

TRANSONIC SHOCKS AND FREE BOUNDARY PROBLEMS FOR THE FULL EULER EQUATIONS IN INFINITE NOZZLES

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ABSTRACT. We establish the existence, stability, and asymptotic behavior of transonic flows with a transonic shock for the steady, full Euler equations in two-dimensional infinite nozzles of slowly varying cross-sections. Given a smooth incoming flow that is close to a uniform supersonic state at the entrance, we prove that there exists a transonic flow whose infinite downstream smooth subsonic region is separated by a smooth transonic shock from the upstream supersonic flow. The solution is unique within the class of transonic solutions that are close to the background constant states. This problem is approached by a free boundary problem in which the transonic shock is formulated as a free boundary. An iteration scheme for the free boundary is developed and its fixed point is shown to exist, which is a solution of the free boundary problem, by combining some delicate estimates for a second-order nonlinear elliptic equation on a Lipschitz domain.

Résumé: Nous établissons l'existence, la stabilité et le comportement asymptotique des écoulements transoniques avec un choc transonique pour les équations d'Euler complètes et indépendantes du temps dans des tuyères bidimensionnelles, infinies et ayant des coupes transversales qui varient lentement. Étant donné un écoulement entrant régulier qui est proche d'un état supersonique uniforme à l'entrée, nous prouvons que—dans la direction de l'écoulement—il existe un écoulement transonique, dont la région (infinie) subsonique devant le choc est séparée de la région supersonique derrière le choc, par un choc transonique à travers une courbe lisse. La solution est unique dans la classe des solutions transoniques qui sont proches des états constants du fond. Ce problème est abordé par un problème à frontière libre, dans lequel le choc est formulé comme frontière libre. Nous développons un schéma d'itération pour la frontière libre et, en combinant quelques estimations délicates pour une équation elliptique nonlinéaire de deuxième ordre sur un domaine Lipschitzien, nous prouvons qu'il existe un point fixe qui est une solution du problème à frontière libre.

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1. INTRODUCTION

We establish the existence, stability, and asymptotic behavior of transonic flows with a transonic shock for the full Euler equations in two-dimensional infinite nozzles of slowly varying cross-sections. The transonic flow is governed by the following two-dimensional steady, full Euler equations:

$$\begin{cases} \nabla \cdot (\rho \mathbf{u}) = 0, \\ \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p = 0, \\ \nabla \cdot (\rho \mathbf{u} (E + p/\rho)) = 0, \end{cases} \quad (1.1)$$

where ∇ is the gradient in $\mathbf{x} = (x_1, x_2) \in \mathbb{R}^2$, $\mathbf{u} = (u_1, u_2)$ is the velocity, ρ the density, p the pressure, and

$$E = \frac{1}{2} |\mathbf{u}|^2 + \frac{p}{(\gamma - 1)\rho}$$

the energy with adiabatic exponent $\gamma > 1$. The sonic speed of the flow is

$$c = \sqrt{\gamma p / \rho}.$$

The flow is subsonic if $|\mathbf{u}| < c$ and supersonic if $|\mathbf{u}| > c$. For a transonic flow, both cases occur in the flow.

Given an incoming smooth flow that is close to a uniform supersonic state (i.e. smooth Cauchy data) at the entrance (say $x_1 = -1$) and the subsonic condition in the smooth downstream region, we are interested in whether there exists a transonic flow whose infinite downstream subsonic region is separated by a smooth transonic shock from the upstream supersonic flow. This nozzle problem can be approached by a free boundary problem in which the transonic shock is formulated as a free boundary.

Such transonic problems have been studied under several different physical situations in the recent years. In Chen-Feldman [5, 6, 7, 8], three nonlinear approaches have been developed to establish the existence and stability of transonic shocks for the multidimensional steady potential flow equation and applied to handling transonic flow problems in infinite channels and nozzles. Chen [11] also considered this problem in a bounded channel for the two-dimensional steady Euler flows with a certain symmetry and obeying the Bernoulli law with a uniform Bernoulli constant (also see [12]). The existence and uniqueness of transonic flows with a transonic shock were established in Chen-Chen-Song [4] for a *bounded* two-dimensional nozzle of slowly varying cross-sections with flat entrance section. Also see [13, 26] for related bounded, nozzle problems. There are related results for further simplified models: the unsteady transonic small disturbance equation in Canic-Keyfitz-Lieberman [1] and Canic-Keyfitz-Kim [2], the pressure-gradient system in Zheng [27, 28], and the nonlinear wave system in Canic-Keyfitz-Kim in [3] (see the further references cited therein). Also see [9, 10, 24, 25] for a program to deal with transonic and sonic-subsonic flows through (vanishing viscosity or relaxation) approximate or exact solutions via the method of compensated compactness.

In this paper, we systematically study the infinite transonic nozzle problem in the context of the full Euler equations. We prove that, for this nozzle problem, there exists a transonic flow whose infinite downstream smooth subsonic region is separated by a smooth transonic shock from the upstream supersonic flow. To achieve this, we first employ the coordinate transformation of Euler-Lagrange type so that the original streamlines in Eulerian coordinates become straight lines and the infinite nozzle in Eulerian coordinates becomes an infinite channel in the new Lagrangian coordinates. Then we use one of the new equations to identify a potential function ϕ in Lagrangian coordinates. By capturing the conservation properties of the Euler system, we derive a single second-order nonlinear elliptic equation for the potential function ϕ in the subsonic region so that the full Euler equations are reduced to this single second-order equation. The advantage of this approach is that, given the shock

location, all the physical variables $(\mathbf{u}, p, \rho)$ can be expressed as functions of the gradient of ϕ , and the asymptotic behavior ϕ_∞ of the potential ϕ at the infinite exit can be uniquely determined.

To solve the free boundary problem, we have to determine both the free boundary and the subsonic phase defined in the downstream region with the free boundary as a part of its boundary. We approach this problem by developing an iteration scheme via updating the location of shock front and designing a corresponding iteration map. In order to define the map for the given shock location, we first linearize the second-order elliptic equation for the identified potential function based on the limit function ϕ_∞ of the potential ϕ , solve the linearized problem in the fixed region, and then make delicate estimates of the solutions, especially the corner singularity near the intersection between the fixed shock and the nozzle boundaries. Finally, these estimates allow us to prove that the map is a contraction map so that the fixed point of the map is the real shock front and the corresponding subsonic solution in the downstream region is the real subsonic phase for the free boundary problem. Since the transformation between the Eulerian and Lagrangian coordinates is invertible, we obtain the existence and uniqueness of solutions of the infinite nozzle problem in Eulerian coordinates by transforming back the solutions in Lagrangian coordinates. The asymptotic behavior of solutions at the infinite exit is also clarified. The stability of transonic shocks and corresponding transonic flows is also established by employing the coordinate transformation of Euler-Lagrange type and careful, detailed estimates of the solution.

Another advantage in our analysis here is in the context of the real full Euler equations so that the solutions do not necessarily obey Bernoulli's law with a *uniform* Bernoulli constant, i.e., the Bernoulli constant is allowed to change for different fluid trajectories (compare with the setup in [11, 12, 13]). Since we work on the infinite channel in the new Lagrangian coordinates by iterating the location of shock front and making estimates of the corresponding solution in the downstream region, we do not require additional symmetry of the solutions (unlike in [6, 11]), or the flat condition of the entrance nozzle part (unlike in [4]). We remark that, by the closeness assumption of the solution U to the uniform flow in the subsonic region, we obtain the asymptotic behavior of U as $x_1 \rightarrow \infty$. The asymptotic state $U_\infty = (\mathbf{u}_\infty, p_\infty, \rho_\infty)$ is uniquely determined by the state U_- of the incoming flow at the entrance $x_1 = -1$. In particular, the vertical component of the asymptotic velocity equals to zero, $u_{2\infty} = 0$, and the pressure p_∞ is a constant determined by the incoming flow U_- . In general, $u_{1\infty}$ and ρ_∞ are not constants, which are actually functions of x_2 ; and the pressure condition at the exit of the nozzle is ill-posed (cf. [6, 7, 8, 14]).

The organization of this paper is as follows. In Section 2, we formulate the transonic nozzle problem into a free boundary problem in the two-dimensional infinite nozzle and state the main theorems. In Section 3, we introduce a coordinate transformation of Euler-Lagrange type and reformulate the free boundary problem in the new coordinates; then we identify a potential function ϕ and reduce the Euler system into a single second-order nonlinear elliptic equation for this potential function ϕ in the subsonic region. In Section 4, we solve a fixed boundary problem in a bounded, truncated domain of the infinite channel in the new coordinates by carefully making boundary estimates, especially near the corners of the truncated domain and employing the Hahn-Banach fixed point argument. Then, in Section 5, we extend the solutions of the fixed boundary problem in the bounded, truncated domains to the infinite channel. In Section 6, we formulate an iteration scheme via updating the location of shock front and designing a corresponding map so that the map is a contraction map, which leads to a fixed point that is a solution. Furthermore, in Section 7, we determine the asymptotic behavior of solutions at the infinite exit. In Section 8, we establish the stability of transonic shocks under the small perturbations of both incoming flows and the nozzle boundaries. In Section 9, we provide a proof of the existence and uniqueness

of supersonic solutions in the upstream region, which is required in order to formulate our infinite nozzle problem into a free boundary problem in Section 2.

2. FREE BOUNDARY PROBLEMS AND MAIN THEOREM

In this section, we formulate the transonic nozzle problem into a free boundary problem in the two-dimensional infinite nozzle and state the main theorem.

For concreteness, the nozzle domain can be formulated in the form:

$$\Omega = \{\mathbf{x} \in \mathbb{R}^2 : x_1 > -1, \zeta_0(x_1) < x_2 < \zeta_1(x_1)\}, \quad (2.1)$$

where $\zeta_i, i = 0, 1$, are functions of x_1 to describe the lower and upper walls of the nozzle. Denote the lower and upper boundaries by Γ_i , i.e.,

$$\Gamma_i = \{\mathbf{x} : x_2 = \zeta_i(x_1), x_1 > -1\}, \quad i = 0, 1. \quad (2.2)$$

We also define

$$\Omega_1 = \Omega \cap \{-1 < x_1 < 1\} \quad (2.3)$$

as the entrance part of the flow $U := (\mathbf{u}, p, \rho)$.

We are interested in transonic flows separated by a transonic shock near the x_2 -axis in the infinite nozzle. Assume that an incoming flow $U_- = (\mathbf{u}_-, p_-, \rho_-)$ is supersonic from left, defined in the domain Ω_1 . Our goal is to seek a shock $S = \{x_1 = s(x_2)\}$ and a downstream subsonic flow U satisfying the Euler equations (1.1) in the domain

$$\Omega_s := \Omega \cap \{\mathbf{x} : x_1 > s(x_2)\} \quad (2.4)$$

and the following Rankine-Hugoniot conditions along the shock $x_1 = s(x_2)$:

$$\begin{cases} [\rho u_1] = s'(x_2)[\rho u_2], \\ [\rho u_1^2 + p] = s'(x_2)[\rho u_1 u_2], \\ [\rho u_1 u_2] = s'(x_2)[\rho u_2^2 + p], \\ [\rho u_1(E + p/\rho)] = s'(x_2)[\rho u_2(E + p/\rho)], \end{cases} \quad (2.5)$$

where $[\]$ denotes the jump between the quantity of two states across the shock front.

Note that $(\mathbf{u}, p, \rho)$, which is smooth in $\Omega_s \cup S$ and $\Omega \setminus \Omega_s$, is a weak solution of the Euler system (1.1) in Ω if and only if it is a classical solution of (1.1) in $\Omega_s \cup S$ and $\Omega \setminus \Omega_s$, and conditions (2.5) hold on the shock front S .

We need to fix one point in the nozzle in order to locate the position of the shock. Without loss of generality, we let $(0, \zeta_0(0))$ be the point for the shock, i.e., $s(\zeta_0(0)) = 0$.

In order to study the infinite nozzle flow of slowly varying-cross sections, we introduce the background solution:

$$U_{\pm}^0 = (u_{1\pm}^0, 0, p_{\pm}^0, \rho_{\pm}^0),$$

which are two constant states: a supersonic state U_-^0 and a subsonic state U_+^0 respectively, separated by a steady transonic shock front at $x_1 = 0$. That is,

$$U^0 = \begin{cases} U_-^0 = (u_{1-}^0, 0, p_-^0, \rho_-^0) & \text{if } x_1 < 0, \\ U_+^0 = (u_{1+}^0, 0, p_+^0, \rho_+^0) & \text{if } x_1 > 0 \end{cases} \quad (2.6)$$

is a transonic shock solution of (1.1) with (2.5) so that

$$|(c_{\pm}^0)^2 - (u_{1\pm}^0)^2| > \delta_0, \quad (2.7)$$

for some $\delta_0 > 0$, where $c_{\pm}^0 = \sqrt{\gamma p_{\pm}^0 / \rho_{\pm}^0}$.

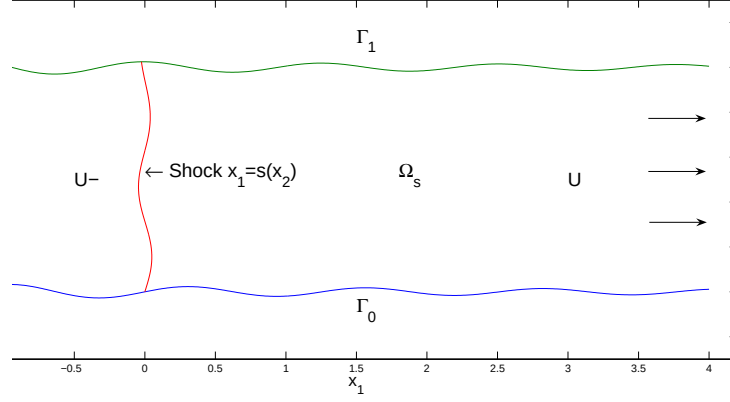


FIGURE 1. The infinite transonic nozzle problem

In this case, $s'(x_2) = 0$, and the Rankine-Hugoniot conditions (2.5) become

$$\begin{cases} [\rho^0 u_1^0] = 0, \\ [\rho^0 (u_1^0)^2 + p^0] = 0, \\ [\rho^0 u_1^0 (\frac{(u_1^0)^2}{2} + \frac{\gamma p^0}{(\gamma - 1)\rho^0})] = 0. \end{cases} \quad (2.8)$$

Conditions (2.7)–(2.8) yield the entropy condition for the constant solution:

$$\rho_+^0 > \rho_-^0, \quad (2.9)$$

which implies

$$u_{1+}^0 < u_{1-}^0, \quad p_+^0 > p_-^0.$$

Since the nozzle has slowly varying cross-sections, the lower and upper boundaries are small perturbations of the straight walls. We assume that, for sufficiently small $\varepsilon > 0$, $\zeta_i = \zeta_i(x_1)$, $i = 1, 2$, satisfy

$$\|\zeta_i - i\|_{C^{3,\alpha}(-1,\infty)} \leq \varepsilon, \quad (2.10)$$

$$|\zeta_i(x_1) - i| \leq \frac{\varepsilon}{(1 + |x_1|)^\beta}, \quad (2.11)$$

where $1 < \beta < 2$ is a fixed constant. Condition (2.11) indicates that the nozzle asymptotically converges to a uniform nozzle at the infinity with algebraic rate of order β .

Since our solutions are expected to be near the background solution U^0 , they will automatically satisfy the entropy condition because of (2.9). In particular, when U satisfies

$$\|U - U_+^0\|_{C^\alpha(\Omega_s)} \leq C\varepsilon$$

for some constant $C > 0$, then U stays subsonic in the subsonic region $\Omega_s \subset \Omega$.

Now we set up the transonic nozzle problem. Let ν be the outer unit normal to $\partial\Omega$.

Problem I (Infinite transonic nozzle problem). Given a smooth incoming flow close to the uniform supersonic flow U_0^- at the entrance, find a transonic flow U that is supersonic after passing the entrance $\{x_1 = -1\}$ and subsonic in the downstream domain Ω_s , separated by a transonic shock $S := \{x_1 = s(x_2)\}$ with $s(\zeta_0(0)) = 0$ for the following

problem of initial-boundary value type in an impermeable nozzle:

$$U|_{x_1=-1} = \tilde{U}_- := (\tilde{\mathbf{u}}_-, \tilde{p}_-, \tilde{\rho}_-)(x_2) \in C^{2,\alpha}(d_0, d_1), \quad (2.12)$$

$$\mathbf{u} \cdot \nu|_{\Gamma_i} = 0, \quad i = 0, 1, \quad (2.13)$$

with the compatibility condition:

$$\tilde{u}_{2-}(d_i) = \zeta'_i(-1)\tilde{u}_{1-}(d_i), \quad (2.14)$$

and the closeness condition to the uniform supersonic flow U_0^- at $x_1 = -1$ and the uniform nozzle for $-1 < x_1 < 1$:

$$\|\tilde{U}_- - U_0^-\|_{C^{2,\alpha}(d_0, d_1)} + \sum_{i=0,1} \|\zeta_i - i\|_{C^{3,\alpha}(-1,1)} \leq \varepsilon \quad (2.15)$$

for some small $\varepsilon > 0$, where $d_i = \zeta_i(-1)$, $i = 0, 1$.

In order to formulate this nozzle problem into a free boundary problem, we show the existence and uniqueness of supersonic flows in the upstream region Ω_1 . This is achieved via the method of characteristics in Section 9.

Theorem 2.1. *There exists $\varepsilon_0 > 0$ such that, when $\varepsilon \in (0, \varepsilon_0)$, there exist a constant $C_0 > 0$ and a unique supersonic solution $U_- = (\mathbf{u}_-, p_-, \rho_-)(x, y) \in C^{2,\alpha}(\Omega_1)$ of Problem (1.1) and (2.12)–(2.15) such that*

$$\|U_- - U_0^-\|_{C^{2,\alpha}(\Omega_1)} \leq C_0 \varepsilon. \quad (2.16)$$

With Theorem 2.1, we can reformulate Problem I into the following free boundary problem.

Problem II. Assume that the domain Ω in (2.1) satisfies condition (2.10)–(2.11). Let U_- be a supersonic solution of (1.1) in the domain Ω_1 satisfying the slip condition (2.13) and the closeness condition to the uniform supersonic flow U_-^0 :

$$\|U_- - U_-^0\|_{C^{2,\alpha}(\Omega_1)} \leq \varepsilon \quad (2.17)$$

for some small constant ε . Find a subsonic flow $U(\mathbf{x})$ satisfying the Euler equations (1.1) in the domain Ω_s defined in (2.4) and the slip condition (2.13), separated by a transonic shock $S = \{x_1 = s(x_2)\}$ satisfying $s(\zeta_0(0)) = 0$ and the Rankine-Hugoniot conditions in (2.5).

At the corners between the shock front S and the boundaries Γ_i , we expect less regularity for the solution; and this less regularity spreads along the boundaries Γ_i so that we will not have the $C^{1,\alpha}$ smoothness for the downstream solution U . Instead, we need to use the following weighed Hölder norms: For any $\mathbf{x}, \mathbf{x}'$ in a two-dimensional domain E and for an open portion P of ∂E , define $\delta_{\mathbf{x}} := \text{dist}(\mathbf{x}, P)$ and $\delta_{\mathbf{x}, \mathbf{x}'} := \min(\delta_{\mathbf{x}}, \delta_{\mathbf{x}'})$. Let $\alpha \in (0, 1)$ and $\sigma \in \mathbb{R}$. We define

$$\begin{aligned} [u]_{k,0;E}^{(\sigma;P)} &= \sup_{\mathbf{x} \in E, |\mathbf{k}|=k} (\delta_{\mathbf{x}}^{\max(k+\sigma,0)} |D^{\mathbf{k}}u(\mathbf{x})|), \\ [u]_{k,\alpha;E}^{(\sigma;P)} &= \sup_{\mathbf{x}, \mathbf{x}' \in E, \mathbf{x} \neq \mathbf{x}', |\mathbf{k}|=k} \left(\delta_{\mathbf{x}, \mathbf{x}'}^{\max(k+\alpha+\sigma,0)} \frac{|D^{\mathbf{k}}u(\mathbf{x}) - D^{\mathbf{k}}u(\mathbf{x}')|}{|\mathbf{x} - \mathbf{x}'|^\alpha} \right), \\ \|u\|_{k,\alpha;E}^{(\sigma;P)} &= \sum_{i=0}^k [u]_{i,0;E}^{(\sigma;P)} + [u]_{k,\alpha;E}^{(\sigma;P)}, \end{aligned} \quad (2.18)$$

where $\mathbf{k} = (k_1, k_2)$, $|\mathbf{k}| = k_1 + k_2$, and $D^{\mathbf{k}} = \partial_{x_1}^{k_1} \partial_{x_2}^{k_2}$. We also use the same notation for one-dimensional domains. In this case, the boundary portion should be understood as the two endpoints.

We define the Banach space $C_{(\sigma;P)}^{k,\alpha}(E)$ by

$$C_{(\sigma;P)}^{k,\alpha}(E) := \{u : \|u\|_{k,\alpha;E}^{(\sigma;P)} < \infty\}. \quad (2.19)$$

We may drop the symbols P, E in the norms within the context if it does not cause ambiguity. For vector-valued functions $U = (u_1, \dots, u_n)$, we define

$$\|U\|_{k,\alpha;E}^{(\sigma;P)} = \sum_{i=1}^n \|u_i\|_{k,\alpha;E}^{(\sigma;P)}. \quad (2.20)$$

In our problem, the boundary portion is $P = \Gamma_0 \cup \Gamma_1 =: \Gamma_{0,1}$. Now we state our main theorem whose proof is provided in Sections 3–6.

Theorem 2.2 (Main Theorem). *There exists $\varepsilon_0 > 0$ such that, when $\varepsilon \in (0, \varepsilon_0)$, if the incoming supersonic flow U_- in Ω_1 satisfies (2.17), there exists a subsonic solution U and the shock S for **Problem II**. Furthermore, if the shock S intersects with Γ_0 and Γ_1 at points (x_1^0, x_2^0) and (x_1^1, x_2^1) respectively, then*

$$\|U - U_+^0\|_{1,\alpha;\Omega_s}^{(-\alpha;\Gamma_{0,1})} \leq C\varepsilon, \quad (2.21)$$

$$\|s\|_{2,\alpha;(x_2^0, x_2^1)}^{(-1-\alpha)} \leq C\varepsilon, \quad (2.22)$$

where C is a constant depending only on α and U_-^0 , but independent of ε . The solution U is unique within the class of transonic solutions U satisfying (2.21).

Remark 2.1. Combining Theorem 2.2 with Theorem 2.1, we solve the infinite transonic nozzle problem, Problem I.

We also establish the stability and asymptotic behavior of transonic nozzle flows in Sections 7–8.

3. LAGRANGIAN COORDINATES AND REDUCTION OF THE EULER SYSTEM

To simplify the analysis, we employ the following coordinate transformation of Euler-Lagrange type:

$$\begin{cases} y_1 = x_1, \\ y_2 = \int_{\zeta_0(x_1)}^{x_2} \rho u_1(x_1, s) ds, \end{cases} \quad (3.1)$$

under which the original curved streamlines become straight. In the new coordinates $\mathbf{y} = (y_1, y_2)$, we still denote the unknown variables $U(\mathbf{x}(\mathbf{y}))$ by $U(\mathbf{y})$ for simplicity of notation.

The original Euler equations in (1.1) become the following equations in divergence form:

$$\left(\frac{1}{\rho u_1}\right)_{y_1} - \left(\frac{u_2}{u_1}\right)_{y_2} = 0, \quad (3.2)$$

$$\left(u_1 + \frac{p}{\rho u_1}\right)_{y_1} - \left(\frac{p u_2}{u_1}\right)_{y_2} = 0, \quad (3.3)$$

$$(u_2)_{y_1} + p_{y_2} = 0, \quad (3.4)$$

$$\left(\frac{1}{2}|\mathbf{u}|^2 + \frac{\gamma p}{(\gamma - 1)\rho}\right)_{y_1} = 0. \quad (3.5)$$

Let $\mathcal{F} : y_1 = f(y_2)$ be a shock front. Then, from the above equations, we can derive the Rankine-Hugoniot conditions along $\mathcal{F}$:

$$\left[\frac{1}{\rho u_1}\right] = -\left[\frac{u_2}{u_1}\right] f'(y_2), \quad (3.6)$$

$$\left[u_1 + \frac{p}{\rho u_1}\right] = -\left[\frac{p u_2}{u_1}\right] f'(y_2), \quad (3.7)$$

$$[u_2] = [p] f'(y_2), \quad (3.8)$$

$$\left[\frac{1}{2}|\mathbf{u}|^2 + \frac{\gamma p}{(\gamma - 1)\rho}\right] = 0. \quad (3.9)$$

Also the original fixed point $(0, \zeta_0(0))$ on S becomes the origin $(0, 0)$ on the new shock $\mathcal{F}$.

Set

$$M = \int_{\zeta_0(x_1)}^{\zeta_1(x_1)} \rho u_1(x_1, s) ds.$$

It is easy to check that M is a constant independent of x_1 from the first equation of (1.1) (conservation of mass). Actually, M is determined by $U_-(-1, x_2)$, the data of incoming flow at the entrance of the nozzle. Also, denote

$$M_0 = \rho_-^0 u_{1-}^0 = \rho_+^0 u_{1+}^0. \quad (3.10)$$

Then we have

$$|M - M_0| \leq C\varepsilon. \quad (3.11)$$

Under this transformation, the whole domain of the infinite nozzle becomes the infinite channel:

$$R = \{y : y_1 > -1, 0 < y_2 < M\}. \quad (3.12)$$

We define

$$R_1 := R \cap \{y_1 < 1\}, \quad (3.13)$$

$$R_f := R \cap \{y_1 > f(y_2)\}. \quad (3.14)$$

We also define

$$\mathcal{B}_0 := R \cap \{y_2 = 0\}, \quad \mathcal{B}_1 = R \cap \{y_2 = M\}, \quad (3.15)$$

which are the lower and upper boundaries of R respectively. Then we have the slip condition:

$$\left. \frac{u_2}{u_1} \right|_{\mathcal{B}_i} = \zeta'_i(y_1). \quad (3.16)$$

Then **Problem II** is equivalent to the following problem.

Problem III. Let U_- be a supersonic solution satisfying equations (3.2)–(3.5) in the upstream region R_1 and the slip condition (3.16). Assume that U_- is a small perturbation of U_-^0 with

$$\|U_- - U_-^0\|_{C^{2,\alpha}(R_-)} \leq \varepsilon \quad (3.17)$$

for some small constant ε . Find a subsonic flow $U(y)$ satisfying equations (3.2)–(3.5) in the downstream region R_f and the slip condition (3.16), separated by a transonic shock $\mathcal{F} := R \cap \{y_1 = f(y_2)\}$ satisfying $f(0) = 0$ and the Rankine-Hugoniot conditions (3.6)–(3.9).

Correspondingly, we have the following theorem that is equivalent to Theorem 2.2.

Theorem 3.1. *There exists $\varepsilon_0 > 0$ such that, when $\varepsilon \in (0, \varepsilon_0)$, for any given incoming supersonic flow U_- satisfying (3.17), there exist a subsonic solution U and the shock $\mathcal{F} := R \cap \{y_1 = f(y_2)\}$ for **Problem III**. Furthermore, we have the following estimates:*

$$\|U - U_+^0\|_{1,\alpha;R_f}^{(-\alpha;\mathcal{B}_{0,1})} \leq C\varepsilon, \quad (3.18)$$

$$\|f\|_{2,\alpha;(0,M)}^{(-1-\alpha)} \leq C\varepsilon, \quad (3.19)$$

where C is a constant depending only on α and U^0 , but independent of ε . Within the class of U satisfying (3.18), the solution is unique.

Remark 3.1. Estimate (3.18) guarantees that the coordinate transformation is $C^{3,\alpha}$ smooth in the supersonic region, $C^{1,\alpha}$ in the subsonic region, and Lipschitz across the shock, and the Jacobian is nonsingular, so that we can transform the Lagrangian coordinates back to Euler coordinates, which renders the equivalence of Theorem 3.1 and Theorem 2.2.

From now on to the end of Section 6, we focus only on establishing Theorem 3.1 in the $\mathbf{y}$ -coordinates, which yields Theorem 2.2 in the $\mathbf{x}$ -coordinates.

According to the coordinate transformation from $\mathbf{x}$ to $\mathbf{y}$, we know that x_2 can be solved as a function of $\mathbf{y}$. Let $x_2 := \phi(\mathbf{y})$ in the subsonic domain R_f and $x_2 := \phi_-(\mathbf{y})$ in the supersonic domain R_1 . Given U_- , we can find the corresponding ϕ_- . We now use the function ϕ to reduce the original Euler system to an elliptic equation in the subsonic domain.

By the definition of coordinate transformation (3.1), we have

$$\phi_{y_1} = \frac{u_2}{u_1}, \quad \phi_{y_2} = \frac{1}{\rho u_1}, \quad (3.20)$$

that is, $\phi(\mathbf{y})$ is the potential function of the vector field $(\frac{u_2}{u_1}, \frac{1}{\rho u_1})$.

Equation (3.5) implies Bernoulli's law:

$$\frac{1}{2}|\mathbf{u}|^2 + \frac{\gamma p}{(\gamma-1)\rho} = B(y_2), \quad (3.21)$$

where $B = B(y_2)$ is completely determined by the incoming flow U_- at the entrance $x_1 = -1$.

From equation (3.2)–(3.5), we find

$$(\gamma \ln \rho - \ln p)_{y_1} = 0,$$

which implies

$$p = A(y_2)\rho^\gamma \quad \text{in the subsonic domain } R_f. \quad (3.22)$$

The function $A = A(y_2)$ can be determined by the incoming flow U_- and the Rankine-Hugoniot conditions on the shock $\mathcal{F}$, provided that the shock position $y_1 = f(y_2)$ is given. The details of this will be discussed later (see (3.38)–(3.45)).

With equation (3.20) and (3.22), we can rewrite Bernoulli's law into the following form:

$$\frac{\phi_{y_1}^2 + 1}{2\phi_{y_2}^2} + \frac{\gamma}{\gamma-1} A \rho^{\gamma+1} = B \rho^2. \quad (3.23)$$

In the subsonic region, $|\mathbf{u}| < c := \sqrt{\gamma p / \rho}$. Therefore, Bernoulli's law (3.21) implies

$$\rho^{\gamma-1} > \frac{2B}{\kappa A}, \quad (3.24)$$

where $\kappa = \frac{\gamma(\gamma+1)}{\gamma-1}$.

Condition (3.24) guarantees that ρ can be solved from (3.23) as a smooth function of $(A, B, \nabla \phi)$.

Assume that we have known $A = A(y_2)$. Then $(\mathbf{u}, p, \rho)$ can be expressed as functions of $\nabla \phi$:

$$\rho = \rho(A, B, \nabla \phi), \quad u_1 = \frac{1}{\rho \phi_{y_2}}, \quad u_2 = \frac{\phi_{y_1}}{\rho \phi_{y_2}}, \quad p = A \rho^\gamma, \quad (3.25)$$

since $B = B(y_2)$ is given by the incoming flow.

We now choose (3.4) to derive a second-order nonlinear elliptic equation for ϕ so that the full Euler system is reduced to this equation. Set

$$N^1 = u_2, \quad N^2 = p - p_+^0. \quad (3.26)$$

Then we have the second-order nonlinear equation for ϕ :

$$(N^1)_{y_1} + (N^2)_{y_2} = 0, \quad (3.27)$$

that is,

$$N_{\phi_{y_1}}^1 \phi_{y_1 y_1} + (N_{\phi_{y_2}}^1 + N_{\phi_{y_1}}^2) \phi_{y_1 y_2} + N_{\phi_{y_2}}^2 \phi_{y_2 y_2} = 0, \quad (3.28)$$

where $N^i = N^i(A(y_2), B(y_2), \nabla\phi)$, $i = 1, 2$, are given by

$$\begin{aligned} N^1(A, B, \nabla\phi) &= \frac{\phi_{y_1}}{\phi_{y_2}\rho(A(y_2), B(y_2), \nabla\phi)}, \\ N^2(A, B, \nabla\phi) &= A(y_2)\rho(A(y_2), B(y_2), \nabla\phi)^\gamma - p_+^0. \end{aligned} \quad (3.29)$$

We now verify that (3.27), or equivalently (3.28), is uniformly elliptic for ϕ , provided that U is a small perturbation of U_+ , i.e.,

$$\|U - U_+^0\|_{C^0(\Omega_f)} \leq \delta \quad (3.30)$$

for any small data $\delta \leq \delta_0$, where δ_0 will be given later in Lemma 4.1. In the following, the positive constants λ_i related to ellipticity will depend only on the background states $U_\pm^0$.

Differentiating (3.23) with respect to $\nabla\phi$, we can calculate $\rho_{\phi_{y_1}}$ and $\rho_{\phi_{y_2}}$ to obtain

$$\rho_{\phi_{y_1}} = \frac{-\phi_{y_1}}{\phi_{y_2}^2(\kappa A\rho^\gamma - 2B\rho)}, \quad (3.31)$$

$$\rho_{\phi_{y_2}} = \frac{\phi_{y_1}^2 + 1}{\phi_{y_2}^3(\kappa A\rho^\gamma - 2B\rho)}. \quad (3.32)$$

Now we calculate $N_{\phi_{y_j}}^i$, $i, j = 1, 2$. First, we have follows:

$$N_{\phi_{y_1}}^1 = \frac{1}{\phi_{y_2}\rho} - \frac{\phi_{y_1}\rho_{\phi_{y_1}}}{\phi_{y_2}\rho^2} = \frac{\phi_{y_2}^2(\gamma A\rho^{\gamma+1} - \frac{\phi_{y_1}^2+1}{\phi_{y_2}^2}) + \phi_{y_1}^2}{\phi_{y_2}^3\rho^2(\kappa A\rho^\gamma - 2B\rho)}, \quad (3.33)$$

where we used (3.31) and (3.23) to obtain the last equality (3.33). Similarly, using (3.31)–(3.32) and (3.23), we have

$$N_{\phi_{y_2}}^1 = N_{\phi_{y_1}}^2 = \frac{-\gamma A\rho^{\gamma-1}\phi_{y_1}}{\phi_{y_2}^2(\kappa A\rho^\gamma - 2B\rho)}, \quad (3.34)$$

$$N_{\phi_{y_2}}^2 = \frac{\gamma A\rho^{\gamma-1}(\phi_{y_1}^2 + 1)}{\phi_{y_2}^3(\kappa A\rho^\gamma - 2B\rho)}. \quad (3.35)$$

By subsonicity of U_+^0 and the small perturbation assumption (3.30), we have

$$\kappa A\rho^\gamma - 2B\rho > \lambda_1 > 0.$$

Hence, we know $N_{\phi_{y_2}}^2 > \lambda_2 > 0$. In the subsonic domain, we have

$$|\mathbf{u}|^2 = \frac{\phi_{y_1}^2 + 1}{\phi_{y_2}^2\rho^2} < c^2 - \lambda_3 = \gamma A\rho^{\gamma-1} - \lambda_3.$$

Therefore, (3.33) implies $N_{\phi_{y_1}}^1 > \lambda_4 > 0$.

Then we have

$$N_{\phi_{y_1}}^1 N_{\phi_{y_2}}^2 - N_{\phi_{y_2}}^1 N_{\phi_{y_1}}^2 = \frac{\gamma A\rho^{\gamma-1}(\gamma A\rho^{\gamma+1} - \frac{\phi_{y_1}^2+1}{\phi_{y_2}^2})}{\phi_{y_2}^4\rho^2(\kappa A\rho^\gamma - 2B\rho)^2} > \lambda_5 > 0, \quad (3.36)$$

which implies that the second-order nonlinear equation (3.27), equivalently (3.28), is uniformly elliptic.

Next we derive the boundary conditions for equation (3.27). Among the four Rankine-Hugoniot conditions (3.6)–(3.9), condition (3.6) is equivalent to the continuity of ϕ across the shock $\mathcal{F}$. That is,

$$\phi = \phi_- \quad \text{on the shock } \mathcal{F}. \quad (3.37)$$

Condition (3.8) will be used to locate the shock front later, and condition (3.9) is already used to compute B . We need all the four conditions (3.6)–(3.9) to determine the function $A = A(y_2)$.

To compute A , we first fix the shock front $\mathcal{F}$. Then, from (3.8), we can determine u_2 :

$$u_2 = u_{2-} + [p]f'(y_2). \quad (3.38)$$

Let $W = (u_1, p, \rho)$. Eliminating u_2 in (3.6)–(3.7) and (3.9) by (3.38) leads to

$$\left[\frac{1}{\rho u_1}\right] + \tilde{G}_1(U_-, W, f') =: G_1(U_-, W, f') = 0, \quad (3.39)$$

$$\left[u_1 + \frac{p}{\rho u_1}\right] + \tilde{G}_2(U_-, W, f') =: G_2(U_-, W, f') = 0, \quad (3.40)$$

$$\left[\frac{1}{2}u_1^2 + \frac{\gamma p}{(\gamma-1)\rho}\right] + \tilde{G}_3(U_-, W, f') =: G_3(U_-, W, f') = 0, \quad (3.41)$$

along the shock $\mathcal{F}$, where

$$\tilde{G}_i(U_-, W, f') = O(|u_{2-}| + |f'|^2).$$

Let $\mathbf{G} = (G_1, G_2, G_3)^\top$. We compute $\nabla_W \mathbf{G} \equiv (\partial_{u_1} \mathbf{G}, \partial_p \mathbf{G}, \partial_\rho \mathbf{G})$:

$$\nabla_W \mathbf{G}|_{\{U_- = U_-^0, f' = 0\}} = \begin{pmatrix} -\frac{1}{\rho u_1^2} & 0 & -\frac{1}{\rho^2 u_1} \\ 1 - \frac{p}{\rho u_1^2} & \frac{1}{\rho u_1} & -\frac{p}{\rho^2 u_1} \\ u_1 & \frac{\gamma}{(\gamma-1)\rho} & -\frac{\gamma p}{(\gamma-1)\rho^2} \end{pmatrix}. \quad (3.42)$$

It is easy to check that

$$\det(\nabla_W \mathbf{G}) = -\frac{c^2 - u_1^2}{(\gamma-1)\rho^3 u_1^3} < -\lambda_6 < 0 \quad (3.43)$$

for some constant λ_6 depending only on U^0 .

Therefore, by the Implicit Function Theorem, we can solve equations (3.39)–(3.41) for W along the shock $y_1 = f(y_2)$. Then we define

$$A(y_2) = \frac{p}{\rho^\gamma}(f(y_2), y_2). \quad (3.44)$$

Let $A^0 = \frac{p_+^0}{(\rho_+^0)^\gamma}$ and $W_+^0 = (u_{1+}^0, \rho_+^0, p_+^0)$. From (3.39)–(3.41), we know

$$\mathbf{G}(U_-^0, W_+^0, 0) = \mathbf{0}.$$

Hence, by Taylor expansion, we conclude that A is a small perturbation of A^0 :

$$A - A^0 = O(|U_-(f(y_2), y_2) - U_-^0| + |f'(y_2)|^2). \quad (3.45)$$

The conditions for ϕ on the lower and upper boundaries $\mathcal{B}_{0,1}$ are

$$\phi|_{\mathcal{B}_i} = \zeta_i \quad \text{for } i = 0, 1. \quad (3.46)$$

This is equivalent to the slip condition (3.16).

Finally, for the fixed shock $\mathcal{F}$, we heuristically determine the *asymptotic behavior* of ϕ as $y_1 \rightarrow \infty$. Let $\phi \rightarrow \phi_\infty(y_2)$ as $y_1 \rightarrow \infty$. From equation (3.27), $N^2 + p_+^0 = p$ approaches to a constant, denoted by p_∞ . Then

$$\rho \rightarrow \left(\frac{p_\infty}{A}\right)^{1/\gamma} \quad \text{as } y_1 \rightarrow \infty.$$

By Bernoulli's law (3.23), we have

$$\frac{1}{2\phi_\infty'(y_2)^2} + \frac{\gamma}{\gamma-1} A \left(\frac{p_\infty}{A}\right)^{(\gamma+1)/\gamma} = B \left(\frac{p_\infty}{A}\right)^{2/\gamma}. \quad (3.47)$$

We can solve for $\phi'_\infty(y_2)$ from the above equation to obtain

$$\phi'_\infty(y_2) = \left(2B \left(\frac{p_\infty}{A} \right)^{2/\gamma} - \frac{2\gamma}{\gamma-1} A \left(\frac{p_\infty}{A} \right)^{(\gamma+1)/\gamma} \right)^{-1/2}. \quad (3.48)$$

We also have the following boundary condition for $l(y_2)$:

$$\phi_\infty(0) = 0, \quad \phi_\infty(M) = 1. \quad (3.49)$$

Integrating (3.48) and using condition (3.49), we can uniquely determine the constant p_∞ and the function $\phi = \phi_\infty(y_2)$. This can be seen as follows.

Define function h by

$$h(A, B, p_\infty) = 2B \left(\frac{p_\infty}{A} \right)^{2/\gamma} - \frac{2\gamma}{\gamma-1} A \left(\frac{p_\infty}{A} \right)^{(\gamma+1)/\gamma}.$$

Define a functional $H : C([0, M]) \times C([0, M]) \times R^1 \times R^1 \rightarrow R^1$ by

$$H(A, B, M, p_\infty) = \int_0^M (h(A(y_2), B(y_2), p_\infty))^{-\frac{1}{2}} dy_2.$$

Therefore, if ϕ_∞ and p_∞ satisfy (3.48) and (3.49) for a given (A, B, M) , then we have

$$H(A, B, M, p_\infty) = \phi_\infty(M) = 1. \quad (3.50)$$

We now prove equation (3.50) is uniquely solvable for p_∞ by showing $\frac{\partial H}{\partial p_\infty}$ is strictly positive.

Actually, it is not hard to check that

$$\frac{\partial H}{\partial p_\infty}(A^0, B^0, M_0, p_+^0) = \frac{\rho_+^0((c_+^0)^2 - (u_{1+}^0)^2)}{M_0^2(c_+^0)^2} > \lambda_7 > 0,$$

where λ_7 only depends on $U_\pm^0$, and $B^0 = \frac{1}{2}(u_{1+}^0)^2 + \frac{\gamma p_+^0}{(\gamma-1)\rho_+^0}$. Computing $\frac{\partial H}{\partial p_\infty}$ explicitly, we see that $\frac{\partial H}{\partial p_\infty}$ is continuous with respect to $(A, B, M, p_\infty) \in C([0, M]) \times C([0, M]) \times R^1 \times R^1$. Hence, there exists a small constant $\delta > 0$, depending on $U_\pm^0$, such that

$$\frac{\partial H}{\partial p_\infty}(A, B, M, p_\infty) > \frac{\lambda_7}{2},$$

provided that

$$\|A - A^0\|_C + \|B - B^0\|_C + |M - M_0| + |p_\infty - p_+^0| \leq \delta. \quad (3.51)$$

Obviously, we have a trivial solution for (3.50):

$$H(A^0, B^0, M_0, p_+^0) = 1.$$

This implies p_∞ is uniquely determined when (3.51) is satisfied.

Remark 3.2. After we obtain estimate (5.3) later in Lemma 5.1, the function $\phi_\infty = \phi_\infty(y_2)$ derived above will be assured to be the asymptotic state.

4. FIXED BOUNDARY PROBLEMS IN FINITE DOMAINS

In this section we solve a fixed boundary problem in the truncated domain of R :

$$R^Q = R \cap \{\mathbf{y} : y_1 < Q\}, \quad (4.1)$$

where Q is a constant greater than 1.

Let

$$R_f^Q = R \cap \{\mathbf{y} : f(y_2) < y_1 < Q\}, \quad \mathcal{E} = \{y_1 = Q\} \cap R. \quad (4.2)$$

We prescribe the condition at the exit $\mathcal{E}$:

$$\phi|_{\mathcal{E}} = h_Q \quad (4.3)$$

with

$$h_Q = \zeta_0(Q) + (\zeta_1(Q) - \zeta_0(Q))l(y_2). \quad (4.4)$$

Using (3.49), it is easy to see the compatibility of the boundary conditions (3.46) and (4.3):

$$h_Q(0) = \zeta_0(Q), \quad h_Q(M) = \zeta_1(Q). \quad (4.5)$$

Now we formulate our fixed boundary problem in the finite domain R_f^Q .

Problem IV. Given an incoming flow ϕ_- with

$$\left\| \phi_- - \frac{y_2}{M_0} \right\|_{2,\alpha;R_1} \leq \varepsilon$$

and the fixed shock front $\mathcal{F} := \{y_1 = f(y_2)\}$, find a solution ϕ of the following boundary value problem:

$$\sum_{i=1,2} (N^i(A(y_2), B(y_2), \nabla \phi))_{y_i} = 0 \quad \text{in } R_f^Q, \quad (4.6)$$

$$\phi|_{\mathcal{F}} = \phi_-|_{\mathcal{F}}, \quad \phi|_{\mathcal{B}_{0,1}} = \zeta_{0,1}, \quad \phi|_{\mathcal{E}} = h_Q. \quad (4.7)$$

Then we have the following lemma for **Problem IV**.

Lemma 4.1. *There exist a constant C , a small constant $\delta_0 > 0$, and a constant $\varepsilon_0(\delta) > 0$ for each $0 < \delta < \delta_0$ with the following properties: If $Q > 1$, $\delta \in (0, \delta_0)$, $\varepsilon \in (0, \varepsilon_0(\delta))$, and a shock function $f = f(y_2)$ satisfies*

$$\|f\|_{2,\alpha;(0,M)}^{(-1-\alpha)} \leq \delta,$$

*then there is a solution ϕ of **Problem IV** satisfying*

$$\|\phi - \phi_\infty\|_{2,\alpha;R_f^Q}^{(-1-\alpha;\mathcal{B}_{0,1})} \leq C(\varepsilon + \delta^2), \quad (4.8)$$

where the norms used above are defined in (2.18). Moreover, the solution is unique in the class $\{\phi : \|\phi - \phi_\infty\|_{2,\alpha;R_f^Q}^{(-1-\alpha;\mathcal{B}_{0,1})} \leq \delta\}$.

Before we prove Lemma 4.1, we need a technical lemma for the elliptic estimate. Since we deal only with the finite domain R_f^Q in this section, we simplify the notation by omitting the domain R_f^Q and the boundaries $\mathcal{B}_{0,1}$ for the weights in the weighted norms.

Consider the boundary value problem for the elliptic equation

$$\sum_{i,j=1,2} (a_{ij}(\mathbf{y})\varphi_{y_i})_{y_j} = \sum_{i=1,2} (b_i(\mathbf{y}))_{y_i} \quad \text{in } R_f^Q \quad (4.9)$$

with the boundary conditions:

$$\varphi|_{y_1=f(y_2)} = g_S(y_2), \quad \varphi|_{\mathcal{B}_{0,1}} = g_{0,1}(y_1), \quad \varphi|_{\mathcal{E}} = g_{\mathcal{E}}(y_2). \quad (4.10)$$

Denote the intersection points of the shock $\mathcal{F}$ and the upper boundary $\mathcal{B}_1$ by $S_1 = (y_1^1, M)$. Also, the intersection points of the exit $\mathcal{E}$ with $\mathcal{B}_{0,1}$ are denoted by E_0 and E_1 . We require the compatibility condition for the boundary data (4.10) so that φ is continuous on the boundary of R_f^Q :

$$g_0(0) = g_S(0), \quad g_1(y_1^1) = g_S(M), \quad g_0(Q) = g_{\mathcal{E}}(0), \quad g_1(Q) = g_{\mathcal{E}}(M). \quad (4.11)$$

We also assume

$$g_{0,1} \in C^{1,\alpha}(\mathcal{B}_{0,1}), \quad (4.12)$$

$$g_S, g_{\mathcal{E}} \in C_{2,\alpha;(0,M)}^{(-1-\alpha)}. \quad (4.13)$$

The coefficients a_{ij} and b_i satisfy

$$\sum_{i,j=1,2} \|a_{ij}\|_{1,\alpha}^{(-\alpha)} + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)} \leq \Lambda, \quad (4.14)$$

$$\|a_{ij} - e_i \delta_{ij}\|_{1,\alpha}^{(-\alpha)} \leq \bar{\delta}, \quad i, j = 1, 2, \quad (4.15)$$

$$\sum_{i,j=1,2} a_{ij} \xi_i \xi_j \geq \lambda |\xi|^2, \quad (4.16)$$

where $\xi = (\xi_1, \xi_2)$ is an arbitrary vector; $\bar{\delta}$ is a fixed small constant depending on U^0 ; λ, Λ, e_i are fixed positive constants, depending on U^0 ; and $\delta_{ij} = 1$ when $i = j$, and 0 otherwise.

Lemma 4.2. *There is a unique solution $\varphi \in C_{2,\alpha;R_f^Q}^{(-1-\alpha;\mathcal{B}_{0,1})}$ for the boundary value problem (4.9)–(4.10) satisfying (4.12)–(4.16). Furthermore, the solution φ satisfies*

$$\|\varphi\|_{2,\alpha}^{(-1-\alpha)} \leq C \left(\sum_{i=0,1} \|g_i\|_{1,\alpha;\mathcal{B}_i} + \sum_{i=S,\mathcal{E}} \|g_i\|_{2,\alpha;(0,M)}^{(-1-\alpha)} + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)} \right), \quad (4.17)$$

where C is a constant depending only on $\lambda, \Lambda, \bar{\delta}$, and e_i , but independent of the length of the nozzle Q .

Proof. The boundary value problem (4.9)–(4.10) admits a unique solution in $C^0(\overline{R_f^Q}) \cap C^{2,\alpha}(R_f^Q)$, which is a classical result (see [16], Chapter 8). To obtain the estimates in the weighted norm $C_{(-1-\alpha)}^{2,\alpha}$ independent of the domain, a detailed analysis is required.

By assumption (4.15), the elliptic operator

$$L = \sum_{i,j=1,2} \partial_{y_i} (a_{ij} \partial_{y_j})$$

is a small perturbation of the operator

$$L_0 = e_1 \partial_{y_1}^2 + e_2 \partial_{y_2}^2.$$

Without loss of generality, we may assume

$$e_1 = e_2 = 1. \quad (4.18)$$

Otherwise, by the transformation $(\tilde{y}_1, \tilde{y}_2) = (\frac{y_1}{\sqrt{e_1}}, \frac{y_2}{\sqrt{e_2}})$, we can change L_0 into the Laplace operator.

We first need to obtain an estimate of the maximum norm of φ , which depends only on the boundary data and nonhomogeneous terms, but independent of the domain. To achieve this, we use the following comparison function

$$v_0 = c_0 (1 + y_2^\alpha + (M - y_2)^\alpha),$$

where

$$c_0 = \tilde{c}_0 \left(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)} \right), \quad G_b = \sum_{i=0,1} \|g_i\|_{1,\alpha;\mathcal{B}_i} + \sum_{i=S,\mathcal{E}} \|g_i\|_{2,\alpha;(0,M)}^{(-1-\alpha)}.$$

Then, using (4.15), we have

$$\begin{aligned}
Lv_0 &= c_0\alpha(\alpha-1)(y_2^{\alpha-2} + (M-y_2)^{\alpha-2}) \\
&\quad + c_0(a_{2i} - \delta_{2i})_{y_i}\alpha(y_2^{\alpha-1} - (M-y_2)^{\alpha-1}) \\
&\leq -\frac{1}{2}\alpha(1-\alpha)c_0(y_2^{\alpha-2} + (M-y_2)^{\alpha-2}) \\
&\leq -\frac{1}{2M}\alpha(1-\alpha)\tilde{c}_0(y_2^{\alpha-1} + (M-y_2)^{\alpha-1}) \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)} \\
&\leq \sum_{i=1,2} (b_i)_{y_i} = L\varphi
\end{aligned}$$

for sufficiently large $\tilde{c}_0$.

On the boundary, $v_0 \geq \varphi$ by definition of v_0 . Hence, by the Comparison Principle, we conclude

$$\|\varphi\|_{0,0} \leq v_0 \leq C(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}), \quad (4.19)$$

where C is independent of Q .

To obtain a better maximum bound, we construct a comparison function v . We focus on the behavior of φ near the origin. The other corner points can be treated in the same way. Let $\tau = (1-\alpha)/5$. Define the function $v(r, \theta)$ in polar coordinates:

$$\begin{aligned}
v(r, \theta) &= c_1 r^{1+\alpha} \sin(\tau + (1+\alpha+\tau)\theta) - c_2 y_2^{1+\alpha} \\
&=: c_1 v_1 - c_2 v_2,
\end{aligned} \quad (4.20)$$

where the constants c_1 and c_2 will be determined later. A simple computation shows that

$$\begin{aligned}
\Delta v_1 &= ((1+\alpha)^2 - (1+\alpha+\tau)^2) r^{\alpha-1} \sin(\tau + (1+\alpha+\tau)\theta) \\
&\leq -2 r^{\alpha-1} \tau \sin \tau.
\end{aligned}$$

Together with

$$\Delta v_2 = \alpha(1+\alpha)y_2^{\alpha-1},$$

we obtain

$$\Delta v \leq -c_2\alpha(1+\alpha)y_2^{\alpha-1} < 0. \quad (4.21)$$

At the corner $S_0 = (0, 0)$, we assume $\varphi(0, 0) = 0$ and $g_0(0) = g_S(0) = g'_0(0) = g'_S(0) = 0$. Otherwise, we can replace φ with $\varphi - g_0(0) - g'_0(0)y_1 - (g'_S(0) - g'_0(0)f'(0))y_2$. Correspondingly, we have $g_0(0) = g_S(0) = g'_0(0) = g'_S(0) = 0$. Hence, the following inequalities hold:

$$\begin{aligned}
|g_0(y_1)| &\leq \|g_0\|_{1,\alpha;B_0} y_1^{1+\alpha} \leq G_b r^{1+\alpha}, \\
|g_S(y_2)| &\leq \|g_S\|_{1,\alpha;(0,M)} y_2^{1+\alpha} \leq G_b r^{1+\alpha}.
\end{aligned}$$

We fix a radius r_0 and let $B_{r_0}^+ = B_{r_0}(0) \cap R_f^Q$. The estimate Δv with the conditions in (4.15) yield

$$\begin{aligned}
Lv &= \Delta v + (L - \Delta)v \\
&\leq -c_2\alpha(1+\alpha)y_2^{\alpha-1} + \sum_{i,j=1,2} (a_{ij} - \delta_{ij})v_{y_i y_j} + \sum_{i,j=1,2} (a_{ij})_{x_i} v_{x_j} \\
&\leq -c_2\alpha(1+\alpha)y_2^{\alpha-1} + c_2\bar{\delta}y_2^{\alpha-1} + c_2\bar{\delta}y_2^{\alpha-1}r^\alpha \\
&\leq \sum_{i=1,2} (b_i)_{y_i}
\end{aligned}$$

for sufficiently large c_2 and small $\bar{\delta}$ in $B_{r_0}^+$.

Let $c_1 := \tilde{c}_1(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)})$. We analyze the value of v on the boundary near the corner $S_0 = (0, 0)$ to find

$$v|_{y_2=0} = \tilde{c}_1(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}) y_1^{\alpha+1} \sin \tau \geq g_0$$

for sufficiently large $\tilde{c}_1$. Also, we have

$$v|_S \geq \frac{1}{2} \tilde{c}_1 G_b r^{1+\alpha} \sin \tau \geq g_S$$

for large $\tilde{c}_1$. Observing (4.19), we have

$$v|_{r=r_0} \geq \frac{1}{2} \tilde{c}_1(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}) r_0^{1+\alpha} \geq \varphi|_{r=r_0}.$$

Therefore, we conclude

$$v|_{\partial B_{r_0}^+} \geq \varphi|_{\partial B_{r_0}^+}.$$

By the Comparison Principle, we obtain

$$\varphi \leq v \leq C(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}) r^{1+\alpha} \quad \text{in } B_{r_0}^+.$$

In the same way, we can show $\varphi \geq -v$ in $B_{r_0}^+$.

Therefore, we have

$$|\varphi| \leq C(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}) r^{1+\alpha}. \quad (4.22)$$

With estimate (4.22), we can use the scaling technique to obtain the $C^{1,\alpha}$ estimate up to the corner. More precisely, for any point $P_0 \in B_{r_0/2}^+$ with polar coordinates (d_0, θ_0) , we consider two cases for different values of θ_0 .

Case 1. $\theta_0 \in [\pi/6, \pi/3]$. Let $B_1 = B_{d_0/6}(P_0)$ and $B_2 = B_{d_0/3}(P_0)$. Then $B_1 \subset B_2 \subset B_{r_0}^+$. By the Schauder interior estimates, we have

$$\|\varphi\|_{1,\alpha;B_2}^{(0)} \leq C\|\varphi\|_{0,0;B_2},$$

where C is a constant independent of d_0 , and the weight of the norm is up to ∂B_2 . Therefore, by (4.22), we conclude

$$\|\varphi\|_{1,\alpha;B_1} \leq C(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}). \quad (4.23)$$

Case 2. $\theta_0 > \pi/3$ or $\theta_0 < \pi/6$. Let $B_3 = R_f^Q \cap B_{2d_0/3}(P_0)$. By the Schauder boundary estimate, we have

$$\|\varphi\|_{1,\alpha;B_3}^{(0)} \leq C(G_b + \|\varphi\|_{0,0} + \sum_{i=1,2} \|b_i\|_{0,\alpha}) \leq C(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}).$$

Combining Case 1 with Case 2 yields the corner estimate:

$$\|\varphi\|_{1,\alpha;B_{r_0/2}^+} \leq C(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}). \quad (4.24)$$

The other three corners can be treated in the same way. Away from the four corners, we have the standard Schauder boundary and interior estimates. We conclude the $C^{1,\alpha}$ estimate:

$$\|\varphi\|_{1,\alpha;R_f^Q} \leq C(G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha;R_f^Q}^{(-\alpha;B_{0,1})}). \quad (4.25)$$

We differentiate equation (4.9) with respect to y_k for $k = 1, 2$ and obtain

$$\sum_{i,j=1,2} (a_{ij}(\varphi_{y_k})_{y_i})_{y_j} = \sum_{i,j=1,2} ((b_i)_{y_k} - (a_{ij})_{y_k} \varphi_{y_j})_{y_i} =: \tilde{b}_k. \quad (4.26)$$

Let $P_0 = (y_1^0, y_2^0) \in R_f^Q$. We consider two cases. In the first case, P_0 is away from the boundary $\mathcal{F}$, we use the Schauder interior estimates. In the second case, for P_0 close to the shock $\mathcal{F}$, we use the Schauder boundary estimate with oblique boundary condition.

Case 1. For the polar angle $\theta_0 < \pi/3$, let $B_1 = B_{y_2^0/4}(P_0)$ and $B_2 = B_{y_2^0/2}(P_0)$. Denote φ_{y_k} by u . Then equation (4.26) is an elliptic equation for u . By the Schauder estimate and using (4.15) and (4.25), we have

$$\begin{aligned} \|u\|_{1,\alpha;B_1} &\leq C \left(\|u\|_{0,0;B_2} + \sum_{i,j,k=1,2} \|(b_i)_{y_k} - (a_{ij})_{y_k} \varphi_{y_j}\|_{0,\alpha;B_2} \right) \\ &\leq C \left(G_b + \sum_{i,j=1,2} (\|b_i\|_{1,\alpha}^{(-\alpha)} + \|b_i\|_{1,\alpha;B_2} + \|a_{ij}\|_{1,\alpha;B_2} \|\varphi_{y_j}\|_{0,\alpha;B_2}) \right) \\ &\leq C |y_2^0|^{-1} (G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}). \end{aligned} \quad (4.27)$$

Case 2. $\theta_0 \geq \pi/3$. This is for the point P_0 close to the shock $\mathcal{F}$. Let $u = \varphi_{y_1}$. We have the elliptic equation (4.26) for u when $k = 1$.

We define $B_1 = B_{5y_1^0/4}(P_0) \cap R_f^Q$ and $B_2 = B_{3y_1^0/2}(P_0) \cap R_f^Q$. Then $B_1 \subset B_2 \subset R_f^Q$. Now we need to derive an oblique boundary condition for u .

Note that $\varphi(f(y_2), y_2) = g_S(y_2)$. Let $D_\tau = f'(y_2)\partial_{y_1} + \partial_{y_2}$. Therefore, we have

$$D_\tau^2 \varphi = f'^2 \varphi_{y_1 y_1} + 2f' \varphi_{y_1 y_2} + \varphi_{y_2 y_2} + f'' \varphi_{y_1} = g_S''. \quad (4.28)$$

Equation (4.9) yields

$$\varphi_{y_2 y_2} = (\bar{g} - a_{11} \varphi_{y_1 y_1} - 2a_{12} \varphi_{y_1 y_2}) / a_{22},$$

where $\bar{g} = \sum_{i,j=1,2} ((b_i)_{y_i} - (a_{ij})_{y_j} \varphi_{y_i})$. Eliminating $\varphi_{y_2 y_2}$ in (4.28) gives

$$\nu_1 u_{y_1} + \nu_2 u_{y_2} = \nu_3 \quad \text{on the shock } S, \quad (4.29)$$

where

$$(\nu_1, \nu_2) = (f'^2 - \frac{a_{11}}{a_{22}}, 2f' - \frac{2a_{12}}{a_{22}}) \in C^\alpha(R_f^Q; \mathbb{R}^2), \quad \nu_3 = g_S'' - f'' \varphi_{y_1} - \frac{\bar{g}}{a_{22}} \in C_{(1;B_{0,1})}^{0,\alpha}(R_f^Q).$$

Since $\nu_1 < -\frac{\epsilon_1}{2\epsilon_2}$, condition (4.29) is an oblique boundary condition. The boundary estimate in B_2 results in

$$\begin{aligned} \|u\|_{1,\alpha;B_1} &\leq C (\|u\|_{0,0;B_2} + \|\nu_3\|_{0,\alpha;B_2} + \|\tilde{b}\|_{0,\alpha;B_2}) \\ &\leq C |y_2^0|^{-1} (G_b + \sum_{i=1,2} \|b_i\|_{1,\alpha}^{(-\alpha)}), \end{aligned}$$

where $\tilde{b}$ is defined in (4.26). Once we obtain the above estimate for $u = \varphi_{y_1}$, by equation (4.9) itself, we obtain the same estimate for φ_{y_2} . Together with estimate (4.27), we obtain estimate (4.17).

The uniqueness follows from estimate (4.17) and the linearity of the problem. This completes the proof of Lemma 4.2. $\square$

Now we come back to the proof of Lemma 4.1.

Proof of Lemma 4.1. By the method we find $\phi_\infty = \phi_\infty(y_2)$ (cf. (3.47)), we know that $\phi_\infty = \phi_\infty(y_2)$ satisfies equation (4.6), that is,

$$\sum_{i=1,2} (N^i(A(y_2), B(y_2), 0, \phi'_\infty(y_2)))_{y_i} = 0. \quad (4.30)$$

Taking the difference of (4.6) and (4.30), we have

$$\sum_{i,j=1,2} (a_{ij}^\phi (\phi - \phi_\infty)_{y_i})_{y_j} = 0, \quad (4.31)$$

where

$$a_{ij}^\phi = \int_0^1 N_{\phi_{y_j}}^i(A, B, \nabla(\phi_\infty + s(\phi - \phi_\infty))) ds, \quad i, j = 1, 2. \quad (4.32)$$

To solve the nonlinear equation (4.6), we construct a map $T : \Sigma \rightarrow \Sigma$, where

$$\Sigma = \{\phi : \|\phi - \phi_\infty\|_{2,\alpha;R_f^Q}^{(-1-\alpha)} \leq \delta\}.$$

By proving that T is a contraction map, we establish the existence and uniqueness of the solution of (4.6).

We first define the map T . For any given $\phi \in \Sigma$, we solve the linearized equation

$$\sum_{i,j=1,2} (a_{ij}^\phi (\tilde{\phi} - \phi_\infty)_{y_i})_{y_j} = 0 \quad (4.33)$$

with boundary condition (3.46), (4.3), and (3.37). We define the solution $\tilde{\phi} := T\phi$. Now we need to prove that

- (i) T is well-defined and maps Σ to itself;
- (ii) T is a contraction map.

For a given ϕ , let $a_{ij} := a_{ij}^\phi$. We know that $\tilde{\phi} - \phi_\infty$ satisfies the linear equation (4.9) in Lemma 4.2. In order to apply Lemma 4.2, we need to verify conditions (4.12)–(4.16). Since $\phi \in \Sigma$, we have

$$\|a_{ij} - e_i \delta_{ij}\|_{1,\alpha}^{(-\alpha)} \leq C_1 \delta,$$

where

$$e_1 = u_{1+}^0, \quad e_2 = \frac{(c_+^0)^2 \rho_+^0 (u_{1+}^0)^3}{(c_+^0)^2 - u_{1+}^0{}^2}$$

are obtained through (3.33) and (3.35) respectively, by plugging the background state U_+^0 . For $\delta < \bar{\delta}/C_1$, condition (4.15) in Lemma 4.2 is satisfied. Conditions (4.14) and (4.16) can also be verified. By Lemma 4.2, we can uniquely solve $\tilde{\phi}$ and obtain the following estimate:

$$\begin{aligned} \|\tilde{\phi} - \phi_\infty\|_{2,\alpha}^{(-1-\alpha)} &\leq C \left(\|\phi - \phi_\infty\|_{2,\alpha}^{(-1-\alpha)} + \sum_{i=0,1} \|\zeta_i - i\|_{1,\alpha} + \|h_Q - \phi_\infty\|_{2,\alpha}^{(-1-\alpha)} \right) \\ &\leq C(\varepsilon + \delta^2). \end{aligned}$$

In the last inequality, we use the fact that

$$\phi_\infty - \frac{y_2}{M} = O(|U_- - U_-^0| + |f'|^2),$$

which is obtained by (3.45), (3.48), and (3.49). As long as $\delta < \delta_0 \equiv \min(\frac{\bar{\delta}}{C_1}, \frac{1}{2C})$ and $\varepsilon < \frac{\delta}{2C}$, we have $\tilde{\phi} \in \Sigma$. This shows that T is a map from Σ to itself.

Now we prove that T is a contraction map. Let $\phi_1, \phi_2 \in \Sigma$. Let $\tilde{\phi}_i := T\phi_i$ for $i = 1, 2$. By definition of T , we have

$$\sum_{i,j=1,2} (a_{ij}^{\phi_k} (\tilde{\phi}_k - \phi_\infty)_{y_i})_{y_j} = 0, \quad k = 1, 2.$$

Taking the difference between the above two equations and letting $u := \tilde{\phi}_1 - \tilde{\phi}_2$, we find

$$\sum_{i,j=1,2} (a_{ij}^{\phi_1} u_{y_i})_{y_j} = - \sum_{i,j=1,2} ((a_{ij}^{\phi_1} - a_{ij}^{\phi_2}) (\tilde{\phi}_2 - \phi_\infty)_{y_i})_{y_j}, \quad (4.34)$$

with boundary condition $u|_{\partial R_f^Q} = 0$. Again, by Lemma 4.2, we have

$$\|u\|_{2,\alpha}^{(-1-\alpha)} \leq C\delta \|a_{ij}^{\phi_1} - a_{ij}^{\phi_2}\|_{1,\alpha}^{(-\alpha)}. \quad (4.35)$$

Define

$$M_{ij}(y_2, s, \mathbf{r}) := N_{\phi_{y_j}}^i(A(y_2), B(y_2), (1-s)(0, \phi_\infty') + s\mathbf{r}).$$

Hence, by definition of a_{ij}^ϕ in (4.32), we have

$$a_{ij}^{\phi_k} = \int_0^1 M_{ij}(y_2, s, \nabla \phi_k) ds. \quad (4.36)$$

Therefore, we obtain

$$a_{ij}^{\phi_1} - a_{ij}^{\phi_2} = \int_0^1 \int_0^1 \sum_{k=1,2} (M_{ij})_{r_k}(y_2, s, \nabla \phi_1 + \mu \nabla(\phi_1 - \phi_2))(\phi_1 - \phi_2)_{y_k} d\mu ds. \quad (4.37)$$

Then we have

$$\|a_{ij}^{\phi_1} - a_{ij}^{\phi_2}\|_{1+\alpha}^{(-\alpha)} \leq C \|\phi_1 - \phi_2\|_{2,\alpha}^{(-1-\alpha)}. \quad (4.38)$$

From (4.35)–(4.38), we obtain

$$\|\tilde{\phi}_1 - \tilde{\phi}_2\|_{2,\alpha}^{(-1-\alpha)} \leq C\delta \|\phi_1 - \phi_2\|_{2,\alpha}^{(-1-\alpha)},$$

which implies that T is a contraction map for sufficiently small $\delta < \delta_0$.

In terms of uniqueness, we consider two solutions ϕ_1 and ϕ_2 satisfying estimate (4.8). It is obvious that they are both fixed points of T . Since T is a contraction map that admits a unique fixed point, we know that $\phi_1 = \phi_2$. This completes the proof of Lemma 4.1.

5. FIXED BOUNDARY PROBLEMS IN INFINITE NOZZLES

In this section, we study the solution in the unbounded domain

$$R_f = \{y : 0 < y_2 < M, y_1 > f(y_2)\}. \quad (5.1)$$

We slightly change the boundary condition of **Problem IV** to form **Problem V** in the unbounded domain.

Problem V. For given incoming flow ϕ_- with

$$\left\| \phi_- - \frac{y_2}{M_0} \right\|_{2,\alpha;R_-} \leq \varepsilon$$

and fixed shock front $\mathcal{F} = \{y_1 = f(y_2)\}$, find a solution ϕ of the boundary value problem for equation (4.6) in R_f with the boundary conditions:

$$\phi|_{\mathcal{F}} = \phi_-, \quad \phi|_{\mathcal{B}_{0,1}} = \zeta_{0,1}.$$

Then we have

Lemma 5.1. *Let the shock function $f = f(y_2)$ satisfy*

$$\|f\|_{2,\alpha;(0,M)}^{(-1-\alpha)} \leq \delta$$

*for some small constant $\delta < \delta_0$, where δ_0 is given in Lemma 4.1. Then there exists $\varepsilon_0 > 0$ such that, when $\varepsilon \in (0, \varepsilon_0)$, there exists a solution ϕ of **Problem V** with the estimate*

$$\|\phi - \phi_\infty\|_{2,\alpha;R_f}^{(-1-\alpha;\mathcal{B}_{0,1})} \leq C(\varepsilon + \delta^2). \quad (5.2)$$

Moreover the following asymptotic behavior holds:

$$\lim_{Q \rightarrow \infty} \|\phi - \phi_\infty\|_{2,\alpha;R_f \setminus R_f^Q}^{(-1-\alpha)} = 0. \quad (5.3)$$

The solution is unique in the class of ϕ satisfying (5.2).

Proof. We have estimate (4.8) for each solution ϕ_Q in R_f^Q with C independent of Q . To obtain the solution for **Problem V**, we simply let $Q \rightarrow \infty$. By choosing a proper subsequence $\{\phi_{Q_k}\} \subset \{\phi_Q\}$, ϕ_{Q_k} converges to a function ϕ in the C^0 norm on any compact subset of $\overline{R_f}$ and in the C^2 norm on any compact subset of R_f . The function ϕ is a solution of **Problem V** with estimate (5.2) directly from (4.8).

In terms of uniqueness, we need to investigate first the limiting behavior of ϕ as $y_1 \rightarrow \infty$. Define $\varphi := \phi - \phi_\infty$. Then φ satisfies the following equation

$$\sum_{i,j=1,2} (a_{ij}^\phi \varphi_{y_i})_{y_j} = 0, \quad (5.4)$$

where a_{ij}^ϕ is defined in (4.32).

We multiply equation (5.4) by φ and integrate over the finite domain R_f^Q . By integration by parts, we have

$$\iint_{R_f^Q} \sum_{i,j=1,2} a_{ij}^\phi \varphi_{y_i} \varphi_{y_j} d\mathbf{y} = \int_{\partial R_f^Q} \sum_{i,j=1,2} a_{ij}^\phi \varphi_{y_i} \varphi \nu_j ds, \quad (5.5)$$

where ν_i is the i -th component of the outer normal $\nu = (\nu_1, \nu_2)$, and ds is the infinitesimal of arch length along the boundary of R_f^Q . By ellipticity of (a_{ij}^ϕ) , we know

$$\iint_{R_f^Q} |\nabla \varphi|^2 d\mathbf{y} \leq C \iint_{R_f^Q} \sum_{i,j=1,2} a_{ij}^\phi \varphi_{y_i} \varphi_{y_j} d\mathbf{y}. \quad (5.6)$$

Assumption (2.11) implies that

$$|\varphi(y_1, iM)| = |\zeta_i - i| \leq \frac{\varepsilon}{(1 + y_1)^\beta}, \quad i = 0, 1. \quad (5.7)$$

Together with the boundedness of $\nabla \varphi$, we conclude

$$\int_{\partial R_f^Q} \sum_{i,j=1,2} a_{ij}^\phi \varphi_{y_i} \varphi \nu_j ds \leq C. \quad (5.8)$$

Hence, from (5.5)–(5.6) and (5.8), we obtain

$$\iint_{R_f^Q} |\nabla \varphi|^2 d\mathbf{y} \leq C,$$

where C is independent of Q . Therefore, letting $Q \rightarrow \infty$, we have

$$\iint_{R_f} |\nabla \varphi|^2 d\mathbf{y} \leq C. \quad (5.9)$$

Let $D_Q = (Q - 2, Q + 2) \times (0, M)$. Then we have

$$\lim_{Q \rightarrow \infty} \iint_{D_Q} |\nabla \varphi|^2 d\mathbf{y} = 0. \quad (5.10)$$

Since

$$\varphi(\mathbf{y}) = \zeta_0(y_1) + \int_0^{y_2} \varphi_{y_2}(y_1, s) ds,$$

we obtain

$$\varphi^2 \leq 2\zeta_0^2 + 2M \int_0^M (\varphi_{y_2})^2(y_1, s) ds.$$

Hence,

$$\iint_{D_Q} \varphi^2 d\mathbf{y} \leq 2M \int_{Q-2}^{Q+2} \zeta_0^2(y_1) dy_1 + 2M^2 \iint_{D_Q} |\nabla \varphi|^2 d\mathbf{y}.$$

By (5.10), we conclude

$$\lim_{Q \rightarrow \infty} \iint_{D_Q} \varphi^2 d\mathbf{y} = 0. \quad (5.11)$$

We then use the local estimates of φ to control the L^∞ -norm of φ . From Theorem 8.25 in [16], we find that, for any $\mathbf{y} \in \{Q\} \times (0, M)$,

$$\|\varphi\|_{L^\infty(B_1(\mathbf{y}))} \leq C(\|\varphi\|_{L^\infty(B_2(\mathbf{y}) \cap \mathcal{B}_{0,1})} + \|\varphi\|_{L^2(B_2(\mathbf{y}))}). \quad (5.12)$$

Estimates (5.11) and (5.12) imply that

$$\lim_{Q \rightarrow \infty} \|\phi - \phi_\infty\|_{L^\infty(R_f \cap \{y_1 > Q\})} = 0.$$

Once we have the above decay in the L^∞ -norm, the asymptotic behavior (5.3) immediately follows by the Schauder interior estimates similar to Lemma 4.2 in the domain $(Q-1, Q+1) \times (0, M)$.

To obtain the uniqueness, we assume that there are two solutions ϕ_1 and ϕ_2 satisfying equation (3.27). By taking the difference of the two equations, we derive an elliptic equation for $\phi_1 - \phi_2$. By the asymptotic behavior of ϕ_1 and ϕ_2 , we know that, for any small $\tau > 0$, there exists Q , depending on τ , such that $|\phi_1(Q, y_2) - \phi_2(Q, y_2)| \leq \tau$. Other three boundary conditions for $\phi_1 - \phi_2$ are 0. Hence, the Maximum Principle implies that $\|\phi_1 - \phi_2\|_{C^0(R_f^Q)} \leq \tau$. Letting τ tend to 0 yields the uniqueness. $\square$

6. FREE BOUNDARY PROBLEMS IN INFINITE NOZZLES

Once we obtain the unique solution for the fixed shock in the infinite nozzle, we can update the location of the shock front by condition (3.8) and construct a map for the shock functions. The fixed point of this map is the real shock front. The process is the following.

Define the set for the shock iteration:

$$\mathcal{H} = \{f : \|f\|_{2,\alpha;(0,M)}^{(-1-\alpha)} \leq \delta\}. \quad (6.1)$$

For any $f \in \mathcal{H}$, we solve the fixed boundary problem, **Problem V**. We can express U in terms of $\nabla\phi$ by (3.25). Then we use the Rankine-Hugoniot condition (3.8) to find a new shock $\tilde{f}$:

$$\tilde{f}'(y_2) = \frac{[u_2]}{[p]}(f(y_2), y_2) \quad (6.2)$$

with $\tilde{f}(0) = 0$.

We define the map $\mathcal{T}$ by $\tilde{f} = \mathcal{T}f$. We need to prove that $\mathcal{T}$ maps from $\mathcal{H}$ into itself and is also a contraction map.

First, by (6.2), we have

$$\|\tilde{f}\|_{2,\alpha}^{(-1-\alpha)} \leq C(\|U_- - U_-^0\|_{1,\alpha;R_1} + \|U - U_+^0\|_{1,\alpha;R_f}^{(-\alpha)}).$$

Estimate (5.2) implies

$$\|U - U_+^0\|_{1,\alpha;R_f}^{(-\alpha)} \leq C\left\|\phi - \frac{y_2}{M_0}\right\|_{2,\alpha;R_f}^{(-1-\alpha)} \leq C(\varepsilon + \delta^2).$$

Therefore, we obtain

$$\|\tilde{f}\|_{2,\alpha}^{(-1-\alpha)} \leq C(\varepsilon + \delta^2) \leq \delta, \quad (6.3)$$

provided that $\delta < \delta_0$ and $\varepsilon < \frac{\delta}{2C}$. Hence, $\mathcal{T}$ is a map from $\mathcal{H}$ into itself.

Next, we prove that $\mathcal{T}$ is a contraction map. For any two shock functions $f_1, f_2 \in \mathcal{H}$, we solve **Problem V** to obtain the corresponding solutions ϕ_1, ϕ_2 , respectively. Let $\tilde{f}_i = \mathcal{T}f_i$ for $i = 1, 2$.

In order to compare the two solutions ϕ_1 and ϕ_2 , we map their own domains R_{f_1} and R_{f_2} to R_0 defined by

$$R_0 = \{\bar{y} : \bar{y}_1 > 0, 0 < \bar{y}_2 < M\}.$$

The coordinate transformations $\sigma_i : R_0 \rightarrow R_{f_i}$, $i = 1, 2$, are defined by

$$\mathbf{y} = \sigma_i(\bar{\mathbf{y}}) = (\bar{y}_1 + \eta(\bar{y}_1)f_i(\bar{y}_2), \bar{y}_2), \quad (6.4)$$

where η is a smooth function satisfies

$$\eta(s) = \begin{cases} 0, & |s| > 1/2, \\ 1, & |s| < 1/4, \end{cases} \quad |\eta|_{C^2} \leq 10. \quad (6.5)$$

A simple calculation gives

$$\frac{\partial y_1}{\partial \bar{y}_1} = 1 + \eta' f_i, \quad \frac{\partial y_1}{\partial \bar{y}_2} = \eta f'_i, \quad \frac{\partial y_2}{\partial \bar{y}_1} = 0, \quad \frac{\partial y_2}{\partial \bar{y}_2} = 1.$$

Define $\bar{\phi}_i := \phi_i \circ \sigma_i$. When we change the coordinates from $\mathbf{y}$ to $\bar{\mathbf{y}}$ by σ_k^{-1} , equation (3.27) becomes

$$\sum_{i=1,2} (\bar{N}^i(\bar{\mathbf{y}}, A_k, \nabla_{\bar{\mathbf{y}}} \bar{\phi}_k, f_k, f'_k))_{\bar{y}_i} = 0, \quad (6.6)$$

where

$$\bar{N}^i(\bar{\mathbf{y}}, A_k, \nabla_{\bar{\mathbf{y}}} \bar{\phi}_k, f_k, f'_k) = \sum_{j=1,2} N^j(A_k, B, (\nabla_{\mathbf{y}} \phi_k) \circ \sigma_k) \frac{\partial \bar{y}_i}{\partial y_j} \Big| \frac{\partial \mathbf{y}}{\partial \bar{\mathbf{y}}} \Big|.$$

Remark 6.1. For a different fixed shock $y_1 = f(y_2)$, the coefficient $A(y_2)$ derived in (3.44) is different, depending on the shock location $y_1 = f(y_2)$. We denote A_i the coefficient for the corresponding shock f_i . Also, the asymptotic behavior of ϕ_i depends on f_i and is denoted by $\phi_\infty^{(i)}$.

For notational convenience, for a general shock $y_1 = f(y_2)$, the coordinate transformation σ , the solution ϕ in the $\mathbf{y}$ -coordinates, and $\bar{\phi}$ in the $\bar{\mathbf{y}}$ -coordinates, we set

$$\bar{\mathbf{t}} = (\bar{t}_1, \bar{t}_2) = \nabla_{\mathbf{y}} \phi \circ \sigma, \quad \mu = (\mu_1, \mu_2) = \nabla_{\bar{\mathbf{y}}} \bar{\phi}.$$

Hence, we have the relation

$$\bar{\mathbf{t}} = \left(\frac{\mu_1}{1 + \eta' f}, \mu_2 - \frac{\mu_1 \eta f'}{1 + \eta' f} \right).$$

More explicit expressions for $\bar{N}^1$ and $\bar{N}^2$ are

$$\bar{N}^1(\bar{\mathbf{y}}, A, \mu, f, f') = N^1(A, B, \bar{\mathbf{t}}) + N^2(A, B, \bar{\mathbf{t}})(-\eta f'), \quad (6.7)$$

$$\bar{N}^2(\bar{\mathbf{y}}, A, \mu, f, f') = N^2(A, B, \bar{\mathbf{t}})(1 + \eta' f). \quad (6.8)$$

Set $\xi = (A, \mu, f, f')$ and $\xi_i = (A_i, \nabla_{\bar{\mathbf{y}}} \bar{\phi}_i, f_i, f'_i)$. Taking the difference of equations (6.6) for $k = 1, 2$ yields

$$\sum_{i=1,2} \left(\int_0^1 \frac{\partial \bar{N}^i}{\partial \xi}(\bar{\mathbf{y}}, \xi_2 + s(\xi_1 - \xi_2)) ds (\xi_1 - \xi_2) \right)_{\bar{y}_i} = 0. \quad (6.9)$$

Set

$$\begin{aligned} \bar{a}_{ij} &= \int_0^1 \frac{\partial \bar{N}^i}{\partial \mu_j}(\bar{\mathbf{y}}, \xi_2 + s(\xi_1 - \xi_2)) ds, & \bar{b}_i &= \int_0^1 \frac{\partial \bar{N}^i}{\partial A}(\bar{\mathbf{y}}, \xi_2 + s(\xi_1 - \xi_2)) ds, \\ \bar{c}_i &= \int_0^1 \frac{\partial \bar{N}^i}{\partial f}(\bar{\mathbf{y}}, \xi_2 + s(\xi_1 - \xi_2)) ds, & \bar{d}_i &= \int_0^1 \frac{\partial \bar{N}^i}{\partial f'}(\bar{\mathbf{y}}, \xi_2 + s(\xi_1 - \xi_2)) ds. \end{aligned}$$

Then we rewrite (6.9) into

$$\sum_{i,j=1,2} (\bar{a}_{ij} \bar{u}_{\bar{y}_i})_{\bar{y}_j} = \sum_{j=1,2} (\tilde{b}_j)_{\bar{y}_j}, \quad (6.10)$$

where

$$\bar{u} = \bar{\phi}_1 - \bar{\phi}_2, \quad \tilde{b}_i = -\bar{b}_i(A_1 - A_2) - \bar{c}_i(f_1 - f_2) - \bar{d}_i(f'_1 - f'_2).$$

From the expressions of $\bar{N}^i$, it is easy to check that $(\bar{a}_{ij})$ satisfies the same ellipticity condition as in (4.16). Also, we have

$$\|\bar{b}_i\|_{1,\alpha}^{(-\alpha)} \leq C, \quad \|(\bar{c}_i, \bar{d}_i)\|_{1,\alpha}^{(-\alpha)} \leq C(\varepsilon + \delta).$$

We investigate the boundary conditions of $\bar{u}$. On the shock $\bar{y}_1 = 0$, we have

$$\begin{aligned}\bar{u}(0, \bar{y}_2) &= \phi_-(f_1(\bar{y}_2), \bar{y}_2) - \phi_-(f_2(\bar{y}_2), \bar{y}_2) \\ &= \int_0^1 \frac{\partial \phi_-}{\partial y_1}(f_2 + s(f_1 - f_2)) ds (f_1 - f_2).\end{aligned}\quad (6.11)$$

On the two walls $\mathcal{B}_{0,1}$, the condition is

$$\begin{aligned}\bar{u}(\bar{y}_1, iM) &= \zeta_i(\bar{y}_1 + \eta(\bar{y}_1)f_1(iM)) - \zeta_i(\bar{y}_1 + \eta(\bar{y}_1)f_2(iM)) \\ &= \int_0^1 \zeta'_i(\bar{y}_1 + s\eta(f_1 - f_2) + \eta f_2) ds \eta(f_1 - f_2).\end{aligned}\quad (6.12)$$

We also truncate the domain R_0 with right end $\bar{y}_1 = Q$ and analyze the condition on $\bar{y}_1 = Q$. By the asymptotic behavior of ϕ_i , we know that, for any given small constant $\tau > 0$, we can choose large Q such that

$$\sum_{i=1,2} \|\phi_i(Q, \cdot) - \phi_\infty^{(i)}\|_{2,\alpha}^{(-1-\alpha)} \leq \tau.$$

From the derivation of ϕ_∞ in (3.47)–(3.48), we also have

$$\|\phi_\infty^{(1)} - \phi_\infty^{(2)}\|_{2,\alpha}^{(-1-\alpha)} \leq C\|A_1 - A_2\|_{1,\alpha}^{(-\alpha)}.$$

On the other hand, from (3.45), we have

$$\begin{aligned}\|A_1 - A_2\|_{1,\alpha}^{(-\alpha)} &\leq C(\|DU_-\|_{1,\alpha;R_-}\|f_1 - f_2\|_{1,\alpha} + \delta\|f'_1 - f'_2\|_{1,\alpha}^{(-\alpha)}) \\ &\leq C(\varepsilon + \delta)\|f_1 - f_2\|_{2,\alpha}^{(-1-\alpha)}.\end{aligned}$$

Therefore, we obtain

$$\|\bar{u}(Q, \cdot)\|_{2,\alpha}^{(-1-\alpha)} \leq \tau + C(\varepsilon + \delta)\|f_1 - f_2\|_{2,\alpha}^{(-1-\alpha)}. \quad (6.13)$$

With the estimates on the boundary of R_0^Q , we apply Lemma 4.2 to obtain

$$\|\bar{u}\|_{2,\alpha;R_0^Q}^{(-1-\alpha)} \leq C\left(\tau + (\varepsilon + \delta)\|f_1 - f_2\|_{2,\alpha}^{(-1-\alpha)}\right). \quad (6.14)$$

Letting $\tau \rightarrow 0$ and $Q \rightarrow \infty$, we obtain the estimate:

$$\|\bar{\phi}_1 - \bar{\phi}_2\|_{2,\alpha;R_0}^{(-1-\alpha)} \leq C(\varepsilon + \delta)\|f_1 - f_2\|_{2,\alpha}^{(-1-\alpha)}. \quad (6.15)$$

The method that we update the new shock $\tilde{f}_1, \tilde{f}_2$ in (6.2) indicates that

$$\|\tilde{f}_1 - \tilde{f}_2\|_{2,\alpha}^{(-1-\alpha)} \leq C\left((\varepsilon + \delta)\|f_1 - f_2\|_{2,\alpha}^{(-1-\alpha)} + \|\bar{\phi}_1 - \bar{\phi}_2\|_{2,\alpha;R_0}^{(-1-\alpha)}\right). \quad (6.16)$$

Estimates (6.15)–(6.16) immediately imply

$$\|\tilde{f}_1 - \tilde{f}_2\|_{2,\alpha}^{(-1-\alpha)} \leq \frac{1}{2}\|f_1 - f_2\|_{2,\alpha}^{(-1-\alpha)} \quad (6.17)$$

for sufficiently small $\varepsilon, \delta > 0$. This is equivalent to saying that $\mathcal{T}$ is a contraction map. There exists a unique fixed point f for $\mathcal{T}$, which is the real shock for **Problem III**. Then we fix this shock f and solve a fixed boundary problem, **Problem V**, to obtain ϕ . Through $\nabla\phi$, together with the quantities A and B , we can find the solution U .

Estimates (3.18) and (3.19) are obtained by letting $\delta = 2C\varepsilon$, where C is the same as in estimate (5.2) in Lemma 5.1.

For uniqueness, we assume two solutions (U_1, f_1) and (U_2, f_2) satisfying condition (3.18). It is easy to see that f_1 and f_2 are two fixed points of $\mathcal{T}$. By contraction of $\mathcal{T}$, we conclude $f_1 = f_2$. Then, Lemma 5.1 gives the same potentials $\phi_1 = \phi_2$. Since U_i can be expressed by $\nabla\phi_i$ for $i = 1, 2$, U_1 and U_2 have to be equal. This concludes the uniqueness.

With these, the proof of Theorem 2.2 is completed.

7. ASYMPTOTIC BEHAVIOR OF SOLUTIONS AT INFINITY

After we obtain the solution of the Euler equations, the quantities p_∞ , $\phi_\infty(y_2)$, and $A(y_2)$ are determined by (3.47)–(3.49). They uniquely define the asymptotic limit U_∞ of U at the infinity, although U_∞ is not given explicitly.

Assume further that the nozzle walls satisfy the decay condition:

$$\|\zeta_i - i\|_{C^{1,\alpha}(x_1,\infty)} \leq \frac{\varepsilon}{(1 + |x_1|)^\beta}, \quad (7.1)$$

for $x_1 > -1$, $i = 0, 1$. Then we can obtain the strong convergence of U to U_∞ with algebraic rate $x_1^{-\beta}$.

Theorem 7.1. *Under assumption (7.1), the solution U for **Problem I** converges to its asymptotic limit U_∞ as $x_1 \rightarrow \infty$ with the following estimate:*

$$\|U - U_\infty\|_{1,\alpha;\Omega_X}^{(-\alpha;\Gamma_{0,1})} \leq \frac{C\varepsilon}{(1 + |X|)^\beta}, \quad (7.2)$$

where $\Omega_X = \Omega \cap \{x_1 > X\}$.

Proof. To obtain estimate (7.2), it suffices to prove

$$\|\phi - \phi_\infty\|_{2,\alpha;R_Y}^{(-1-\alpha;\mathcal{B}_{0,1})} \leq \frac{C\varepsilon}{(1 + |Y|)^\beta}, \quad (7.3)$$

where $R_Y = (Y, \infty) \times (0, M)$, ϕ is the potential function defined in (3.20) and satisfies the nonlinear equation (4.31). The coefficients a_{ij}^ϕ , $i, j = 1, 2$, satisfy condition (4.15). We first use a comparison function to obtain the L^∞ estimate for $\phi - \phi_\infty$, and then the standard Schauder estimates lead to (7.3). The method is similar to that in Lemma 4.2.

To control $|\phi - \phi_\infty|$, we first estimate the solution of (4.31) in R_f^Q , denoted by ϕ_Q , and then let $Q \rightarrow \infty$. We use the following comparison function

$$v_3 = \frac{y_2^\alpha + (M - y_2)^\alpha}{(C_0 + y_1)^\beta}, \quad (7.4)$$

where C_0 is chosen large enough, depending only on the width of the nozzle M and parameters α, β, δ . It is straightforward to check

$$\sum_{i,j=1,2} (a_{ij}^{\phi_Q}(v_3)_{y_i})_{y_j} \leq -\frac{\alpha(1-\alpha)}{2}(C_0 + y_1)^{-\beta}(y_2^{\alpha-2} + (M - y_2)^{\alpha-2}) \leq 0 \quad (7.5)$$

for sufficiently large C_0 , together with condition (4.15). Let $v_4 = C_1\varepsilon v_3$ with sufficiently large C_1 . On the bounded domain $R_1^Q = (1, Q) \times (0, M)$, we use the boundary conditions (3.46) and (4.3). By (7.1), we know that $v_4 \geq \phi_Q - \phi_\infty$ on the walls $\mathcal{B}_{0,1}$. By the definition of h_Q , we have

$$(\phi_Q - \phi_\infty)|_{y_1=Q} \leq \frac{C\varepsilon}{(1 + Q)^\beta} \leq v_4|_{y_1=Q}.$$

Also estimate (4.8) implies $(\phi_Q - \phi_\infty)|_{y_1=1} \leq C\varepsilon \leq v_4|_{y_1=1}$. By the Comparison Principle, we conclude

$$|\phi_Q(y) - \phi_\infty(y_2)| \leq \frac{C\varepsilon}{(1 + |y_1|)^\beta}. \quad (7.6)$$

Since the constant C in (7.6) is independent of Q , we let Q tend to infinity to obtain the same estimate for ϕ .

Once we have the L^∞ estimate of $|\phi_Q - \phi_\infty|$ above, we use the standard Schauder boundary estimate (up to the boundary $\mathcal{B}_{0,1}$) in the domain

$$R_{Y-2}^{Y+2} := (Y - 2, Y + 2) \times (0, M)$$

to obtain

$$\|\phi - \phi_\infty\|_{2,\alpha;R_{Y-1}^{Y+1}}^{(-1-\alpha;\mathcal{B}_{0,1})} \leq \frac{C\varepsilon}{(1+|Y|)^\beta}.$$

This immediately gives estimate (7.3). $\square$

8. SHOCK STABILITY

In this section, we discuss the stability of transonic shocks under the small perturbation of both the incoming flows and the nozzle walls. We first investigate the shock stability in Lagrangian coordinates.

Shock stability in Lagrangian coordinates. Assume that there are two nozzles whose walls are described by $\zeta_i^{(1)}$ and $\zeta_i^{(2)}$, $i = 0, 1$, and two incoming flows $U_-^{(i)}$, $i = 1, 2$, in Eulerian coordinates.

Let

$$M_i = \int_{\zeta_0^{(i)}(-1)}^{\zeta_1^{(i)}(-1)} \rho_-^{(i)} u_{1-}^{(i)}(-1, s) ds, \quad i = 1, 2. \quad (8.1)$$

The domains for the transonic flows $U_-^{(i)}$ and $U^{(i)}$ in Lagrangian coordinates are defined by

$$R^{(i)} = (-1, \infty) \times (0, M_i). \quad (8.2)$$

We use $R^{(0)}$ as our standard domain to compare the flows $U^{(1)}$ and $U^{(2)}$ later, where M_0 is defined in (3.10). The domains for the incoming flows $U_-^{(i)}$ are

$$R_1^{(i)} := (-1, 1) \times (0, M_i), \quad (8.3)$$

and the domains for the subsonic flows $U^{(i)}$ are

$$R_{f_i}^{(i)} = R^{(i)} \cap \{y_1 > f_i(y_2)\}, \quad (8.4)$$

where f_i are the corresponding shock functions.

To compare the two different flows, we need to use the standard domain $R^{(0)}$. Hence, we define the coordinate transformations $\bar{\sigma}_i : R^{(0)} \rightarrow R^{(i)}$ by

$$\mathbf{y} = \bar{\sigma}_i(\bar{\mathbf{y}}) = (\bar{y}_1 + \eta(\bar{y}_1) \bar{f}_i(\bar{y}_2), \frac{M_i}{M_0} \bar{y}_2), \quad (8.5)$$

where

$$\bar{f}_i(\bar{y}_2) = f_i\left(\frac{M_i}{M_0} \bar{y}_2\right), \quad (8.6)$$

and η is defined in (6.5). Therefore, $\bar{\sigma}_i^{-1}$, $i = 1, 2$, map the domains $R^{(i)}$ into $R^{(0)}$ and flatten the shocks f_i . Also, we define

$$\bar{U}_-^{(i)}(\bar{\mathbf{y}}) = U_-^{(i)}\left(\bar{y}_1, \frac{M_i}{M_0} \bar{y}_2\right). \quad (8.7)$$

We now state the theorem for the shock stability in Lagrangian coordinates.

Theorem 8.1. *Let two incoming flows $U_-^{(i)}$, $i = 1, 2$, in two nozzles $R^{(i)}$ satisfy*

$$\|U_-^{(i)} - U_-^0\|_{C^{2,\alpha}(R_1^{(i)})} \leq \varepsilon. \quad (8.8)$$

Let $U^{(i)}$ and f_i be the unique solution and corresponding shock for each $i = 1, 2$, determined by Theorem 3.1. Then, in the domain $R^{(0)}$, we have the following stability estimate:

$$\|\bar{f}_1 - \bar{f}_2\|_{2,\alpha;(0,M_0)}^{(-1-\alpha)} \leq C \left(\|\bar{U}_-^{(1)} - \bar{U}_-^{(2)}\|_{1,\alpha;R_1^{(0)}}^{(-\alpha)} + \sum_{i=0,1} \|\zeta_i^{(1)} - \zeta_i^{(2)}\|_{1,\alpha;(-1,\infty)} \right). \quad (8.9)$$

Proof. The proof basically follows the procedure in Section 6. The difference between the transformations $\bar{\sigma}_i$ here and σ_i in Section 6 is that $\bar{\sigma}_i$ also scale the vertical direction by the factor $M_i/M_0, i = 1, 2$. Therefore, there is an extra term M_i appearing in $\bar{N}^i$ as in (6.6).

Also notice the difference in the upper and lower boundary conditions. We obtain

$$\|\bar{f}_1 - \bar{f}_2\|_{2,\alpha;(0,M_0)}^{(-1-\alpha)} \leq C \left(\|\bar{U}_-^{(1)} - \bar{U}_-^{(2)}\|_{1,\alpha;R_1^{(0)}}^{(-\alpha)} + |M_1 - M_2| + \sum_{i=0,1} \|\zeta_i^{(1)} - \zeta_i^{(2)}\|_{1,\alpha;(-1,\infty)} \right).$$

It is easy to check

$$|M_1 - M_2| \leq C \left(\|\bar{U}_-^{(1)} - \bar{U}_-^{(2)}\|_{0,0;R_1^{(0)}} + \sum_{i=0,1} \|\zeta_i^{(1)} - \zeta_i^{(2)}\|_{0,0;(-1,\infty)} \right).$$

Thus, estimate (8.9) is obtained from the above inequalities. $\square$

Shock stability in Eulerian coordinates. The stability in Eulerian coordinates is not as nice as in Lagrangian coordinates due to the fact that the solutions and the shocks are not smooth enough at the corners. Before we describe the shock stability in Eulerian coordinates, we introduce some notations and transformations, similarly as in the Lagrangian case.

Let two nozzles $\Omega^{(1)}$ and $\Omega^{(2)}$ be defined by

$$\Omega^{(i)} = \{\mathbf{x} : -1 < x_1 < \infty, \zeta_0^{(i)}(x_1) < x_2 < \zeta_1^{(i)}(x_1)\}. \quad (8.10)$$

The domains for the incoming flows $U_-^{(i)}$ are

$$\Omega_1^{(i)} = \Omega^{(i)} \cap \{x_1 < 1\}. \quad (8.11)$$

We also define the standard flat nozzle

$$\Omega^{(0)} = (-1, \infty) \times (0, 1), \quad \Omega_1^{(0)} = (-1, 1) \times (0, 1). \quad (8.12)$$

Define $\pi_i : \Omega^{(i)} \rightarrow \Omega^{(0)}$ by

$$\bar{\mathbf{x}} = \pi_i(\mathbf{x}) = \left(x_1, \frac{x_2 - \zeta_0^{(i)}(x_1)}{\zeta_1^{(i)}(x_1) - \zeta_0^{(i)}(x_1)} \right). \quad (8.13)$$

Let $\bar{U}_-^{(i)} = U_-^{(i)} \circ \pi_i^{-1}$. Let the x_2 -coordinates of the lower and upper ends of the shock $S_i = \{x_1 = s_i(x_2)\}$ be z_i and w_i respectively. We rescale the shocks s_i to $\bar{s}_i$ onto $(0, 1)$ by

$$\bar{s}_i(\bar{x}_2) = s_i(z_i + (w_i - z_i)\bar{x}_2). \quad (8.14)$$

We have the following stability result in the C^α norm.

Theorem 8.2. *Let the two incoming flows $U_-^{(1)}$ and $U_-^{(2)}$ be defined in $\Omega_1^{(1)}$ and $\Omega_1^{(2)}$ respectively, and satisfy*

$$\|U_-^{(i)} - U_-^{(0)}\|_{C^{2,\alpha}(\Omega_1^{(i)})} \leq \varepsilon, \quad i = 1, 2. \quad (8.15)$$

Let $U_-^{(i)}$ and s_i be the unique solution and corresponding shock for each $i = 1, 2$, determined by Theorem 2.2. Then

$$\|\bar{s}_1 - \bar{s}_2\|_{0,\alpha;(0,1)} \leq C \left(\|\bar{U}_-^{(1)} - \bar{U}_-^{(2)}\|_{1,\alpha;\Omega_1^{(0)}}^{(-\alpha)} + \sum_{i=0,1} \|\zeta_i^{(1)} - \zeta_i^{(2)}\|_{1,\alpha;(-1,\infty)} \right). \quad (8.16)$$

Proof. We notice that the shock $y_1 = f_i(y_2)$ in Lagrangian coordinates gives an equation for $\bar{s}_i$ as below:

$$\bar{s}_i(\bar{x}_2) = \bar{f}_i \left(\frac{M_0}{M_i} F_i(\bar{s}_i(\bar{x}_2), z_i + (w_i - z_i)\bar{x}_2) \right), \quad (8.17)$$

where

$$F_i(\mathbf{x}) = \int_{\zeta_0^{(i)}(x_1)}^{x_2} \rho_-^{(i)} u_{1-}^{(i)}(x_1, s) ds.$$

Using (8.17), we find

$$\begin{aligned} & \|\bar{s}_1 - \bar{s}_2\|_{0,\alpha;(0,1)} \\ & \leq C\|\bar{f}_1 - \bar{f}_2\|_{0,\alpha;(0,M_0)} \\ & \quad + C\varepsilon\left(|M_1 - M_2| + |z_1 - z_2| + |w_1 - w_2| + \|\bar{s}_1 - \bar{s}_2\|_{0,\alpha;(0,1)} + \|\bar{U}_-^{(1)} - \bar{U}_-^{(2)}\|_{1,\alpha;\Omega_1^{(0)}}^{(-\alpha)}\right). \end{aligned}$$

Since $z_i = \zeta_0^{(i)}(\bar{s}_i(0))$ and $w_i = \zeta_1^{(i)}(\bar{s}_i(1))$, we conclude

$$|z_1 - z_2| + |w_1 - w_2| \leq C\left(\sum_{i=0,1} \|\zeta_i^{(1)} - \zeta_i^{(2)}\|_{0,0;(-1,\infty)} + \|\bar{s}_1 - \bar{s}_2\|_{0,0;(0,1)}\right).$$

Therefore, applying (8.9), we obtain the C^α stability (8.16) for the shocks in Eulerian coordinates. $\square$

9. SOLUTIONS IN THE SUPERSONIC REGION

In this section we give a proof of Theorem 2.1, regarding the existence and uniqueness of supersonic solutions in the upstream region Ω_1 defined in (2.3). We actually solve an initial-boundary value problem (2.12)–(2.13) and (2.14)–(2.15) for the quasilinear hyperbolic system (1.1).

Proof of Theorem 2.1. We employ the characteristic method and the contraction mapping theorem to solve the initial-boundary value problem for the hyperbolic system.

Although the proof can be done for the Euler system in the original coordinates, we prefer to use the Lagrangian coordinates, in which case the boundaries are straight and hence the proof is more straightforward. Since the coordinate transformation is $C^{3,\alpha}$, we can go back to the original coordinates with the same smoothness and $C^{2,\alpha}$ estimates.

We rewrite the Euler equations (3.2)–(3.4) in Lagrangian coordinates as the non-divergence form:

$$AV_{y_1} + BV_{y_2} = 0, \quad (9.1)$$

where $V = (\mathbf{u}, p)^\top$,

$$A = \begin{pmatrix} 1 & 0 & u \\ 0 & 1 & 0 \\ \frac{1}{\rho u_1} & 0 & \frac{1}{\rho^2 c^2} \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 0 & -\frac{u_2}{u_1} \\ 0 & 0 & 1 \\ -\frac{u_2}{u_1} & 1 & 0 \end{pmatrix}, \quad (9.2)$$

and ρ can be expressed by V through Bernoulli's law (3.21).

By solving $\det(B - \lambda A) = 0$, we find the eigenvalues of (9.1):

$$\lambda_1 = 0, \quad \lambda_{2,3} = \frac{c\rho(cu_2 \pm u_1\sqrt{u_1^2 + u_2^2 - c^2})}{u_1^2 - c^2}.$$

The corresponding left eigenvectors are

$$l_1 = (u_1, u_2, 0), \quad l_i = \left(-\frac{u_2}{u_1} - \frac{\lambda_i}{\rho u_1}, 1, \lambda_i\right), \quad i = 2, 3.$$

System (9.1) is strictly hyperbolic when $u_1 > c$. We employ the characteristic method to solve the problem. The approach is standard (cf. [19]).

We emphasize that the initial-boundary value problem for the hyperbolic system is more subtle than the Cauchy problem because the well-posedness of the initial-boundary value problem requires restrictive boundary conditions. In our case, we do have the proper boundary condition, which is the slip condition (2.13). For a given point in the domain, the characteristic starting from this point may hit the boundary when it travels backward. Since one slip condition is not enough to determine the values of V of three variables on the boundary, we need to trace the information back from the initial data by two of the characteristics: one travels along the wall and the other travels back inside the domain. The immediate

conclusion from some estimates and the contraction mapping is the local existence and uniqueness of the solution. If the initial data is a small perturbation from the constant state, the lifespan of the solution can be long enough. We refer the reader to Section 6 in [4] for more detailed discussion. This completes the proof.

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