - k_0^*) t_1 \frac{t_0 - k_0^*}{k_0 - k_0^*} v$$

$$+ \frac{k_1 + k_0^*}{k_0} \frac{t_0 - k_0^*}{k_0 - k_0^*} v$$

$$= (k_0 - k_0^*) \frac{t_0 - k_0^*}{k_0 - k_0^*} t_1 \frac{t_0 - k_0^*}{k_0 - k_0^*} v$$

$$+ \frac{k_1 + k_0^*}{k_0} \frac{t_0 - k_0^*}{k_0 - k_0^*} v$$

} \*

Find

$$\frac{t_0 - k_0^*}{k_0 - k_0^*} t_1 \frac{t_0 - k_0^*}{k_0 - k_0^*} v$$

$$t_1 \frac{k_0 - k_0^*}{k_0 - k_0^*} v =$$

$$t_1 \left( \frac{\theta k_0 + \theta^* k_0^* - k_3 - k_3^*}{(\theta - \theta^*)(k_0 - k_0^*)} v + \frac{\theta}{(\theta - \theta^*)(k_0 - k_0^*)} Gov \right)$$

(by L14)

$$t_1 v = \frac{q^* \theta^* (k_1, k_1^*) - k_2 k_2^*}{q^* \theta^* - q \theta} v + \frac{1}{q \theta - q^* \theta^*} G_2 v \quad (\text{by L19})$$

$$t_1 Gov = \frac{q^* \theta (k_1, k_1^*) - k_2 k_2^*}{q^* \theta - q \theta^*} Gov + \frac{1}{q \theta^* - q^* \theta} G_2 Gov$$

(by L19, with  $v$  replaced  
by  $Gov$  and  $\theta$  replaced  
by  $\theta^*$ )

Now eval

$v, G_2 v, Gov, G_2 Gov$

$$V = \frac{t_0 - k_0^*}{k_0 - k_0^*} V + \frac{t_0 - k_0}{k_0^* - k_0} V$$

by L32

$$G_2 V = \frac{t_0 - k_0^*}{k_0 - k_0^*} G_2 V + \frac{t_0 - k_0}{k_0^* - k_0} G_2 V$$

L32

$$G_0 V = \frac{k_3 + k_3^* - \theta k_0^* - \theta^* k_0}{\theta} \frac{t_0 - k_0^*}{k_0 - k_0^*} V + \frac{k_3 + k_3^* - \theta k_0 - \theta^* k_0^*}{\theta} \frac{t_0 - k_0}{k_0^* - k_0} V$$

L32  
if  $G_0 \neq 0$   
L14(i) if  
 $G_0 = 0$

$$G_2 G_0 V = \frac{t_0 - k_0^*}{k_0 - k_0^*} G_2 G_0 V + \frac{t_0 - k_0}{k_0^* - k_0} G_2 G_0 V$$

L32

Observe

$$\frac{t_0 - k_0^*}{k_0 - k_0^*} \frac{t_0 - k_0^*}{k_0 - k_0^*} = \frac{t_0 - k_0^*}{k_0 - k_0^*}$$

$$\frac{t_0 - k_0^*}{k_0 - k_0^*} \frac{t_0 - k_0}{k_0^* - k_0} = 0$$

Combining the above info we get

$$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} \quad t_1 \quad \frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} v =$$

term	coef	
$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} G_{2v}$	$\frac{\theta k_0 + \theta^{-1} k_0^{-1} - k_3 - k_3^{-1}}{(\theta - \theta^{-1})(k_0 - k_0^{-1})}$	$\frac{1}{q\theta - q^{-1}\theta^{-1}}$
$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} v$	$\frac{\theta k_0 + \theta^{-1} k_0^{-1} - k_3 - k_3^{-1}}{(\theta - \theta^{-1})(k_0 - k_0^{-1})}$	$\frac{q^{-1}\theta^{-1}(k_1 + k_1^{-1}) - k_2 - k_2^{-1}}{q^{-1}\theta^{-1} - q\theta}$
	+	
	$\frac{q^{-1}\theta(k_1 + k_1^{-1}) - k_2 - k_2^{-1}}{(\theta - \theta^{-1})(k_0 - k_0^{-1})}$	$\frac{k_3 + k_3^{-1} - \theta k_0^{-1} - \theta^{-1} k_0}{q^{-1}\theta - q\theta^{-1}}$
$\frac{t_0 - k_0^{-1}}{k_0 - k_0^{-1}} G_{1G_0v}$	$\frac{\theta}{(\theta - \theta^{-1})(k_0 - k_0^{-1})}$	$\frac{1}{q\theta^{-1} - q^{-1}\theta}$

Result follows using \*.

3e<sup>2</sup> □



Shortly we will return to the 3-term rec of Th 35

First we need to describe the unred  $\hat{H}_q$  modules

Notation

For unreds  $\lambda_1, \lambda_2, \lambda_3$

$$G(\lambda_1, \lambda_2, \lambda_3) = (\lambda_1 + \lambda_1^{-1})^2 + (\lambda_2 + \lambda_2^{-1})^2 + (\lambda_3 + \lambda_3^{-1})^2$$

$$- (\lambda_1 + \lambda_1^{-1})(\lambda_2 + \lambda_2^{-1})(\lambda_3 + \lambda_3^{-1}) - 4$$

$$= \lambda_1^{-2} (\lambda_1 - \lambda_2 \lambda_3^{-1})(\lambda_1 - \lambda_2^{-1} \lambda_3)(\lambda_1 - \lambda_2 \lambda_3)(\lambda_1 - \lambda_2^{-1} \lambda_3^{-1})$$

With ref to Cor 9, for  $0 \neq \theta \in \mathbb{F}$

$$G_0^2 \text{ acts on } V_X(\theta) \text{ as } G(\theta, k_0, k_3) I$$

$$G_1^2 \text{ -- } V_Y(\theta) \text{ -- } G(\theta, k_0, k_1) I$$

$$G_2^2 \text{ -- } V_X(\theta) \text{ -- } G(q^{-1}\theta, k_1, k_2) I$$

$$G_3^2 \text{ -- } V_Y(\theta) \text{ -- } G(q^{-1}\theta, k_2, k_3) I$$