

The Final Exam is in our usual classroom (B203 Van Vleck) at 7:25pm on Saturday May 13. It consists of approximately six proofs from the material below which I will write on the blackboard.

A copy of this document will be handed out to you at the Final.

1 Review

Theorem 1.1 *Minimal polynomials are irreducible: If α is in some extension field of F and define:*

$$I = \{f(x) \in F[x] : f(\alpha) = 0\}$$

Then:

- (a) *I is an ideal in $F[x]$*
- (b) *(assuming I is nontrivial) $I = \langle p(x) \rangle$ where $p(x)$ is any polynomial of minimal positive degree in I and*
- (c) *$p(x)$ is irreducible and so I is a maximal ideal.*

Theorem 1.2 *If $p(x)$ is an irreducible polynomial of degree n in $F[x]$ and α a root of p in some extension field, then $1, \alpha, \alpha^2, \dots, \alpha^{n-1}$ is a basis for $F(\alpha)$ as a vector space over F and hence $[F(\alpha) : F] = n$.*

Theorem 1.3 *Suppose $\text{char}(F)=0$ and $p(x) \in F[x]$ is irreducible, then p does not have any multiple roots in any extension of F .*

Theorem 1.4 *Suppose $\text{char}(F)=0$ and $[E : F] < \infty$, then there exists $\alpha \in E$ such that $E = F(\alpha)$.*

Theorem 1.5 *If $p(x) \in F[x]$ is an irreducible polynomial and α and β are two roots of p , then $F(\alpha) \simeq F(\beta)$ with an isomorphism which fixes F and takes α to β .*

Theorem 1.6 *If $\sigma : F \rightarrow F'$ is an isomorphism, $f \in F[x]$ any polynomial, $E \supseteq F$ a splitting field of f over F , and $E' \supseteq F'$ a splitting field of $\sigma(f)$ over F' , then there exists an isomorphism $\rho \supseteq \sigma$ such that $\rho : E \rightarrow E'$.*

2 Galois Theory

In this section we assume that all fields have characteristic 0.

Definition 2.1 *The field $K \supseteq F$ is a Galois extension of the field F iff K is the splitting field over F of some polynomial with coefficients in F .*

Proposition 2.2 *Suppose $F \subseteq E \subseteq K$ are fields and K is a Galois extension of F . Then K is a Galois extension of E .*

Definition 2.3 For fields $F \subseteq E$ define $\text{aut}(E|F)$ to be the set of all automorphisms σ of E which fix F , i.e., $\sigma(a) = a$ for all $a \in F$.

Proposition 2.4 $\text{aut}(E|F)$ is a group. Furthermore, if $F \subseteq E \subseteq K$ are fields, then $\text{aut}(K|E)$ is a subgroup of $\text{aut}(K|F)$.

Lemma 2.5 Suppose $\sigma, \rho \in \text{aut}(F(\alpha)|F)$. Then $\sigma = \rho$ iff $\sigma(\alpha) = \rho(\alpha)$.

Similarly, if $\sigma, \rho \in \text{aut}(F(\alpha_1, \alpha_2, \dots, \alpha_n)|F)$ then $\sigma = \rho$ iff $\sigma(\alpha_k) = \rho(\alpha_k)$ for all $k = 1, 2, \dots, n$.

Theorem 2.6 Suppose that K is the splitting field of a polynomial in $F[x]$ of degree n . Then $\text{aut}(K|F)$ is isomorphic to a subgroup of S_n .

Lemma 2.7 Suppose K is a Galois extension of F , $K \subseteq L$, and $\sigma : K \rightarrow L$ an embedding which fixes F . Then $\sigma(K) = K$.

Theorem 2.8 Suppose K is a Galois extension of F , then $|\text{aut}(K|F)| = [K : F]$

Lemma 2.9 Suppose $F \subseteq E, E' \subseteq K$, K is a Galois extension of F and $\sigma : E \rightarrow E'$ and isomorphism which fixes F . Then there exists $\rho \in \text{aut}(K|F)$ which extends σ .

Theorem 2.10 Suppose K and E are Galois extensions of F and $F \subseteq E \subseteq K$. Then $\text{aut}(K|E)$ is a normal subgroup of $\text{aut}(K|F)$ and

$$\frac{\text{aut}(K|F)}{\text{aut}(K|E)} \simeq \text{aut}(E|F)$$

3 Solvability by radicals

In this section we assume all our fields are subfields of the complex numbers \mathbb{C} .

Definition 3.1 For G a finite group define G is a solvable group by induction on $|G|$. G is solvable iff either G is abelian or there exists a normal subgroup $H \triangleleft G$ such that both H and G/H are solvable.

Definition 3.2 Given fields $F \subseteq E \subseteq \mathbb{C}$ we say that E is a radical Galois extension of F iff there exists $n \in \mathbb{N}$ and $a \in F$ such that E is the splitting field of the polynomial $x^n - a$ over F .

Theorem 3.3 Suppose that E is a radical Galois extension of F , then $\text{aut}(E|F)$ is a solvable group.

Lemma 3.4 Suppose that G is solvable group and G' is a homomorphic image of G , then G' is solvable. Hence quotient groups of solvable groups are solvable.

Theorem 3.5 *Suppose that $F_1 \subseteq F_2 \subseteq F_3 \cdots \subseteq F_m$ is a sequence of radical Galois extensions, i.e., F_{k+1} is a radical Galois extension of F_k for each $k = 1, 2, \dots, m - 1$. Suppose that K is a Galois extension of F_1 such that $K \subseteq F_m$. Then $\text{aut}(K|F_1)$ is a solvable group.*

Corollary 3.6 *Suppose $f \in \mathbb{Q}[x]$ is a polynomial which is solvable by radicals. Then if K is the splitting field of f over \mathbb{Q} , then $\text{aut}(K|\mathbb{Q})$ is a solvable group.*

Theorem 3.7 *The group A_5 is simple.*

Corollary 3.8 *The group S_5 is not solvable.*

Lemma 3.9 *Suppose G is a subgroup of S_5 which contains a transposition and a 5-cycle. Then $G = S_5$.*

Example 3.10 *There is a polynomial $f \in \mathbb{Q}[x]$ of degree 5 whose splitting field K has $\text{aut}(K|\mathbb{Q})$ isomorphic to S_5 , i.e., the Galois group of f is S_5 .*

Corollary 3.11 (Abel) *Fifth degree polynomials are not solvable by radicals.*

4 Sylow Theorems

Let p be a prime and G a finite group.

Definition 4.1 *Define group action $T : G \times X \rightarrow X$, $\text{orb}(x)$, $\text{stab}(x)$, $[G : H]$, $Z(G)$, $C(a)$, $\text{conj}(a)$, p -group, p -Sylow subgroup, $N(H)$.*

Proposition 4.2 *If G is group acting on a set X , then $\text{stab}(x)$ is a subgroup of G for any $x \in X$ and $\{\text{orb}(x) : x \in X\}$ partitions the set X .*

Theorem 4.3 (Orbit-Stabilizer) *Suppose G acts on X , then for any $x \in X$*

$$|\text{orb}(x)| = [G : \text{stab}(x)]$$

Theorem 4.4 (Class equation)

$$|G| = |Z(G)| + [G : C(a_1)] + [G : C(a_2)] + \cdots + [G : C(a_n)]$$

where $\text{conj}(a_1), \text{conj}(a_2), \dots, \text{conj}(a_n)$ are the nontrivial conjugacy classes of G .

Corollary 4.5 *Every p -group has a nontrivial center, hence is not simple unless its isomorphic to \mathbb{Z}_p .*

Corollary 4.6 *Groups of order p^2 are abelian.*

Theorem 4.7 (Sylow 1) *If G is a finite group and p^n divides $|G|$, then there exists a subgroup $H \subseteq G$ with $|H| = p^n$.*

Theorem 4.8 (Sylow 2) *If G is a finite group, H a p -subgroup of G , and P a p -Sylow subgroup of G , then there exists $a \in G$ such that $H \subseteq aPa^{-1}$.*

Corollary 4.9 *Let G be a finite group such that p divides $|G|$.*

- (a) *Any p -subgroup of G is contained in a p -Sylow subgroup of G .*
- (b) *Any two p -Sylow subgroups of G are conjugates.*
- (c) *Any two p -Sylow subgroups of G are isomorphic.*
- (d) *A p -Sylow subgroup is of G normal iff it is the only p -Sylow subgroup of G .*

Theorem 4.10 (Sylow 3) *If $|G| = p^n m$ where p does not divide m and $n(p)$ is the number of p -Sylow subgroups of G , then:*

- (a) *$n(p) = [G : N(P)]$ for any P a p -Sylow subgroup of G ,*
- (b) *$n(p)$ divides m , and*
- (c) *$n(p) \equiv 1 \pmod{p}$*

5 Linear Transformations

In this section we consider only finite dimensional vector spaces V or W over an arbitrary field \mathbb{F} .

Theorem 5.1 *Every linear transformation $L : \mathbb{F}^n \rightarrow \mathbb{F}^m$ is determined by an $m \times n$ matrix A :*

$$L(X) = AX$$

for every $X \in \mathbb{F}^n$

Theorem 5.2 *Suppose V and W are vector space over a field \mathbb{F} . If $\dim(V) = \dim(W)$, then V is isomorphic to W .*

Definition 5.3 *For $L : V \rightarrow W$ a linear transformation, define the null space (or kernel) of L , $\text{null}(L)$, and the range space of L , $\text{range}(L)$ as follows:*

- (a) $\text{null}(L) = \{v \in V : L(v) = z\}$
- (b) $\text{range}(L) = \{w \in W : \text{there exists } v \in V \text{ such that } L(v) = w\}$

Proposition 5.4 *$\text{null}(L)$ and $\text{range}(L)$ are subspaces of V and W , respectively.*

Theorem 5.5 *Suppose $L : V \rightarrow W$ is a linear transformation. Then*

$$\dim(V) = \dim(\text{null}(L)) + \dim(\text{range}(L)).$$

Theorem 5.6 *Suppose $A, B \in \mathbb{F}^{n \times n}$, then A is similar to B iff there exists a basis v_1, v_2, \dots, v_n for $\mathbb{F}^{n \times 1}$ such that for every j*

$$\mathbf{A}(v_j) = \sum_{i=1}^n \text{entry}_{ij}(B)v_i.$$

Furthermore, given such a basis if P is the invertible matrix where $\text{col}_j(P) = v_j$ for each j , then P witnesses their similarity, i.e., $A = PBP^{-1}$.

6 Triangulizability

In this section we consider only square matrices over the field of complex numbers, \mathbb{C} . All vector spaces V , W , etc are assumed to be finite dimensional vector spaces over the complex numbers.

Theorem 6.1 *Suppose for every linear transformation $L : V \rightarrow V$ that V has a basis v_1, v_2, \dots, v_n such that*

$$L(v_k) \in \text{span}(\{v_1, \dots, v_k\})$$

for every k with $1 < k \leq n$. Then every $n \times n$ matrix is similar to an upper triangular matrix.

Theorem 6.2 *Suppose V is a finite dimensional vector space over \mathbb{C} and $L : V \rightarrow V$ is a linear transformation. Then there exists a nontrivial $v \in V$ and $\lambda \in \mathbb{C}$ such that $L(v) = \lambda v$.*

Definition 6.3 *If W_1 and W_2 are subspaces of a vector space V such that $W_1 \cap W_2 = \{0\}$, then define*

$$W_1 \oplus W_2 = \{w_1 + w_2 : w_1 \in W_1, w_2 \in W_2\}.$$

Whenever we write $W_1 \oplus W_2$ we will be assuming that $W_1 \cap W_2 = \{0\}$.

Lemma 6.4 *For V a vector space and W_i 's subspaces:*

- (a) $W_1 \oplus W_2$ is a subspace of V
- (b) For any $u \in W_1 \oplus W_2$, $w_1, w'_1 \in W_1$, and $w_2, w'_2 \in W_2$, if $u = w_1 + w_2$ and $u = w'_1 + w'_2$ then $w_1 = w'_1$ and $w_2 = w'_2$.
- (c) If B_1 is a basis for W_1 and B_2 is a basis for W_2 , then $B_1 \cup B_2$ is a basis for $W_1 \oplus W_2$.
- (d) Given $W_1 \oplus W_2$ define $P : W_1 \oplus W_2 \rightarrow W_2$ by $P(w_1 + w_2) = w_2$ where $w_2 \in W_2$, and $w_1 \in W_1$, then P is a linear transformation such that $\text{kernel}(P) = W_1$ and $P(v) = v$ for all $v \in W_2$. (P is called a projection.)
- (e) For any W_1 a subspace of a finite dimensional V there exists W_2 a subspace of V such $V = W_1 \oplus W_2$.

Lemma 6.5 *Suppose $L : V \rightarrow V$ is a linear transformation and $W \neq V$ a proper subspace of V . Then there exists $v \in V$ such that $v \notin W$ and $\lambda \in \mathbb{C}$ such that $L(v) - \lambda v \in W$.*

Theorem 6.6 *Suppose $L : V \rightarrow V$ is a linear transformation. Then V has a basis v_1, v_2, \dots, v_n such that for each $k = 1, \dots, n$ $L(v_k) \in \text{span}(\{v_1, v_2, \dots, v_k\})$.*

Corollary 6.7 *Every matrix $A \in \mathbb{C}^{n \times n}$ is similar to an upper triangular matrix.*

Definition 6.8 A sequence u_1, u_2, \dots, u_n in an inner product space is orthonormal iff for all i, j

$$\langle u_i, u_j \rangle = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

Proposition 6.9 Orthonormal sequences are linearly independent.

Theorem 6.10 (Gram-Schmidt Orthogonalization Process). If v_1, v_2, \dots, v_n and linear independent, then there exists u_1, \dots, u_n an orthonormal sequence such that for every $k = 1, \dots, n$

$$\text{span}(\{v_1, \dots, v_k\}) = \text{span}(\{u_1, \dots, u_k\}).$$

Theorem 6.11 Suppose V is a finite dimensional inner product space and $L : V \rightarrow V$ is a linear transformation, then V has an orthonormal basis u_1, u_2, \dots, u_n such that for each $k = 1, \dots, n$

$$L(u_k) \in \text{span}(\{u_1, u_2, \dots, u_k\}).$$

Corollary 6.12 (Schur) For every matrix $A \in \mathbb{C}^{n \times n}$ there exists a unitary matrix P (ie $P^{-1} = P^*$ the conjugate transpose) such that $P^{-1}AP$ is an upper triangular matrix.

Corollary 6.13 If $A = A^*$ then A is (unitarily) similar to a diagonal matrix all of whose entries are real. Hence all the eigenvalues of A are real.

7 Jordan Normal Form

In this section all vector spaces V, W , etc., are assumed to be finite dimensional vector spaces over an algebraically closed field \mathbb{F} , e.g., the complex numbers.

Definition 7.1 $\langle v_1, v_2, \dots, v_n \rangle$ is an L -shifting sequence iff $v_1 \neq \mathbf{0}, L(v_1) = \mathbf{0}$ and $L(v_{k+1}) = v_k$ for each $k = 1, 2, \dots, n - 1$.

Definition 7.2 For $W \subseteq V$ $L(W) = \{L(v) : v \in W\}$. It is the same as the range of L when $W = V$.

Theorem 7.3 An L -shifting sequence $\langle v_1, v_2, \dots, v_n \rangle$, is linearly independent. Also if $W = \text{span}(\{v_1, v_2, \dots, v_n\})$, then $L(W) \subseteq W$.

Theorem 7.4 Suppose $L : V \rightarrow V$ is a linear transformation and let $W_1 = \{v \in V : \exists n L^n(v) = \mathbf{0}\}$. Then $L(W_1) \subseteq W_1$ and there exists W_2 with $L(W_2) \subseteq W_2$ such that $V = W_1 \oplus W_2$.

Definition 7.5 Define a linear transformation $L : V \rightarrow V$ to be nilpotent iff for every $v \in V$ there exists n such that $L^n(v) = \mathbf{0}$.

Theorem 7.6 Suppose $L : V \rightarrow V$ is a nilpotent linear transformation. Then there exists W_1, W_2 such that $L(W_1) \subseteq W_1$, $L(W_2) \subseteq W_2$, $V = W_1 \oplus W_2$ and W_1 has an L -shifting sequence for a basis.

Definition 7.7 The shift matrix S is the square matrix such that entry $s_{i,i+1} = 1$ for each i and all other entries of S are 0.

Definition 7.8 Matrices of the form $J = \lambda I + S$ are called Jordan block matrices.

Theorem 7.9 (Jordan normal form) Every square matrix A is similar to a matrix in the block diagonal form:

$$\begin{bmatrix} J_1 & 0 & \dots & 0 \\ 0 & J_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & J_n \end{bmatrix}$$

where each J_i is a Jordan block matrix.