Here are some solutions to the final exam from two years ago: http://www.math.wisc.edu/~angenent/234.2015f/final/exam2013-with-some-solutions.pdf

(1) (a)

$$f_x(x,y) = e^{x-2y} + xe^{x-2y} f_y(x,y) = -2xe^{x-2y}$$

So, we have at the point x = 2, y = 1

$$f(2,1) = 2$$

 $f_x(2,1) = 3$
 $f_y(2,1) = -4$

Thus the linear approximation of f(x, y) near x = 2, y = 1 is

(b)
$$f(x,y) \approx 2 + 3(x-2) - 4(y-1).$$

(3) (a)

$$f_x(x,y) = 2x$$

$$f_y(x,y) = -6y + 3y^2$$

So there are two critical points: (0,0) and (0,2). (b)

$$\begin{aligned}
 f_{xx}(x,y) &= 2 \\
 f_{xy}(x,y) &= 0 \\
 f_{yy}(x,y) &= -6 + 6y
 \end{aligned}$$

At the critical point (0,0), the quadratic part in Taylor's expansion is

$$Q(\Delta x, \Delta y) = \frac{1}{2}(2\Delta x^2 - 6\Delta y^2)$$

= $\Delta x^2 - 3\Delta y^2$
= $(\Delta x - \sqrt{3}\Delta y)(\Delta x + \sqrt{3}\Delta y)$

So (0,0) is a saddle point. Since, $\Delta x = x - 0$ and $\Delta y = y - 0$, the equations of the tangent lines to the level set are

$$\begin{array}{rcl} x - \sqrt{3}y &=& 0\\ x + \sqrt{3}y &=& 0 \end{array}$$

At the critical point (0, 2),

$$Q(\Delta x, \Delta y) = \frac{1}{2}(2\Delta x^2 + 6\Delta y^2)$$
$$= \Delta x^2 + 3\Delta y^2$$

So (0, 2) is a local minimum.

(4) $f(x,y) = xy^2$, $g(x,y) = x^2 + y^2 = 3$. At the points satisfying $\overrightarrow{\nabla}g = \overrightarrow{0}$, we cannot use Lagrange multiplier. $g_x = 2x$ and $g_y = 2y$, so (0,0) is the only point making $\overrightarrow{\nabla}g$ zero. But this point (0,0) does not satisfy g(x,y) = 3, which means it's not on the constraint set we are considering.

Now for all points on the constraint set, we could apply Lagrange multiplier,

$$\begin{cases} y^2 = \lambda 2x \\ 2xy = \lambda 2y \\ x^2 + y^2 = 3 \end{cases}$$

There are six solutions $(x, y, \lambda) = (\sqrt{3}, 0, 0), (-\sqrt{3}, 0, 0), (1, \sqrt{2}, 1), (1, -\sqrt{2}, 1), (-1, \sqrt{2}, -1)$ and $(-1, -\sqrt{2}, -1)$. So the maxima are at points $(1, \sqrt{2}), (1, -\sqrt{2}), (-1, \sqrt{2}), (-1, -\sqrt{2})$.

(7) (a) the region \mathcal{R} in cylindrical coordinates is presented by

$$\begin{array}{rrrr} 0 \leq & r & \leq 2 \\ \frac{\pi}{4} \leq & \theta & \leq \frac{\pi}{2} \\ 0 \leq & z & \leq r^2 \end{array}$$

(b)

$$\iiint_{\mathcal{R}} 1 \ dV = \int_{0}^{2} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_{0}^{r^{2}} r \ dz \ d\theta \ dr$$
$$= \pi$$
$$\iiint_{\mathcal{R}} z \ dV = \int_{0}^{2} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_{0}^{r^{2}} zr \ dz \ d\theta \ dr$$
$$= \frac{4}{3}\pi$$

So the average of z in \mathcal{R} is

$$\frac{\iiint_{\mathcal{R}} z \ dV}{\iiint_{\mathcal{R}} 1 \ dV} = \frac{4}{3}.$$

(8)

$$\int_{0}^{3} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_{0}^{\frac{\pi}{2}} \rho^{3} \sin^{2} \phi \cos \theta \, d\phi \, d\theta \, d\rho.$$

(9) See problem 1 on Dec 10's handout.

Here are solutions to 8,9,10 on http://www.math.wisc.edu/~angenent/234. 2015f/final/lineintegralproblems.html

(8) $\vec{T} ds = d\vec{x} = \begin{pmatrix} dx \\ dy \end{pmatrix}$, and because \vec{N} is the unit normal obtained by rotating \vec{T} clockwise by

$$\vec{N} ds = \begin{pmatrix} dy \\ -dx \end{pmatrix}$$

Thus, we could see that

$$\vec{F} = \vec{H} = \begin{pmatrix} \sin(x) \\ e^{xy} \end{pmatrix}$$
, and $\vec{G} = \begin{pmatrix} e^{xy} \\ -\sin(x) \end{pmatrix}$.

(9) Apply Green Theorem.

$$I = \int_{\mathcal{C}} \vec{F} \cdot \vec{T} \, ds$$
$$= -\iint_{R} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) \, dA$$
$$= -\iint_{R} 0 \, dA = 0$$

We have a negative sign above is because the curve C is in the clockwise orientation. And for J, since \vec{N} is the outward unit normal,

$$J = \int_{\mathcal{C}} \vec{F} \cdot \vec{N} \, ds$$

= $\iint_{R} \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} \right) \, dA$
= $\iint_{R} (x^{2} + y^{2}) \, dA$
> 0

The last step is because the integrand $x^2 + y^2 \ge 0$.

(10) Because $\vec{T} \cdot \vec{T} = \|\vec{T}\|^2 = 1$, $\vec{N} \cdot \vec{N} = \|\vec{N}\|^2 = 1$ and $\vec{T} \cdot \vec{N} = 0$, we have $I_1 = I_2 = \int_{\mathcal{C}} 1 \, ds$ represent the length of \mathcal{C} and $I_3 = 0$