

# Crash course in Riemannian geometry

1. Metrics
2. Tensors
3. Covariant derivs
4. Riemann curvature tensor.

1.  $M$  = smooth mfd.

A Riemannian metric,  $g$ , is a smoothly varying inner product on the tangent spaces of  $M$ .

$$v, w \in T_x M \mapsto g_x(v, w) \in \mathbb{R}$$

$\begin{matrix} \xrightarrow{+} & \xrightarrow{-} & \xrightarrow{+} \\ \xrightarrow{+} & \xrightarrow{-} & \xrightarrow{+} \end{matrix}$

↳ pos. def. symmetric bilinear.

$$X, Y \in \mathcal{X}(M) \rightsquigarrow g(X, Y) \in C^\infty(M).$$

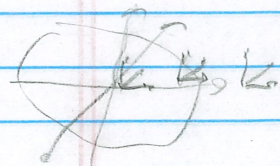
$$f, h \in C^\infty(M)$$

$$g(fX + hY, Z) = fg(X, Z) + hg(Y, Z).$$

Local notation: fix coords  $x^i$   $i=1, \dots, n$  on  $U \subset M$

$$\left\{ \partial_i = \frac{\partial}{\partial x^i} \right\}_{i=1}^n \quad \text{local frame}$$

for  $TM|_U$ .



$$\text{Let } g_{ij} = g(\partial_i, \partial_j).$$

= local components:  $(g_{ij}(x)) =$  metric-valued function.

Arbitrary summation convention

$$X = X^i \partial_i, \quad Y = Y^j \partial_j \in \mathcal{X}(M)$$

$$\begin{aligned} g(X, Y) &= g(X^i \partial_i, Y^j \partial_j) \\ &= X^i Y^j g(\partial_i, \partial_j) \\ &= X^i Y^j g_{ij} \end{aligned}$$

From Riem. metric get. length, distance & volume

$$l(\gamma) = \int_a^b \sqrt{g(\gamma'(t), \gamma'(t))} dt$$

$$d_g(p, q) = \text{Inf} \{ l(\gamma) \mid \gamma \text{ connects } p \text{ and } q \}$$

Metric on  $M$  in usual sense!

$$dV_g = \sqrt{|\det(g_{ij})|} dx^1 \wedge \dots \wedge dx^n$$

oriented basis.

Riemannian volume form.



(also on  $k$ -dim submanifolds.)

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2. A covariant  $q$ -tensor  $T \in T^{(0,q)}$  is a smoothly varying multilinear function on  $T_x M \times \dots \times T_x M$ .

Given  $X_1, \dots, X_q \in \mathcal{X}(M)$ ,

$$T(X_1, \dots, X_q) \in C^\infty(M)$$

Defines  $C^\infty$ -linear function

$$T: \mathcal{X}(M) \times \dots \times \mathcal{X}(M) \rightarrow C^\infty(M)$$

$$T(fX + gY, X_2, \dots, X_q) = fT(X, X_2, \dots, X_q) + gT(Y, X_2, \dots, X_q)$$

Tensor product:

$$T \otimes T^{(0,q)}, S \in T^{(0,r)} \mapsto S \otimes T \in T^{(0,r+q)}$$

Locally:  $x^i \mapsto \frac{\partial}{\partial x^i}$

$$T_{i_1, \dots, i_q} = T\left(\frac{\partial}{\partial x^{i_1}}, \dots, \frac{\partial}{\partial x^{i_q}}\right), \quad i_1, \dots, i_q \in \{1, \dots, n\}$$

"  $n^q$  functions!

Local components. Determine  $T$  uniquely by:

$$X_i = X^i \frac{\partial}{\partial x^i} \text{ etc.}$$

$$T(X_1, \dots, X_q) = X_1^{i_1} \dots X_q^{i_q} T_{i_1, \dots, i_q}$$

Different coords?  $\sum_{i_1, \dots, i_q} \frac{\partial x^{i_1}}{\partial x'^{j_1}} \dots \frac{\partial x^{i_q}}{\partial x'^{j_q}} T_{i_1, \dots, i_q} = T'_{j_1, \dots, j_q}$

$$\tilde{T}_{j_1 \dots j_q} = T \left( \frac{\partial}{\partial \tilde{x}^{j_1}}, \dots, \frac{\partial}{\partial \tilde{x}^{j_q}} \right)$$

$$= T \left( \frac{\partial x^{i_1}}{\partial \tilde{x}^{j_1}} \frac{\partial}{\partial x^{i_1}}, \dots, \frac{\partial x^{i_q}}{\partial \tilde{x}^{j_q}} \frac{\partial}{\partial x^{i_q}} \right)$$

$$= \frac{\partial x^{i_1}}{\partial \tilde{x}^{j_1}} \dots \frac{\partial x^{i_q}}{\partial \tilde{x}^{j_q}} T_{i_1 \dots i_q}$$

Transf. law for a covariant tensor components.

Anything that transforms as a tensor gives a well-def'd fld on  $\mathbb{R}^n(x) \rightarrow \mathbb{R}^n(x)$ .

$T^{(0,q)}$  = sections of  $T^*M \otimes \dots \otimes T^*M$   
 $q$  times.

Ex:  $g \in T^{(0,2)}$ , Riem. metric

$\mathcal{R}^q(M) \subset T^{(0,q)}$ , alternating tensors  
 = differential  $q$ -forms!

Mixed tensors:  $T^{(p,q)}$  = smoothly varying multilinear forms on  $\mathbb{R}^n(x) \times \dots \times \mathbb{R}^n(x) \times \mathcal{R}^1(M) \times \dots \times \mathcal{R}^1(M)$   
 $p$  forms  $q$  forms.

Ex:  $\mathcal{X}(M) = T^{(0,0)}M$ .

$X \rightsquigarrow$  form on diff'd form:

loc  $\alpha \mapsto \alpha(X) \in C^\infty(M)$   
 "  $\alpha_j dx^j$  "  $\parallel$

$$\alpha_j dx^j (X^i \partial_i)$$

$$= \alpha_j X^i dx^j(\partial_i)$$

$$= \alpha_j X^i \delta^j_i$$

Reason for

ambiguity conversion!

$$\alpha(X) = \alpha_i X^i \quad \tilde{\alpha}_k = \alpha_i \frac{\partial x^i}{\partial \tilde{x}^k}$$

Check in local coord:  $X = X^i \frac{\partial}{\partial x^i} = X^i \frac{\partial \tilde{x}^j}{\partial x^i} \frac{\partial}{\partial \tilde{x}^j} \Rightarrow \tilde{X}^j = X^i \frac{\partial \tilde{x}^j}{\partial x^i}$

Can use this duality to contract indices:

$$T_{m,n} : T^{(p,q)} \rightarrow T^{(p-1,q-1)}$$

$$T^{i_1 \dots i_p}_{j_1 \dots j_q} \mapsto T^{i_1 \dots i_{p-1}}_{j_1 \dots j_{q-1}}$$

Can also use <sup>a</sup> metric  $g$  to raise & lower

indices:  $(\cdot)^b : \mathcal{X}(M) \rightarrow \mathcal{X}'(M)$

$$X^b = g(X, -)$$

$$(X^i) \mapsto g_{ij} X^j$$

isomorphism. Let  $(\ )^\# : \mathcal{X}(M) \rightarrow \mathcal{X}(M)$   
 be the inverse.  $\alpha \mapsto \alpha^\#$

Local f'ld: let  $(g^{ij}) = \text{inverse matrix of } (g_{ij})$

$$(\alpha^\#)^i = g^{ij} \alpha_j$$

Can do on any tensor:

$$(\ )^\# : T^{(p,q)} \rightarrow T^{(p-1,q-1)}$$

$$T^{i_1 \dots i_p}_{j_1 \dots j_q} \mapsto g^{i_{p+1}} T^{i_1 \dots i_p}_{j_1 \dots j_q} =: (T^\#)^{i_1 \dots i_p}_{j_1 \dots j_q}$$

3. How to take the derivative of a tensor?

Special cases:  $C^\infty(M)$

• 0-tensor =  $C^\infty$  fun.

$$X \quad f \rightsquigarrow X(f) \in C^\infty(M)$$

$$f \rightsquigarrow \mathcal{D}f \in T^{(0,1)}$$

$$X \mapsto X(f) !$$

tensorial b/c  $(gX + hY)(f) = gX(f) + hY(f)$  ✓

$d$  extends to alternating covariant tensors

$$d: \underbrace{\mathcal{L}^k(\mathcal{M})}_{\hat{\Gamma}(0, k)} \rightarrow \underbrace{\mathcal{L}^{k+1}(\mathcal{M})}_{\hat{\Gamma}(0, k+1)}$$

$$\begin{aligned} d\omega(X_0, X_1, \dots, X_k) &= \sum (-1)^i X_i(\omega(X_0, \dots, \hat{X}_i, \dots, X_k)) \\ &\quad + \sum_{i < j} (-1)^{i+j} \omega([X_i, X_j], X_0, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_k) \end{aligned}$$

Lie bracket of v.-fields:

$$X, Y \in \mathcal{X}(\mathcal{M}) \quad X \circ Y = f \mapsto X(f)(Y) \text{ not deriv.}$$

but  $[X, Y]$  is.

$$\begin{aligned} & \text{''} \\ & L_X Y \end{aligned}$$

Extend:

$$L_X(T \otimes S) = L_X T \otimes S + T \otimes L_X S$$

$$(L_X T)_{j_1 \dots j_r}^{i_1 \dots i_r} = X^k \partial_k T_{j_1 \dots j_r}^{i_1 \dots i_r}$$

$$- (\partial_k X^l) T_{j_1 \dots j_r}^{i_1 \dots i_r} + \dots - \partial_k X^l T_{j_1 \dots j_r}^{i_1 \dots i_r}$$

$$+ (\partial_{j_1} X^k) T_{j_2 \dots j_r}^{i_1 \dots i_r} + \dots + \partial_{j_r} X^k T_{j_1 \dots j_{r-1}}^{i_1 \dots i_r}$$

$L_X T \neq \{L_X T\} \Rightarrow$  not determined at  $p$  by  $X(p)$ .

Can fix this but not (yet) in a unique way.

Def. a covariant derivative is a map

$$\nabla : \mathcal{X}(M) \times \mathcal{X}(M) \longrightarrow \mathcal{X}(M)$$

$$X, Y \mapsto \nabla_X Y \quad \text{satisfying:}$$

(1) For constants  $c_1, c_2 \in \mathbb{R}$ ,

$$\nabla_X (c_1 Y_1 + c_2 Y_2) = c_1 \nabla_X Y_1 + c_2 \nabla_X Y_2$$

(2) For  $f_1, f_2 \in C^\infty(M)$ , have

$$\nabla_{(f_1 X_1 + f_2 X_2)} Y = f_1 \nabla_{X_1} Y + f_2 \nabla_{X_2} Y$$

(3) For  $g \in C^\infty(M)$ , have:

$$\nabla_X (gY) = X(g)Y + g \nabla_X Y. \quad (\text{Leibniz})$$

Example: directional deriv. on  $\mathbb{R}^n$ :  $\nabla_X Y = (X^i \partial_i Y^j) \partial_j$ . directed coord. on  $\mathbb{R}^n$ :  $\partial_i = \frac{\partial}{\partial x^i}$

Locally: let  $A_{ij}^k \in C^\infty(U)$  be determined by

$$\partial_i \partial_j = \frac{\partial}{\partial x^i} \partial_j = A_{ij}^k \partial_k$$

Then for  $X = X^i \partial_i$ ,  $Y = Y^j \partial_j$ , have:

$$\begin{aligned} \nabla_X Y &= \nabla_{X^i \partial_i} (Y^j \partial_j) \\ &\stackrel{(2)}{=} X^i \nabla_{\partial_i} (Y^j \partial_j) \\ &= X^i \partial_i Y^j \partial_j + X^i Y^j \nabla_{\partial_i} \partial_j \\ &= X^i \partial_i Y^j \partial_j + X^i Y^j A_{ik}^l \partial_l \end{aligned}$$



$$= X^i \partial_j Y^j + X^i \partial_j (A_{ij}^k) Y^k$$

$$= X^i (\partial_j Y^j + A_{ik}^j Y^k) \partial_k$$

Local coeffs determine  $\nabla$  by  
this rule.

conversely, any  $A_{ij}^k$  (a matrix-val'd  
funs  $A_i$ )

determine a connection,

locally.

⚠  $A_{ij}^k$  is not a tensor in  $j$  and  $k$ !

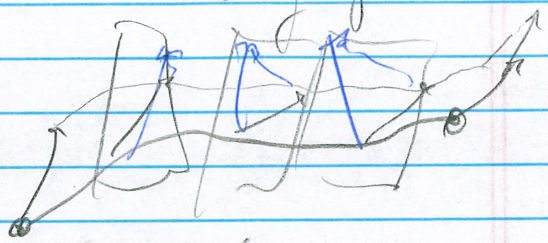
(not  $C^\infty$ -linear on  $Y$ , by (3).)

Difference of two conn's <sup>(1.2)</sup> is a tensor:

$$\begin{aligned} (\nabla_x - \nabla'_x)(g^Y) &= X(g^Y) + g^Y \partial_x - X(g^Y) - g^Y \partial'_x \\ &= g^Y (\nabla_x - \nabla'_x) \quad \checkmark \end{aligned}$$

Convenient for anal. eqns. (next time).

connection  $\rightarrow$  parallel transport rule 10  
 along paths.



$X$  parallel along  $\gamma \Leftrightarrow \nabla_{\dot{\gamma}(t)}(X) \equiv 0$ .

Induced connection on  $\mathbb{R}^n(M)$ :

want  $X(\alpha(Y)) = \nabla_X \alpha(Y) + \alpha(\nabla_X Y)$ .

$$\partial_i \partial_j Y^i = (\nabla_{\partial_i} \partial_j) Y^i + \partial_j (\partial_i Y^i + A_{ik}^i Y^k)$$

$$(\partial_i \partial_j Y^i + \partial_j \partial_i Y^i)$$

$$(\partial_i \partial_j Y^i - \partial_j \partial_i Y^i) = \nabla_{\partial_i} \partial_j Y^i$$

$$\boxed{\nabla_{\partial_i} \partial_j = \partial_i \partial_j - A_{ijk}^k}$$

Symbolically: for  $T \in T^{(p,q)}$ ,

$$(\nabla_{\partial_i} T)^{j_1 \dots j_q} = \partial_i T^{j_1 \dots j_q} + A_{ik}^i T^{k j_1 \dots j_q} + \dots$$

$$\boxed{\text{DEFINES } \nabla: T^{(p,q)} \rightarrow T^{(p,q+1)} \quad \nabla T(x_0, x_1, \dots, x_p) = \nabla_x T}$$

Now bring back the Riem. metric  $g$ .

Want to attach a canonical connection

$$\nabla = \nabla^g \text{ to } g.$$

Add two requirements:

Metric-compatibility:

$$\cdot Xg(Y, Z) = g(\nabla_X Y, Z) + g(Y, \nabla_X Z).$$

Torsion-freeness:

$$\nabla_{\partial_i} \partial_j = \nabla_{\partial_j} \partial_i \quad (\text{compatibility with } d.)$$

First fund'l Lemma of Riem-geom.

Given  $g$ ,  $\exists!$  tors-free compatible conn.

$\nabla = \nabla^g$ , called the Levi-Civita connection,  
with the local fla:

$$A_{ij}^k = \Gamma_{ij}^k = \frac{1}{2} g^{kl} (2g_{jl,i} + g_{ik,j} - g_{ij,k}).$$

"Christoffel symbols".

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Pf:  $\partial_j g_{jk} = g(\partial_j \partial_i, \partial_k) + g(\partial_j, \partial_i \partial_k)$

$$= \Gamma_{ij}^l g_{lk} + \Gamma_{ik}^l g_{jl}$$

$$= \Gamma_{ij}^l g_{lk} + \cancel{\Gamma_{ik}^l g_{jl}}$$

Cyclic:  $\partial_j g_{ki} = \cancel{\Gamma_{jk}^l g_{li}} + \Gamma_{ij}^l g_{kl}$

$$\partial_k g_{ij} = \cancel{\Gamma_{ki}^l g_{jl}} + \cancel{\Gamma_{jk}^l g_{li}}$$

$$\partial_j g_{ki} + \partial_j g_{ki} - \partial_k g_{ij} = 2 \Gamma_{ij}^l g_{kl}$$

(detail compatible)

Unique locally  $\Rightarrow$  well-defined globally.  $\square$

Examples: Directional deriv., inclined coord.

4. Geometric properties of a connection?

Example:



Curvature!

Defn.  $X, Y, Z \in \mathcal{X}(M)$

$$R(X, Y)Z := \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z$$

↳ Riemann curvature operator

$$R(X, Y): \mathcal{X}(M) \rightarrow \mathcal{X}(M)$$

Second fund'l lemma of Riem. geom.:

$R(X, Y)Z$  is tensorial in  $X, Y$ , and  $Z$ !

$$\text{Pf: } \nabla_X \nabla_Y (f \cdot Z) - \nabla_Y \nabla_X (f \cdot Z) - \nabla_{[X, Y]} (f \cdot Z)$$

$$= \nabla_X (Y(f)Z + f \nabla_Y Z) - \nabla_Y (X(f)Z + f \nabla_X Z)$$

$$- [X, Y](f)Z + f \nabla_{[X, Y]} Z$$

$$= f R(X, Y)Z \quad \checkmark \quad \text{Can also check}$$

$$X \neq Y.$$

$\Rightarrow R(\cdot, \cdot, \cdot)$  is a  $(3, 1)$ -tensor.

Defn. The Riemann curvature tensor is the

$(0, 4)$ -tensor defined by:

$$R(X, Y, Z, W) = g(\underbrace{R(X, Y)Z}_\triangleleft, W)$$

